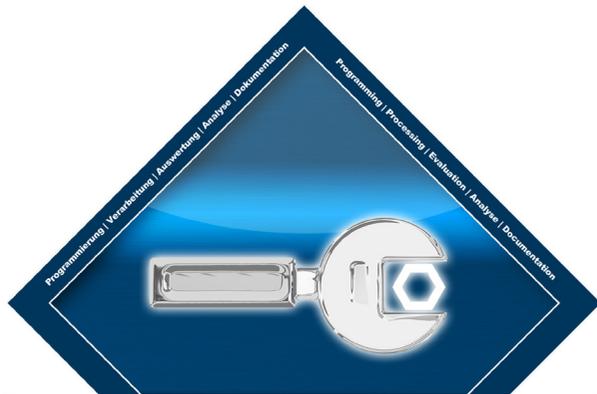


OPERATING INSTRUCTIONS



HST-Tool-Manager

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HELP AND SUPPORT



Support for the HST-Tool-Manager can be reached here:
service@hs-technik.com | Telephone: +49 7628 9111-57

Please note that our support service may only clarify questions about understanding the programming and settings, but may not define any programs of the client.



NOTE

This symbol indicates additional information which will make working with the tool easier.



WARNING

General warning in order to avoid malfunctions and breakdowns.



DANGER

This indicates direct danger for the worker or the tool. This warning symbol is particularly important and must be followed.



OPEN FLAT GEAR

This symbol indicates functions which are used particularly for open flat drives.

1 INSTALLATION OF THE DRIVER



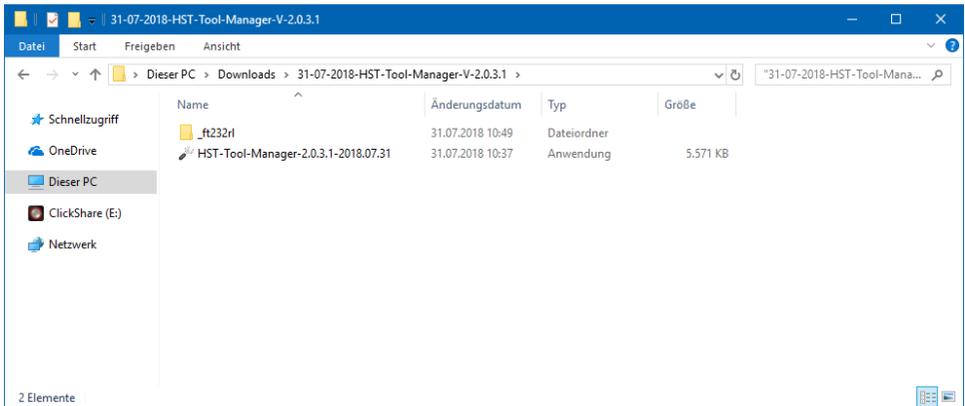
Open the data carrier.



NOTE

The current software as well as the driver are available as a download on our webpage in the software area.

Then the folder will open automatically. If it does not open, go to “Start” - “This PC” and open it manually.



1 Installation

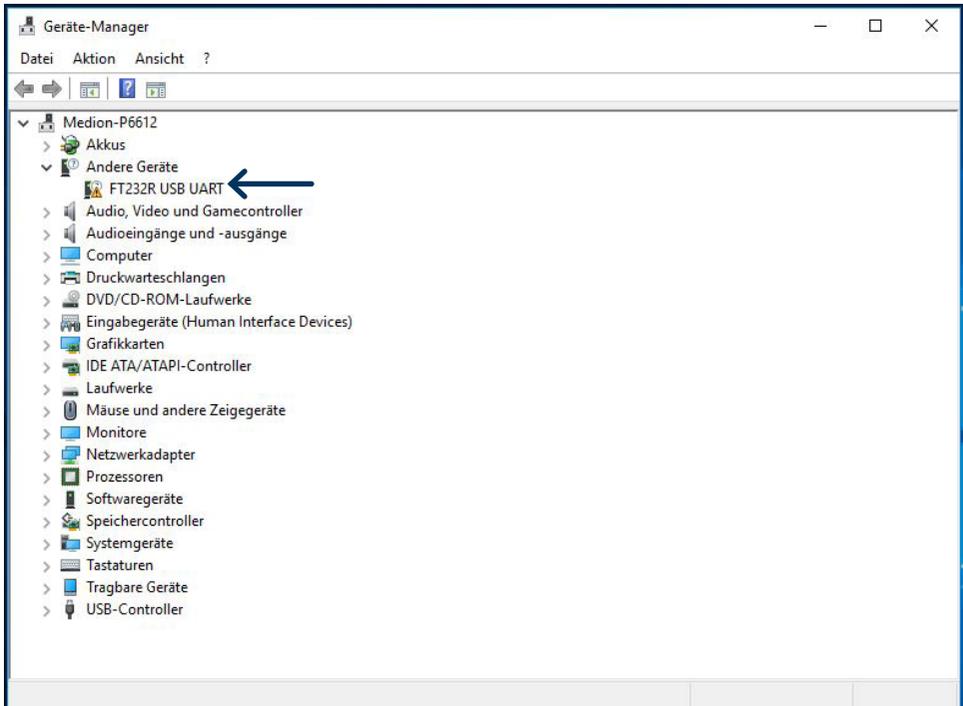
Save the files in a folder on the desktop or in another folder on your computer. Name the folder, for example **Date-HST-Tool-Manager-Version**. If you save it in another folder we advise that you create a shortcut on the desktop. Then you can start HST-Tool-Manager.exe.



NOTE

The installation of drivers on a computer requires administrative rights. If you do not have these contact your IT department.

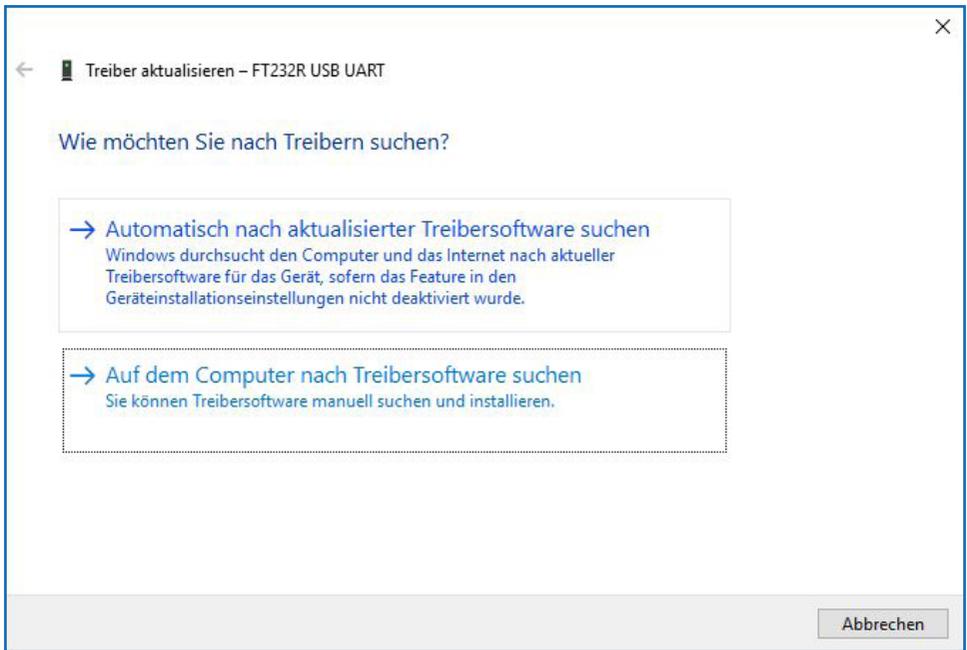
If the software does not open or the software does not recognise the tool check whether you have already installed the USB driver (ft232rl). To do this connect the tool to the computer via USB and open the device manager.



2 Adapter not recognised

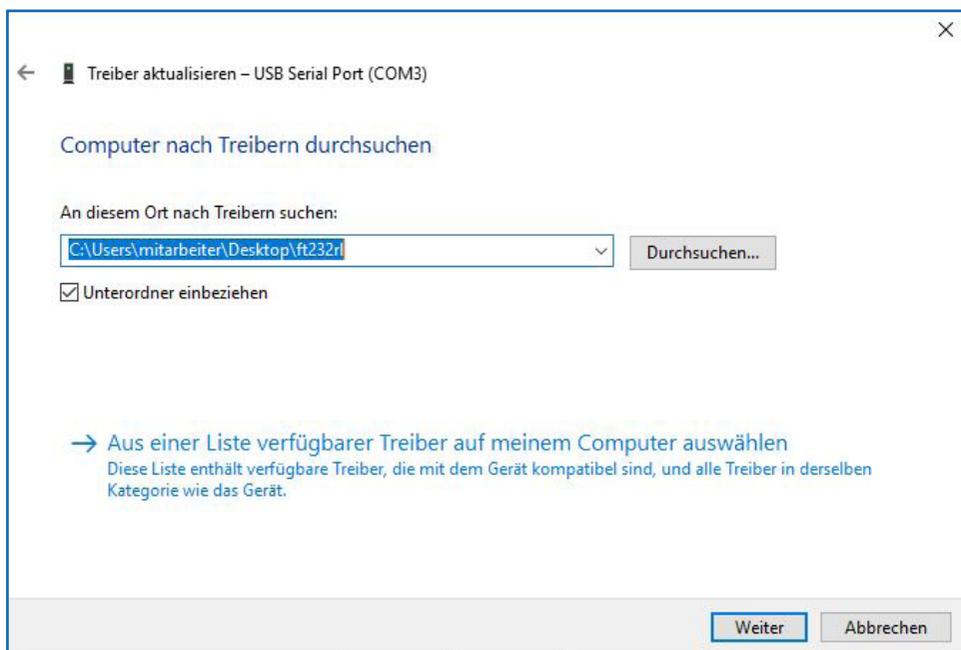
The ft232rl driver is not yet installed and does not correctly recognise the COM-Port.

After connecting the tool to the computer using the USB go to “New hardware detected” on the bottom right of your computer. The window for updating the driver software will open.



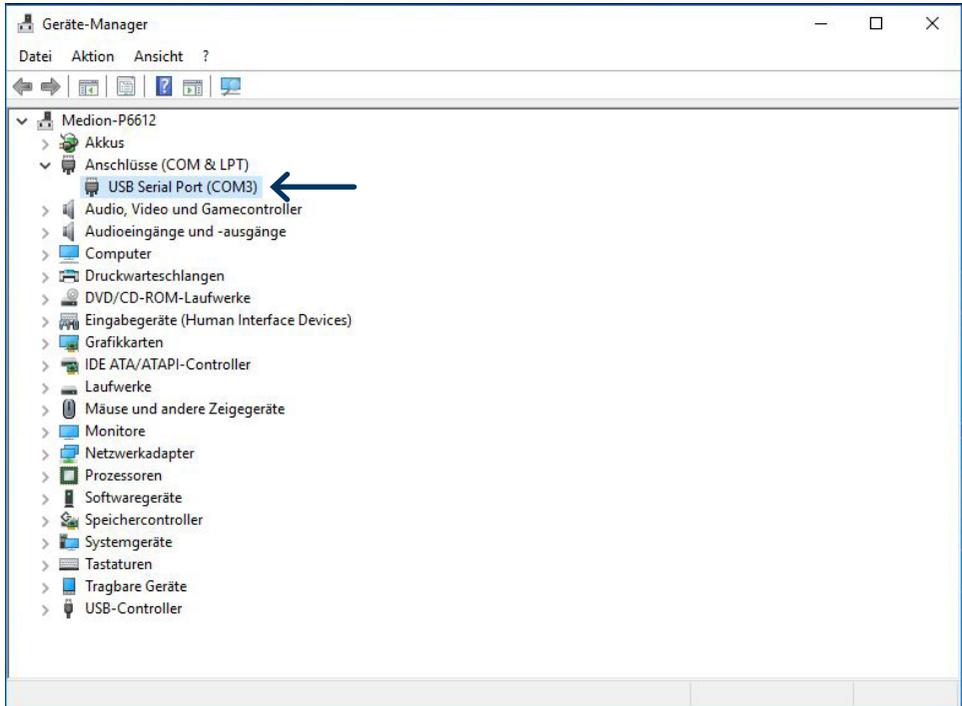
3 Manually search for driver

Click on: “Search for driver software on the computer” and select the ft232rl folder from the data carrier or the folder into which you copied the files.



4 Open driver location

The device manager will no longer display an error and the USB serial port will be displayed if the tool is connected to the computer. The software is now functional.



5 Driver detected

2 GENERAL INFORMATION

2.1 OVERVIEW

The HST-Tool-Manager is a programming interface which makes it possible to change the various parameters of the product features and functionality in all compatible tools. All settings for a tool are made with the HST-Tool-Manager via USB. The software does not require installation (only the driver has / needs to be installed).

A change in the tool can only be made if there is a connection to it.

Settings for a tool can be loaded for editing in the HST-Tool-Manager software. After the editing the file can be transferred back to the tool via USB.

2.2 INTRODUCTION

The HST-Tool-Manager requires no installation and is available as an .exe file for download at <https://www.hs-technik.eu/produkte/software:>

The HST-Tool-Manager can be copied into any directory and executed directly. However all users will require write permissions for this directory.

2.3 GUARANTEE AND LIABILITY

Guarantee and liability claims for personal injury and property damage are excluded, if caused by one or more of the following:

- unintended usage
- improper installation, commissioning, operation and maintenance
- operating the tool with defective safety devices or improperly installed, or non-functioning safety and protective devices
- non-compliance with the instructions in the operating instructions regarding transporting, storing, assembling, commissioning, operating, and maintaining the tool
- unauthorised structural changes to the tool
- improperly performed repairs
- catastrophes due to external influences and acts of God

2.4 COPYRIGHT

These operating instructions designed solely for the operator and his personnel. It contains guidelines and information which may not be fully, or partially

- reproduced
- distributed or
- otherwise shared.

The copyright of these operating instructions is retained by the company HS-Technik GmbH.

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Telephone: 07628 - 91 11-0
Fax: 07628 - 91 11-90
E-mail: info@hs-technik.com
Internet: www.hs-technik.com

2.5 SYSTEM REQUIREMENTS

The minimum system requirements for the HST-Tool-Manager:

- Windows XP, Vista, Windows 7, Windows 8 oder Windows 10 operating system
- In order to run the program on XP operating systems Microsoft .NET-Framework Version 4.0 or higher is required.
- USB 2.0
- Pentium III Processor (recommended: Dual Core)

2.6 INSTALLATION OF THE HST-TOOL-MANAGER

The software can be stored in every directory. It is important that every user on the computer has writing permission for the directory. Separate installation is not necessary.

2.7 SETTINGS OPTIONS BY USER GROUP

SETTING/FUNCTION	EVALUATION	PROGRAMMER	ADMINISTRATOR	NETWORK ADMINISTRATOR	CALIBRATOR	SERVICE
Open file	●	●	●	●	●	●
Save file		●	●	●	●	●
Print current view	●	●	●	●	●	●
Settings		●	●	●	●	●
Display		●	●	●	●	●
Data		●	●	●	●	●
Roles		●	●	●	●	●
Change user	●	●	●	●	●	●
Connect without read out			●	●	●	●
Send configuration to the tool (write)		●	●	●	●	●
Display statistics	●	●	●			
Display graphic	●	●	●			
Programming	●	●	●			
Program	●	●	●			
Program 1-100	●	●	●			
Program	●	●	●			
Counting function	●	●	●			
Measurement window	●	●	●			
Option	●	●	●			
Step 1-5	●	●	●			
Drive	●	●	●			
Switching conditions	●	●	●			

	EVALUATION	PROGRAMMER	ADMINISTRATOR	NETWORK ADMINISTRATOR	CALIBRATOR	SERVICE
Process 1	●	●	●			
Barcode	●	●	●			
Barcode 1-10	●	●	●			
Settings		●	●	●	●	●
General		●	●			
Display		●	●			
OLED Display		●	●			
Acoustic signal		●	●			
Communication			●	●		
Messages			●			
Wi-Fi				●		
IPv4				●		
IEEE 802.1x				●		
EAP				●		
EAP-TLS X.509				●		
Roaming				●		
GA Suite		●	●			
Default setting		●	●			
Update			●			
Adjustment					●	
Service						●
Log file	●	●	●	●	●	●
Change Language	●	●	●	●	●	●

2.8 SETTINGS OPTIONS BY TOOL TYPE

	TORQBEE LIGHT	TORQBEE-SO	TORQBEE-SOP	TORQBEE-ECO	TORQBEE-EC	TORQBEE-EC ²
PROGRAMMING						
Program 0 & 1	●	●	●	●	●	●
Program 2-99		●	●	●	●	●
Program	●	●	●	●	●	●
Options		●	●	●	●	●
Double Hit (Rehit)	●	●	●	●	●	●
Barcode* optional		●	●	●	●	●
Process		●	●	●	●	●
Program-table* optional		●	●	●	●	●
Graphic (Diagram)		●	●	●	●	●
Statistics		●	●	●	●	●
SETTINGS						
General	●	●	●	●	●	●
Process control		●	●	●	●	●
Energy & lighting	●	●	●	●	●	●
Functions		●	●	●	●	●
Management	●	●	●	●	●	●
Display	●	●	●	●	●	●
OLED Display		●	●	●	●	●
LEDs	●	●	●	●	●	●
Acoustic signal	●	●	●	●	●	●
Vibration	●	●	●	●	●	●
Communication* optional		●	●	●	●	●

SETTINGS

	TORQBE LIGHT	TORQBE-SO	TORQBE-SOP	TORQBE-ECO	TORQBE-EC	TORQBE-EC ²
Graphics (Settings)	●	●	●	●	●	●
System time	●	●	●	●	●	●
Default setting	●	●	●	●	●	●
Update	●	●	●	●	●	●
Adjustment			●	●	●	●
Service	●	●	●	●	●	●
MCT	●	●	●	●	●	●

3 READ OUT TOOL DATA

In order to read out the data from a tool connect it to the computer via USB or connect via Wi-Fi.



Start the HST-Tool-Manager, log in and read out the current tool by clicking on “read”. Now you can edit the settings as described in the following steps. So that the tool parametrization is not lost we recommend saving this separating under another name.



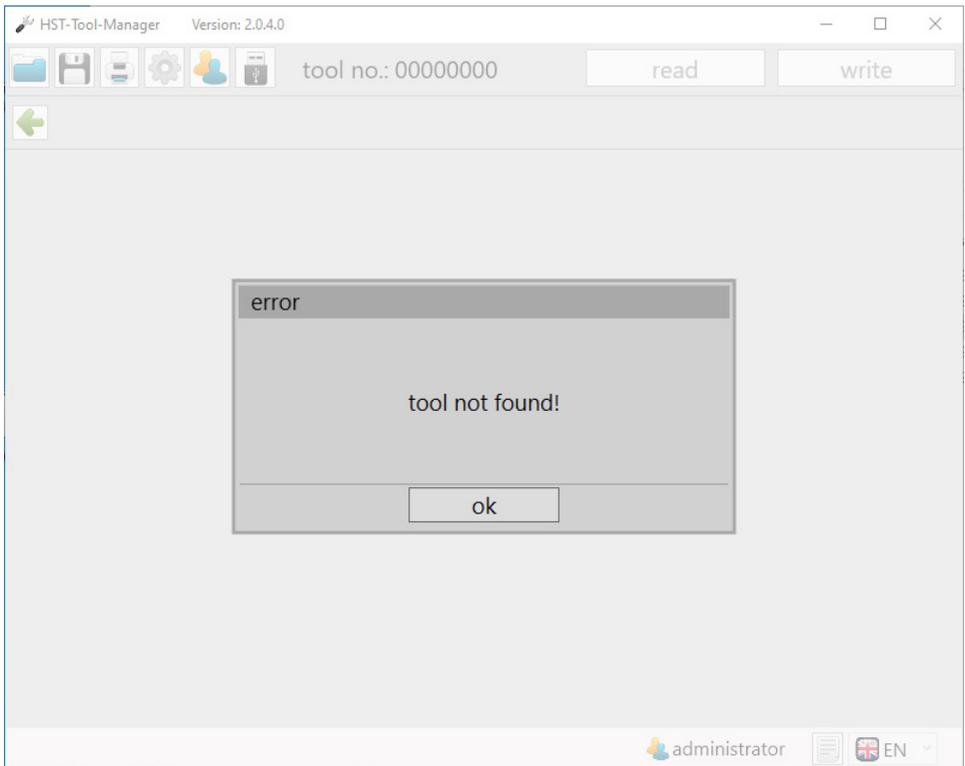
DANGER

With every use of the HST-Tool-Manager the corresponding operating instructions for operating the tool must be read and understood!



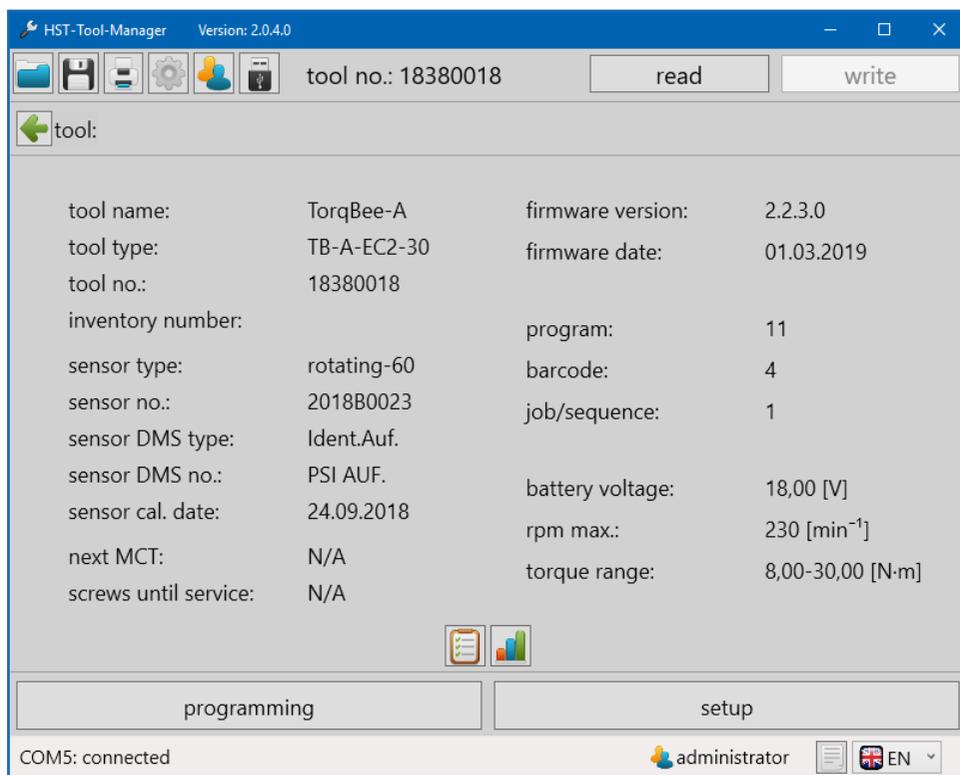
NOTE

It rare cases the data may not be loaded right away. Click on „read“ again, if this does not work check the cable connection as well as the USB driver and repeat the process.



6 Not found

3.1 BASIC INFORMATION ON THE TOOL

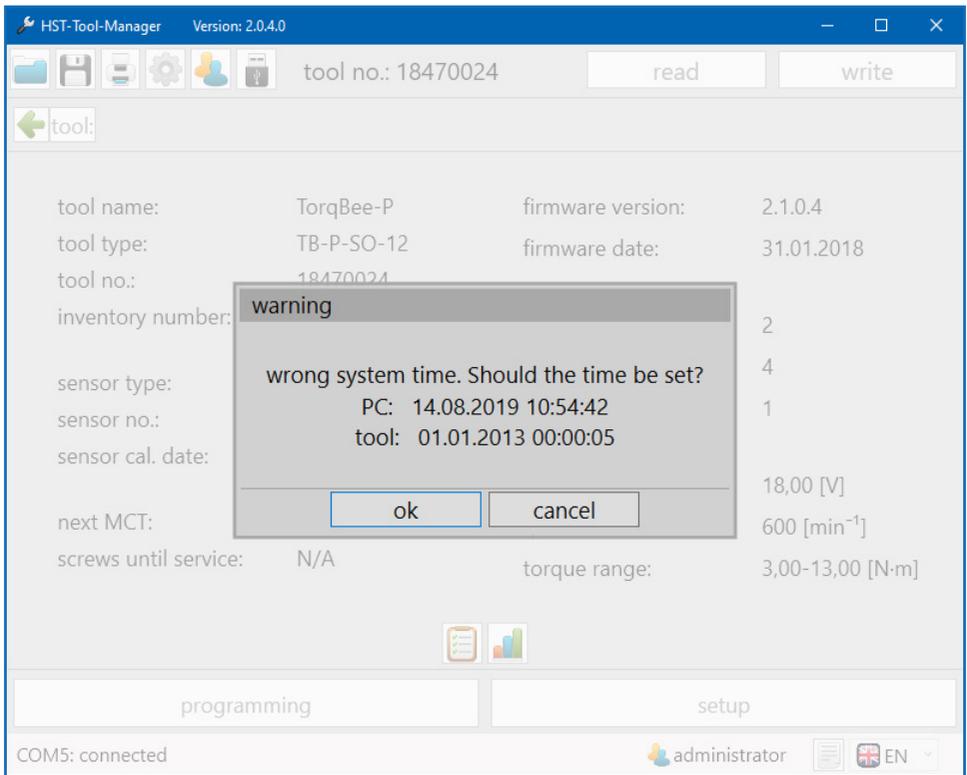


7 Homepage

The basic information about the tool is displayed. Depending on the type of tool different information is displayed.

“tool name”	Manufacturer’s designation
“tool type”	Basic article number of the manufacturer
“tool no.”	Serial number of the tool
“inventory number”	Can be specified under settings - management by the administrator.

“sensor type”	Built in sensor type
“sensor no.”	Serial number of sensor
“sensor DMS type”	Built in DMS sensor type
“Sensor DMS no.”	Serial number of the DMS sensor
“sensor cal. date”	Last calibration of the sensor
“next MCT”	Date of the next MCT
“screws until service”	At 0 turns the tool must go to maintenance and be inspected.
“firmware version”	Firmware version on the tool
“firmware date”	Creation date of the firmware
“program”	Number of saved programs which are available on the tool.
“barcode”	Number of saved barcodes which are available on the tool.
“job/sequence”	Number of saved processes which are available on the tool.
“battery voltage”	Nominal voltage of the battery: The tool can only be operated with batteries with this nominal voltage.
“rpm max.”	Maximum idling speed with which the tool can be operated.
“torque range”	Torque range within which the tool can be operated.



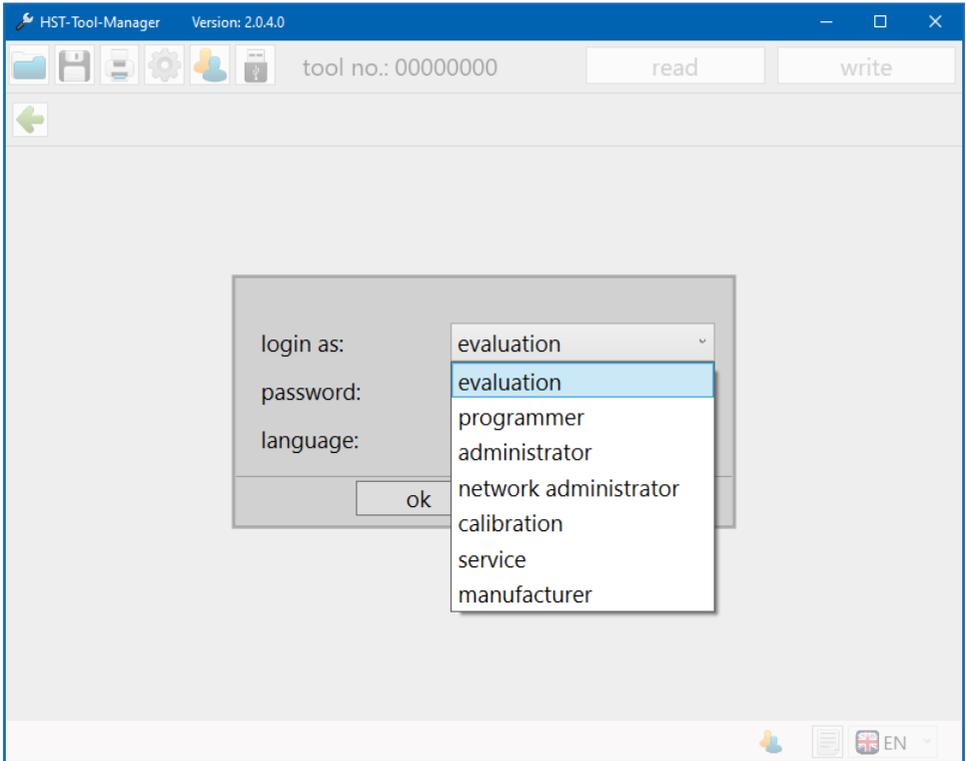
8 System time

If the system time and the time on the tool amounts to a difference of more than 30 seconds a warning will appear indicating that the system time is incorrect. Click on "ok" in order to adjust to the time on the tool. The update system time is required in order to correctly record the time stamp of the wrenching process. Click "cancel" for no synchronisation to take place.

4 FIRST STEPS

4.1 LOGIN TO THE HST-TOOL-MANAGER

In order to start the HST-Tool-Manager you will need the login data as “evaluation”, “programmer”, “administrator”, “network administrator”, “calibration” or “service”.



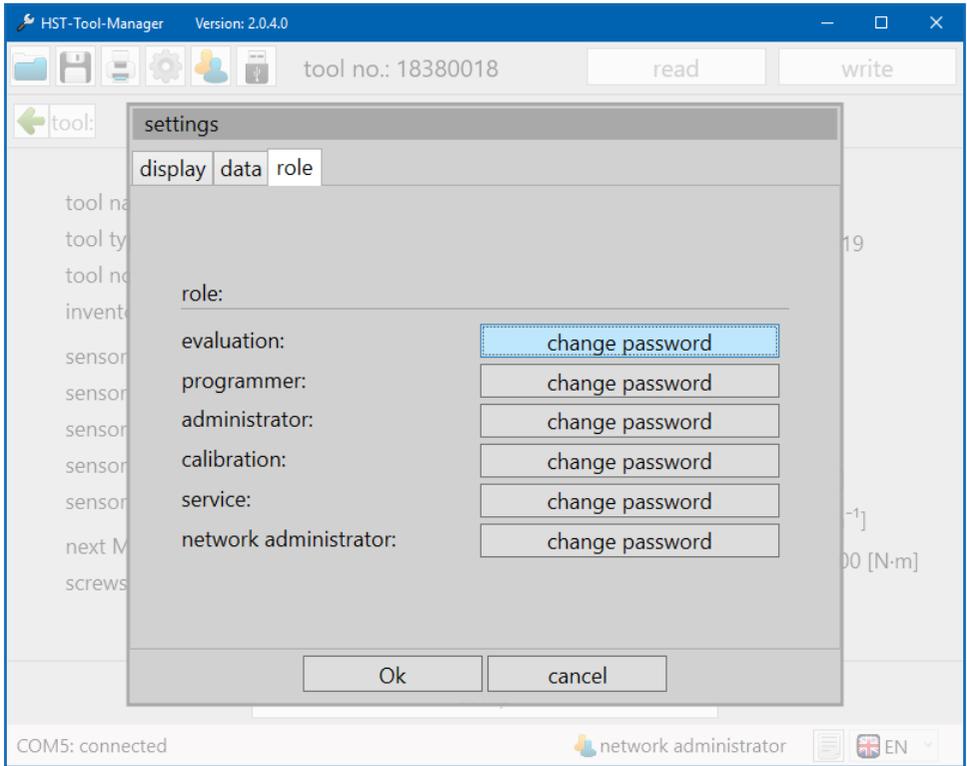
9 Logon

WHERE DO I FIND THE PASSWORDS?

The passwords are delivered in printed form upon delivery to the key contact, or purchaser for the tools.

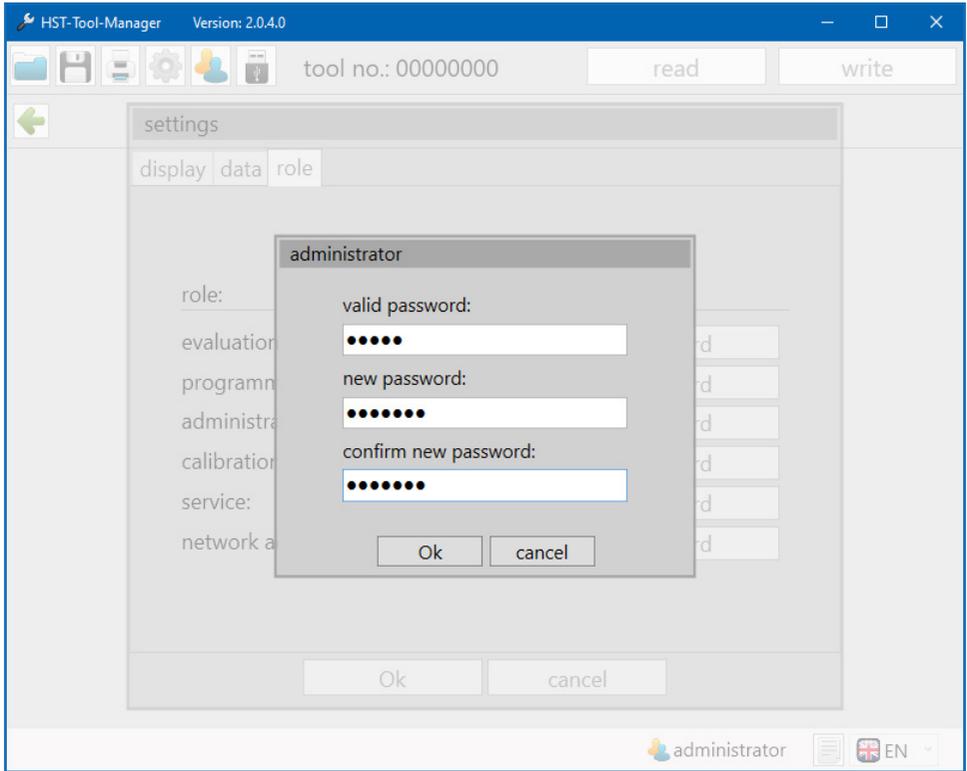
In settings under „role“ the passwords for the individual user types (roles) can be changed. To do this you must click on “change password”.

Each user group may only be assigned 1 password. In order to change the password the current password is required.



10 Change roles

After clicking “change password” for the corresponding user group, the pop-up window for changing the password opens. At the top, in the header of the window, the display indicates which user group the password change is being made for. First, the current keyword must be entered. Then the new keyword must be entered twice. When one of the above-mentioned conditions is not met the “Ok” button for confirming the change of the password remains greyed out.



11 Change password

4.2 SET STORAGE LOCATION



DANGER

Only work with a correctly adjusted tool and only with a tool whose settings and programming you are familiar with.

After logging on as an administrator go to settings in the top left of the toolbox.

HST-Tool-Manager Version: 2.0.4.0

tool no.: 18380018 read write

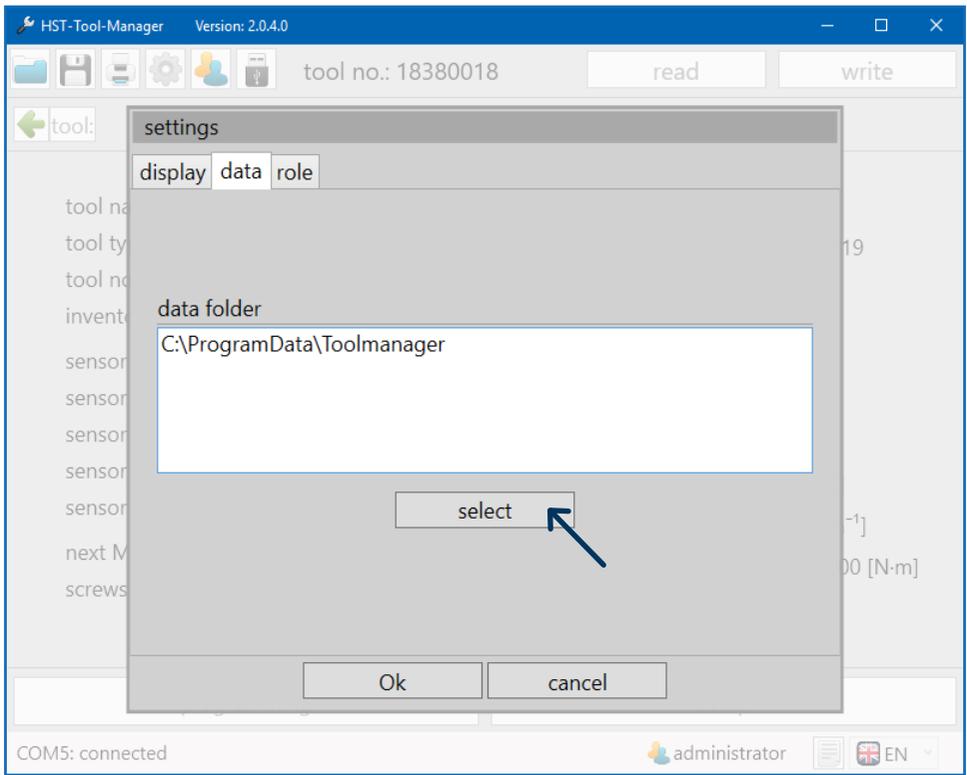
tool:

tool name:	TorqBee-A	firmware version:	2.2.3.0
tool type:	TB-A-EC2-30	firmware date:	01.03.2019
tool no.:	18380018		
inventory number:		program:	11
sensor type:	rotating-60	barcode:	4
sensor no.:	2018B0023	job/sequence:	1
sensor DMS type:	Ident.Auf.		
sensor DMS no.:	PSI AUF.	battery voltage:	18,00 [V]
sensor cal. date:	24.09.2018	rpm max.:	230 [min ⁻¹]
next MCT:	N/A	torque range:	8,00-30,00 [N·m]
screws until service:	N/A		

programming setup

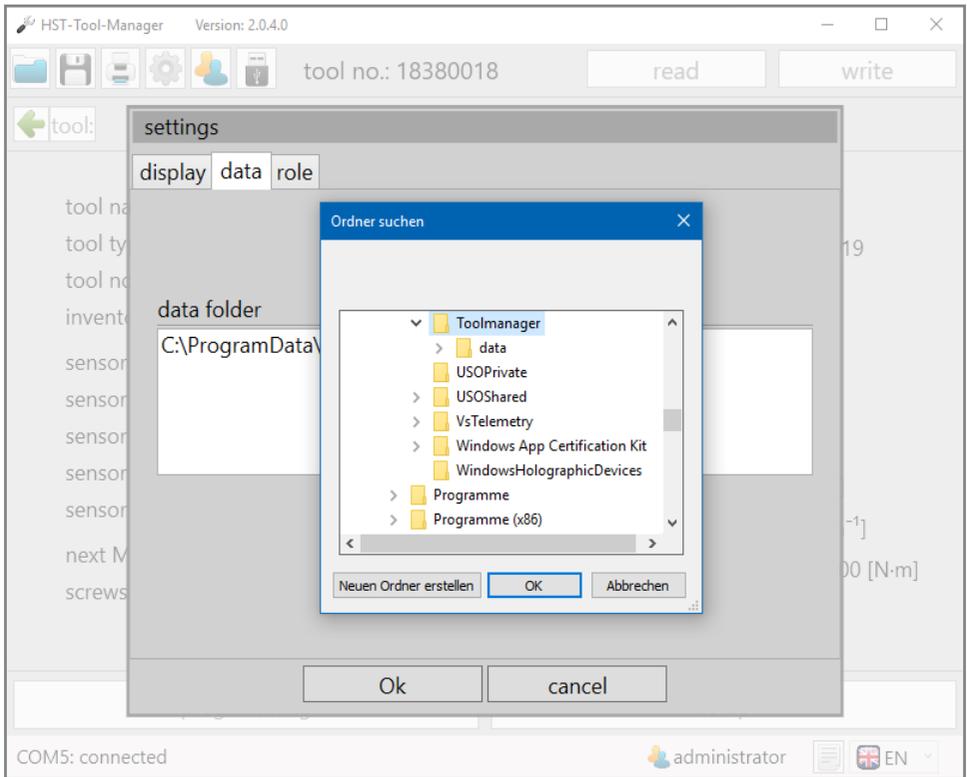
COM5: connected administrator EN

12 Homepage



13 File path

Now go to the “data” tab in the opened pop-up window and click on “select” in order to specify a new storage location.



14 Settings data storage location

Select the new storage location. In our case it is a software folder on the desktop.

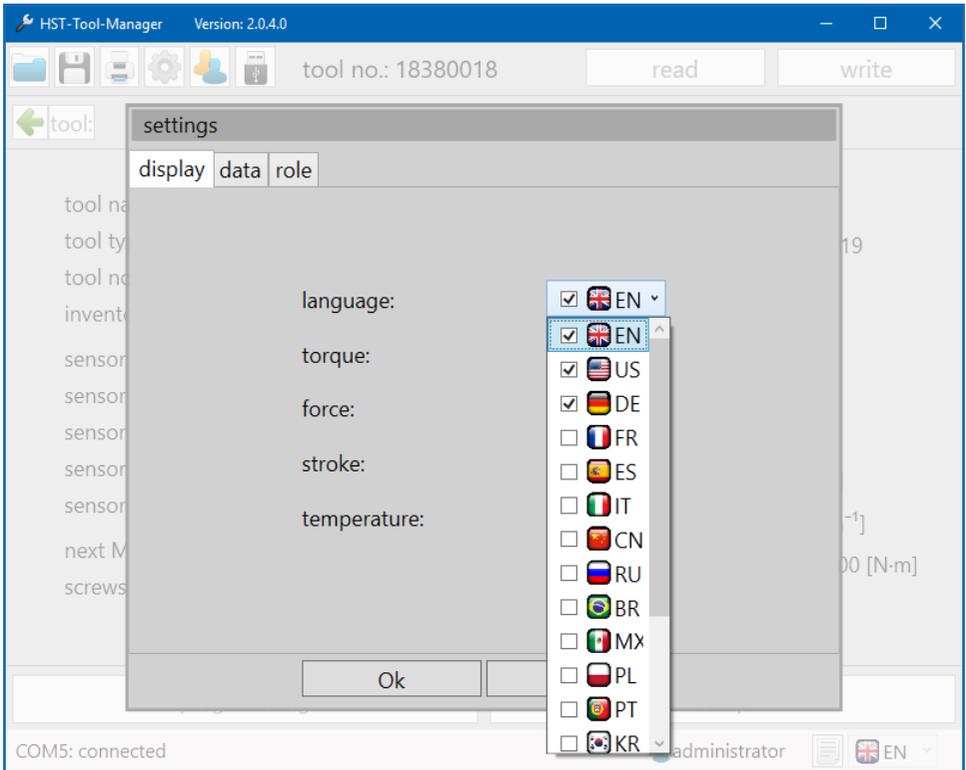
The “data” folder is automatically created in the folder selected. Backup copies and log files for the tool are automatically saved here.

Afterwards, click “OK”.

The data folder is once again displayed in the pop-up window. By clicking “OK” you will confirm the storage location.

4.3 ACTIVATE ADDITIONAL LANGUAGES

In order to now activate additional languages for other users go to

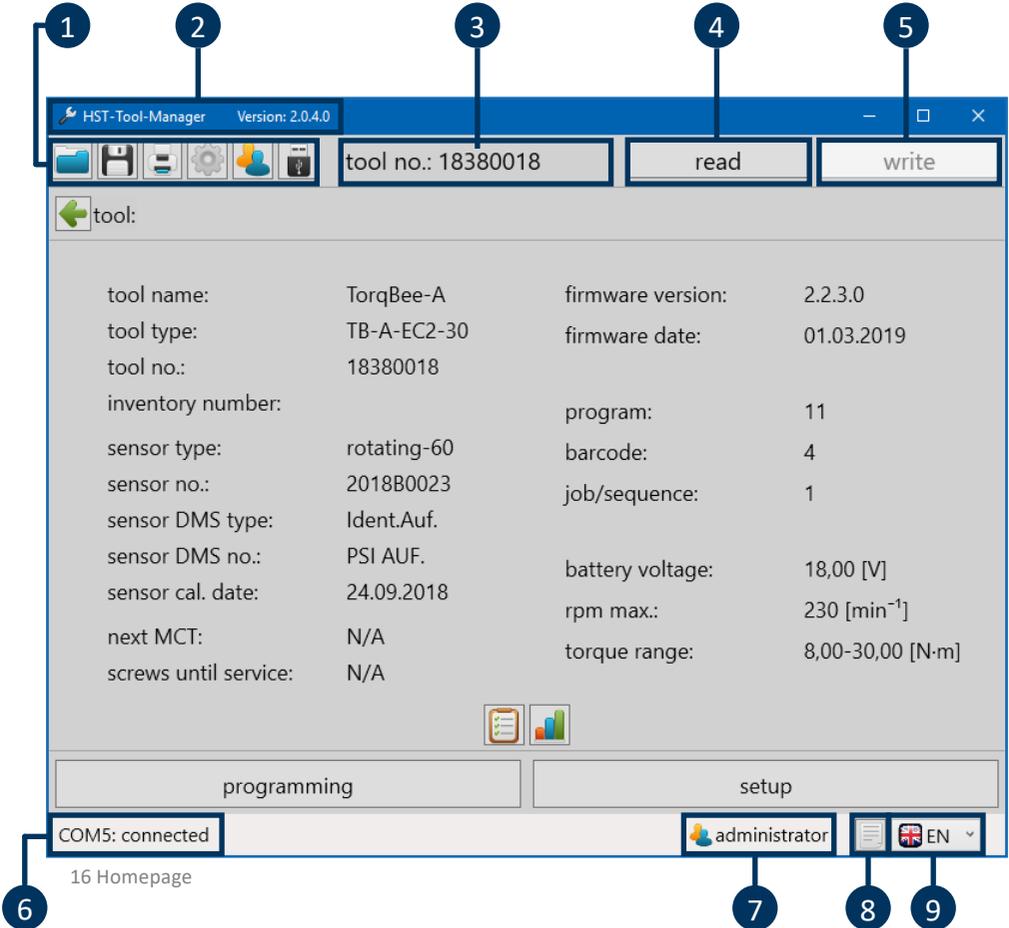


15 Languages

Open the drop down menu and activate the desired languages for the users by clicking in the box in front of the language. The software will start in the language highlighted in blue. The display settings “language” - “torque” - “force” - “stroke” - “temperature”, may only be made by an administrator. All languages which are selected are then permanently available for the users.

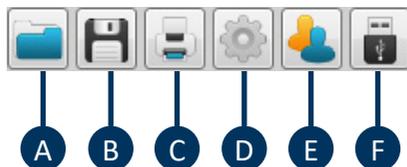
4.4 GENERAL SOFTWARE INTERFACE

The start window



The start window after login contains various messages and buttons which are important for working with the HST-Tool-Manager.

1 Toolbox



- A Load saved configuration
- B Save current configuration
- C Print menu (multiple options)
- D Display settings (language, torque, power, path, temperature)
- E Change user
- F Connect with the tool without read out (in order to conduct the update or to restore the tool in an emergency)

2 Software version

 HST-Tool-Manager Version: 2.0.4.0

Displays the opened software version.

3 Tool number

tool no.: 18380018

After connecting and the read out the serial number of the connected tool is displayed.

4 Read

read

After connecting the tool all internal tool data is read out of the tool using the “read” button. Do not double click because this can lead to errors in the software.

5 Write

write

After configuration of the tool all the changed data is sent to the tool using the “write” button. The button only becomes active after changing configurations or parameters.

6 COM Port

COM5: connected

Message box for the status of the connection with the tool.

7 User display

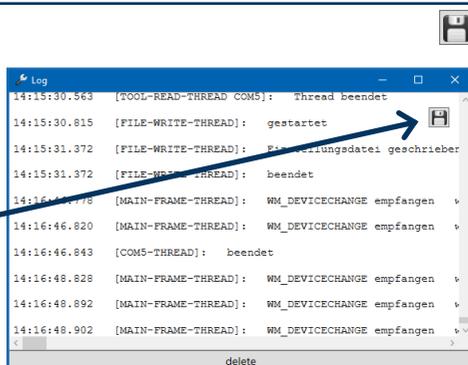
 administrator

The user display shows which user is active (evaluation, administrator,...).

8 Log window

Show or hide the log window or save on the data carrier as a text file. The communication between the tool and the software is recorded in the log.

It is a good aide in those instances when the tool cannot be completely or partially read out. The log file provides detailed information about where the problem is and is intended for technical support. The log contains primarily specific notifications. e.g. in the event of a problem show the log window, save as a .txt file and send it to the technical support.



9 Language

 EN

The language can be temporarily changed in the language drop down menu (bottom right).

4.4.1 DIRECT HELP OPTION

The screenshot displays the HST-Tool-Manager software interface (Version: 2.0.4.0) with a help tooltip. The tooltip text reads: "enable / disable lower torque limit - exceeding results in stop of the tool and NOK evaluation".

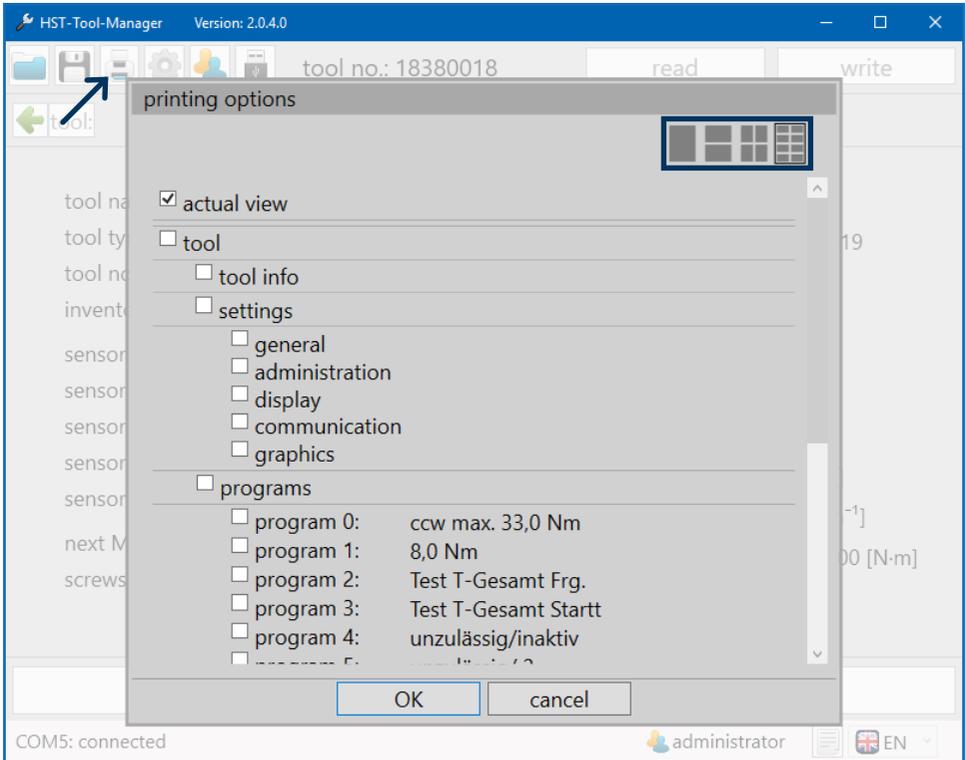
The interface includes the following elements:

- Tool no.: 18380018
- Buttons: read, write
- Navigation: tool: programs: program 1: step 2: (with back and forward arrows)
- Tabs: general, gear, strategy, option, evaluation
- Shifting conditions section:
 - torque: Mtarget 8,00 [N-m]
 - Mstart 4,00 [N-m]
 - Mlimit* 0,00 [N-m]
- Evaluation section:
 - torque: 7,44 ≤ Mactual ≤ 8,56 [N-m] %
 - angle: 10 ≤ α actual ≤ 1080 [°]
 - current:
- Graph: torque [N-m] and current [A] vs. angle [°] and time [s]. The graph shows a blue curve starting at Mstart = 4,00 N-m. The x-axis has markers for α_min = 10 and α_max = 1080.
- Status bar: COM5: connected, administrator, EN

17 Help

If you place the cursor over an input field or over an ON / OFF Button, a help text for the associated function will appear automatically.

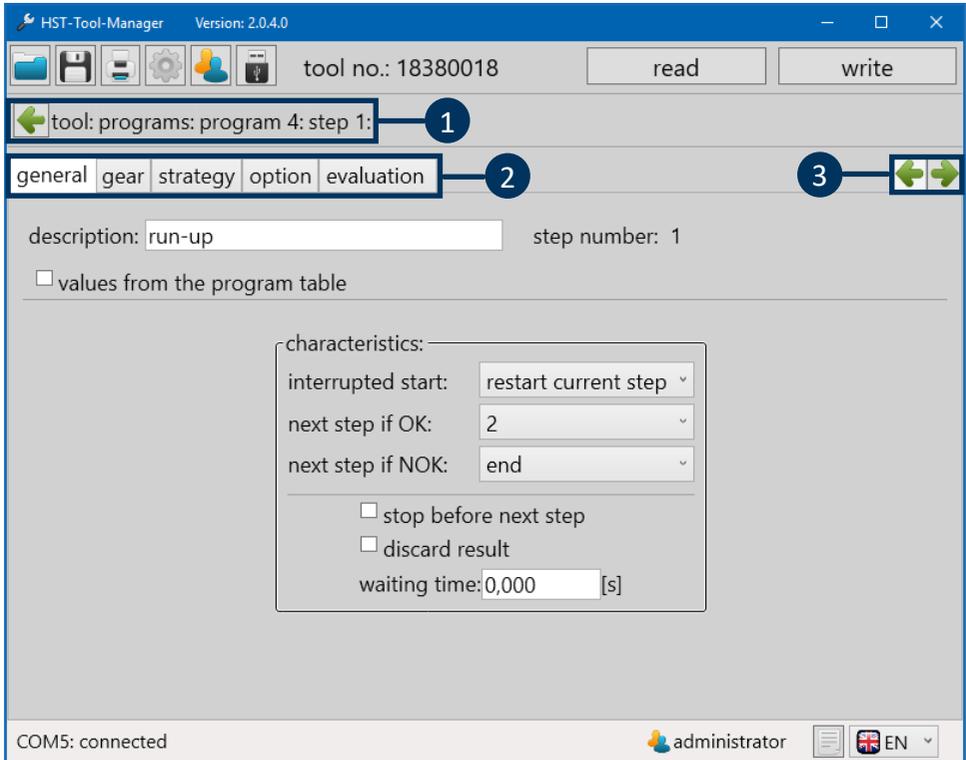
4.4.2 PRINT OPTION



18 Print options

In order to print data, programs or settings in a clear format a special print option was integrated which makes it possible to print every view from different pages. In addition, at the top right you can specify whether 1, 2, 4 or 8 of the pages should be printed on one DIN-A4 page. With co-option and deselection the desired number of pages can be printed. Each selected element is printed. In this example the current view will be printed.

4.5 GENERAL OPERATION



19 Operator interface

1

Navigation Bar

Here you are taken directly back to the desired subitem by clicking on the individual fields. For example, click on programming in order to get to the program overview. Alternatively you will go back one level with one click on the green arrow.

2

Register

In this register you can switch between the individual tabs. The navigation buttons are connected with the register.

3 Navigation Buttons

These elements are only available in the steps. Using these you can toggle between the current view and the next step quickly, in order to compare them.

Currently one would go to step 2 with the right arrow and nothing would happen with the left arrow because we are currently in step 1.

Conversion of reference values from
“is equal or larger than” to 
“is equal or smaller than” 
the value entered.

Check all entries and send to the tool by clicking on “write”.

write

Many input areas have a limit. If a red box appears around the number which you would like to enter then it is too high, too low, or invalid characters are being used.

5000 [s]

5 TOOL SETTINGS

After reading out every tool a homepage with type-specific information is displayed. Different settings can be made in each tool type which are important for working at the workplace, or which make the work easier. In order to clarify the settings they are divided into individual tabs. Go to the homepage and click on "setup".



NOTE

Changes can only be made to a tool that is connected.

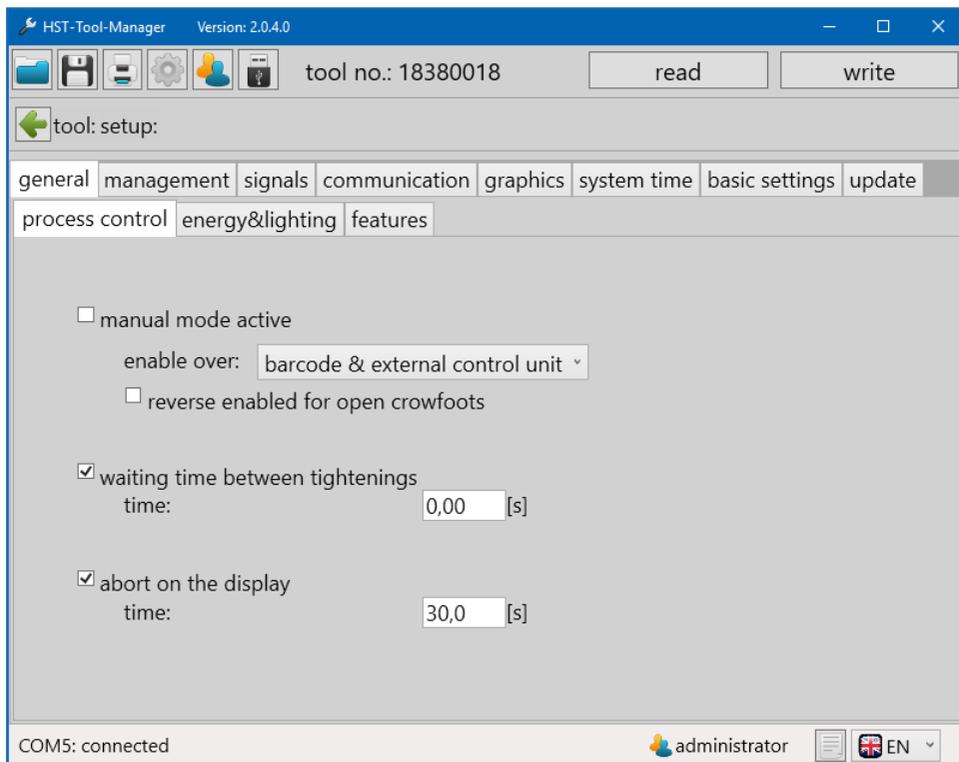
The screenshot shows the HST-Tool-Manager software interface. The title bar indicates the version is 2.0.4.0. The main window displays tool information for tool no. 18380018. The tool name is TorqBee-A, and the firmware version is 2.2.3.0. The tool type is TB-A-EC2-30, and the firmware date is 01.03.2019. The tool no. is 18380018. The inventory number is blank. The sensor type is rotating-60, and the sensor no. is 2018B0023. The sensor DMS type is Ident.Auf., and the sensor DMS no. is PSI AUF. The sensor cal. date is 24.09.2018. The next MCT is N/A, and the screws until service is N/A. The program is 11, the barcode is 4, and the job/sequence is 1. The battery voltage is 18,00 [V], the rpm max. is 230 [min⁻¹], and the torque range is 8,00-30,00 [N-m]. The interface includes a 'programming' tab and a 'setup' tab, with a blue arrow pointing to the 'setup' tab. The status bar shows 'COM5: connected' and the user 'administrator'.

tool name:	TorqBee-A	firmware version:	2.2.3.0
tool type:	TB-A-EC2-30	firmware date:	01.03.2019
tool no.:	18380018		
inventory number:		program:	11
sensor type:	rotating-60	barcode:	4
sensor no.:	2018B0023	job/sequence:	1
sensor DMS type:	Ident.Auf.		
sensor DMS no.:	PSI AUF.	battery voltage:	18,00 [V]
sensor cal. date:	24.09.2018	rpm max.:	230 [min ⁻¹]
next MCT:	N/A	torque range:	8,00-30,00 [N-m]
screws until service:	N/A		

20 Homepage

5.1 TAB “GENERAL”

5.1.1 PROCESS CONTROL



21 Process control

„manual mode active“

In applications in which the tool is being used as an individual solution this mode can be activated. If a connected tool needs to be quickly tested without being connected to a controller this mode can also be activated. When deselecting the type of enabling must be selected using the drop-down menu.

“enable over”

- “start key”

press the start key 3x in quick succession in order to enable the tool.

- “time”
Enables the tool after time entered in seconds.
- “start key & time”
Combination of function start key and time.
- “barcode”
Enabling through correct barcode scan.
- “external control”
External control issues the enabling.
- “barcode & external control”
After scanning a barcode external control issues the enabling.



“reverse enabled for open crowfoots”

Is used for open flat drives in particular. By activating the checkbox you can always screw backwards.

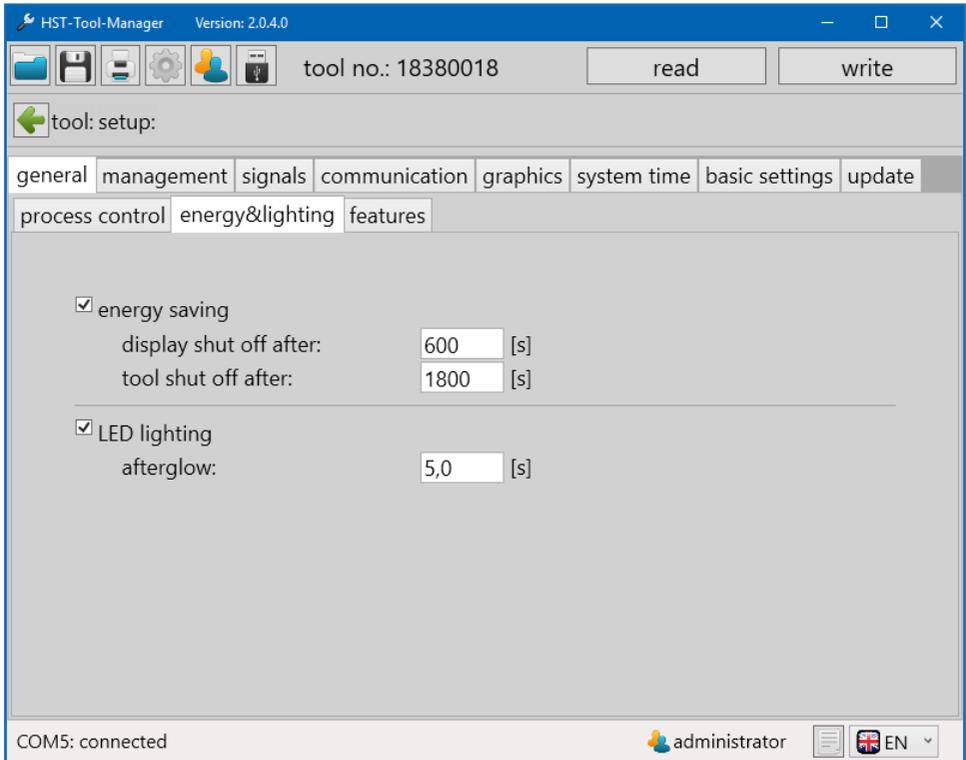
“waiting time between tightenings”

Break time between the individual screw connections of a job/sequence.

“abort on the display”

Cancellation of an active job/sequence using the yellow button on the display. The time determines the length of time the button must be pushed until the prompt for interruption appears on the display  .

5.1.2 ENERGY AND LIGHTING



22 Energy and lighting

“energy saving”

“display shut off after”

Display switches to standby after the time entered in seconds, if the tool is not being used.

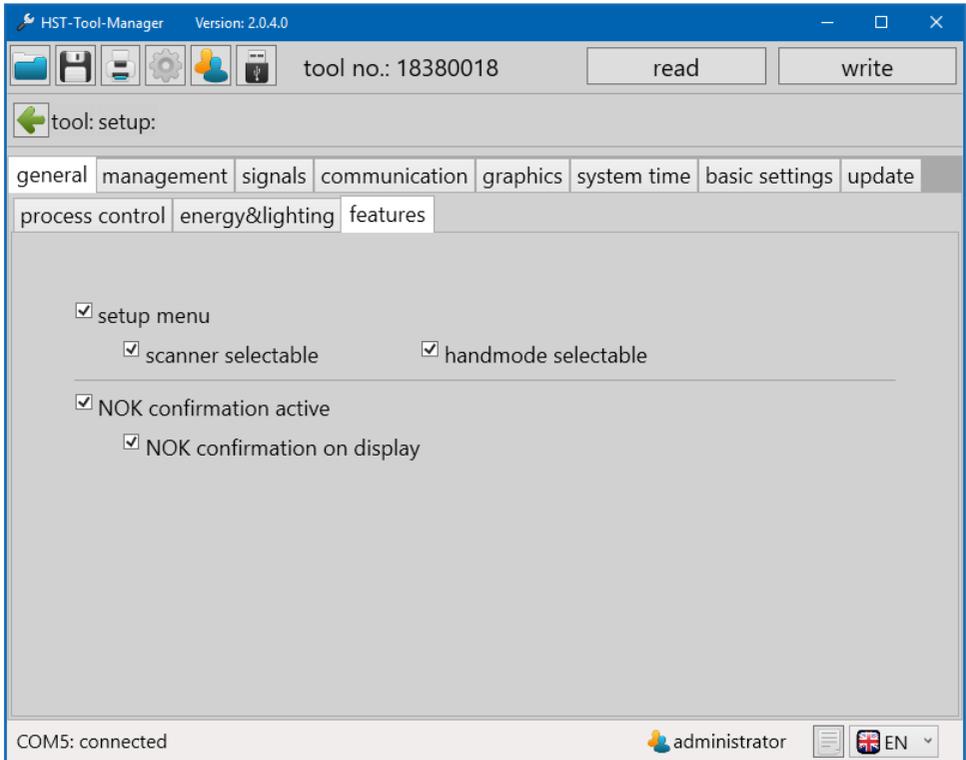
“tool shut off after”

Tool powers off after the time entered in seconds, if it is not being used.

“LED lighting
afterglow”

With every activation of the trigger switch the lighting LED is activated. The LED continues to glow for the length of time entered in seconds.

5.1.3 FEATURES



23 Functions

“setup menu”



If this function is selected the program or the process can be changed using the keys under the display, or the torque can be adjusted in Program 1. In order to get into setup mode hold down the start key and push the battery up.

If “scanner selectable” is activated you can now go to the display in setup mode with the yellow display key  and confirm by pressing the start key. Then you must still confirm the left adjustment knob (on the left next to the yellow display knob). This way barcodes can be scanned in the emergency strategy or also the network settings.

If you have activated “handmode selectable” you can now go in setup mode with the yellow display key to the display **M** then you must still confirm the left adjustment knob (on left next to the yellow display knob). Now the tool will execute the default program which is identified with a yellow star in the tool manager.

“NOK conformation active”

In the event of a NOK result it must be loosened in an anti-clockwise direction and tightened again.

“NOK confirmation on display”

Acknowledgement NOK screw connection with yellow key on display or loosen in the case of a NOK - screw connection. Must be selected under programs under “characteristics”.

5.2 TAB “MANAGEMENT”

HST-Tool-Manager Version: 2.0.4.0

tool no.: 18380018 read write

tool: setup:

general management signals communication graphics system time basic settings update

location: Hall 1, Position 4

inventory number: HQX61859234

COM5: connected administrator EN

24 Administration

“location”

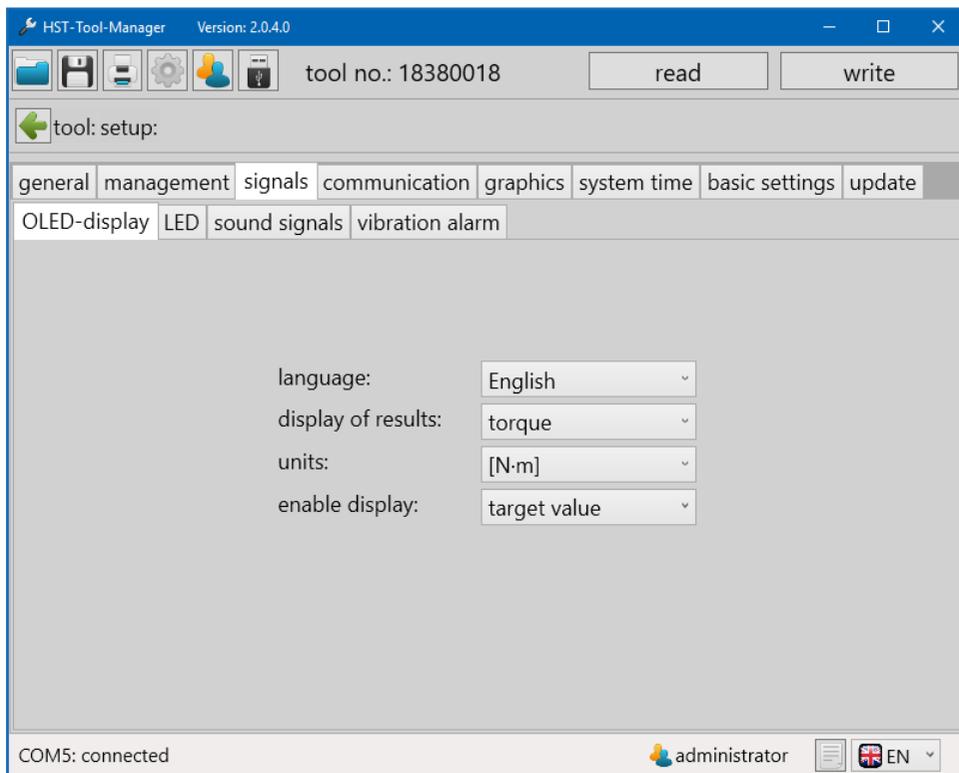
Freely writeable text lines in order to enter the location for use or the system on which the tool will be used. This field is limited to 20 characters.

“inventory number”

Freely writeable text lines in order to enter the internal company inventory number. This field is limited to 40 characters.

5.3 TAB “SIGNALS”

5.3.1 OLED-DISPLAY



25 OLED-Display

“language”

One of 2 languages may be selected for the display of the tool and its display.

- *German*
- *English*

“display of results”

In the display for the evaluation of the screw connection various modes can be displayed.

- *Smiley*
- *Torque*
- *Counter*
- *Angle*

“units”

Setting the physical unit.

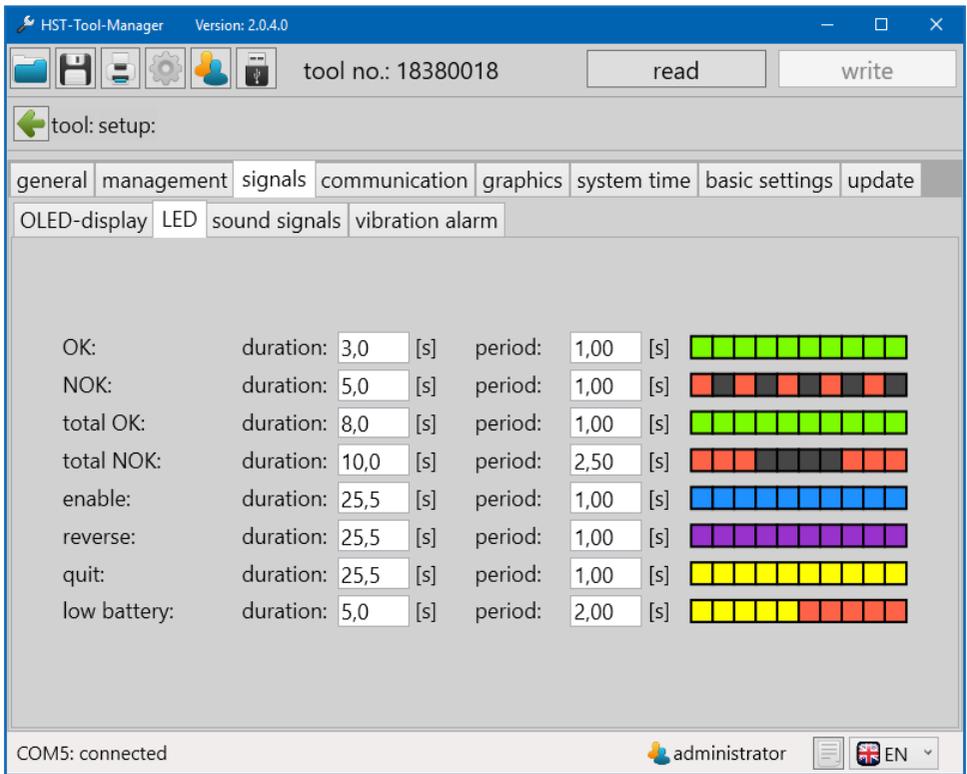
- $N \cdot m$
 - $Lbf \cdot in$
 - $Lbf \cdot ft$
-

“enable display”

Determines the information shown in the display upon receipt of an enabling.

- *Target value*: Displays the target value of the last step (in case of multiple switching conditions torque is prioritised).
 - *Barcode*: Barcode ID for enabling is displayed.
-

5.3.2 LED



26 LED

One LED signal each may be selected for the various results and information:

“duration” Total duration of the LED signal. (25.5. seconds = continuous light)

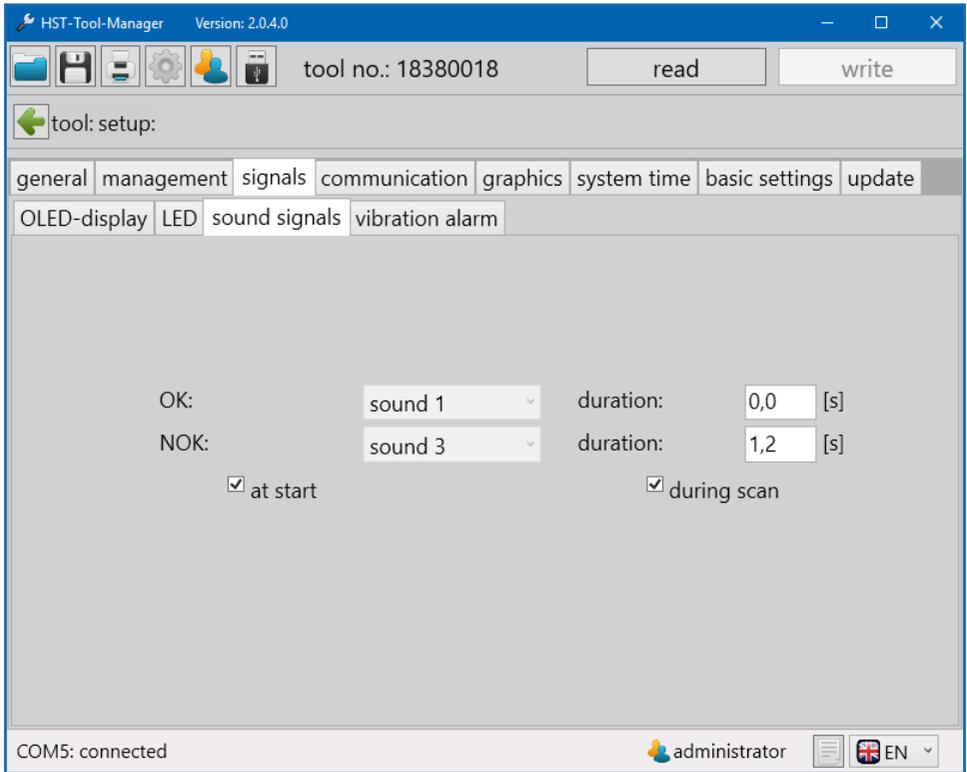
“period” Duration of the signal sequence

Selectable colours



The colours of the LED lights can be changed by clicking on the coloured fields.

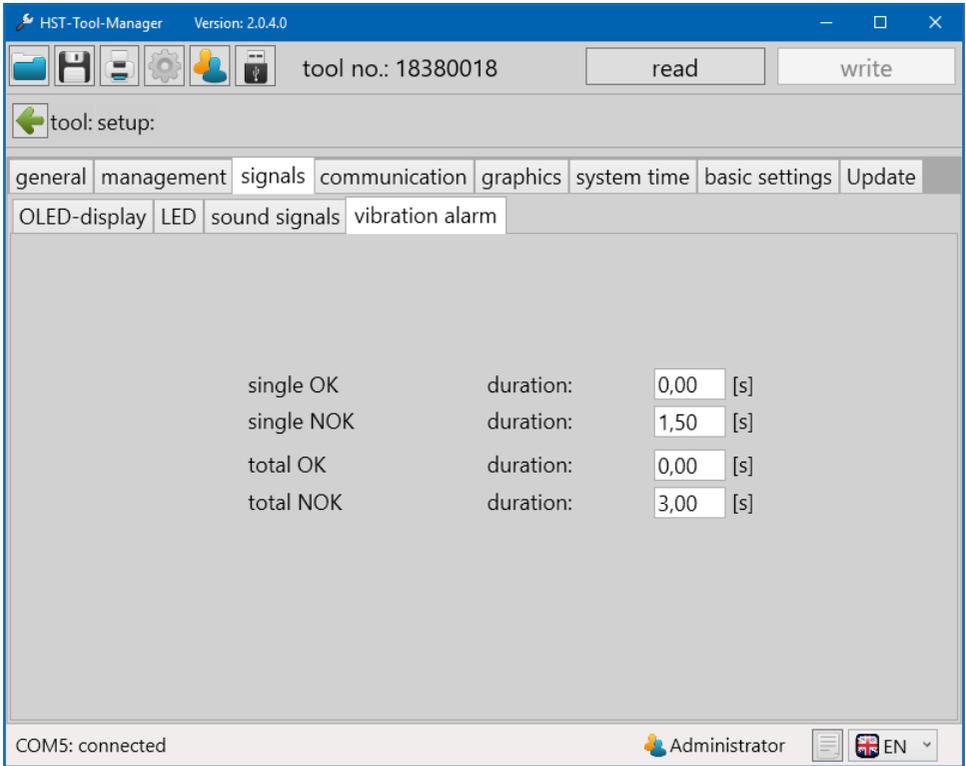
5.3.3 SOUND SIGNALS



27 Acoustic signal

“OK”	Signal tone is activated for the time entered. (can be deactivated with the value 0)
“NOK”	Signal tone is activated for the time entered. (can be deactivated with the value 0)
“at start”	After pushing in the battery a melody is played.
“during scan”	After scanning a barcode a signal tone is heard.

5.3.4 VIBRATION ALARM



28 Vibration

The duration of the vibration can be specified for each of the individual screw connection results (single OK / single NOK / total OK / total NOK).

5.4 TAB “COMMUNICATION”

5.4.1 WI-FI (only network administrator)

The screenshot shows the HST-Tool-Manager software interface. The title bar indicates the version is 2.0.4.0. The main window has a blue header with icons for file operations and a status bar showing 'tool no.: 18380018' and buttons for 'read' and 'write'. Below the header, there is a 'tool: setup:' section with a green arrow icon. The 'communication' tab is selected, and the 'Wi-Fi' sub-tab is active. The settings are as follows:

authentication type:	WPA2
SSID:	Customer Network
network key:	123456789
region:	Europe
band:	2.4 GHz
transmitting power:	17 dBm / 50 mW
channel list:	auto

At the bottom of the window, the status bar shows 'COM5: connected', the user 'network administrator', and a language dropdown set to 'EN'. A QR code is visible in the bottom right corner of the main settings area.

29 Wi-Fi Communication

The network settings of the tool are saved under communication Wi-Fi & IPv4; these serve as communication between the tool and an external control.



NOTE

Under the communication tab there are various access functions for administrators and network administrators.

“authentication type”	Select Wi-Fi Encryption procedure
“SSID”	Service Set Identifier Network name
“network key”	Password for the network. The entry in the “SSID” or “network key” window can be encrypted using the button with the key symbol.
“region”	Provision of the wireless channels depending on the region selected. Selection must correspond with the setting in the access point used. (US/Europe/Japan)
“band”	Select frequency band for data transmission Frequency band: 2.4 GHz / 5 GHz
“transmitting power”	Must be selected depending on the distance between the tool and control, or access point.
“channel list”	Activation / deactivation of different wireless channels.

5.4.2 IPV4

HST-Tool-Manager Version: 2.0.4.0

tool no.: 18380018 read write

tool: setup:

communication

Wi-Fi IPv4 IEEE 802.1X roaming

network protocol: TCP

DHCP

own IP-address: 192.168.1.12 port: 8002 - 8002

server IP-address: 192.168.1.1 port: 8001

subnet mask: 255.255.255.0

default gateway: 192.168.1.250

MAC: 00:23:A7:50:A3:E3

COM5: connected network administrator EN

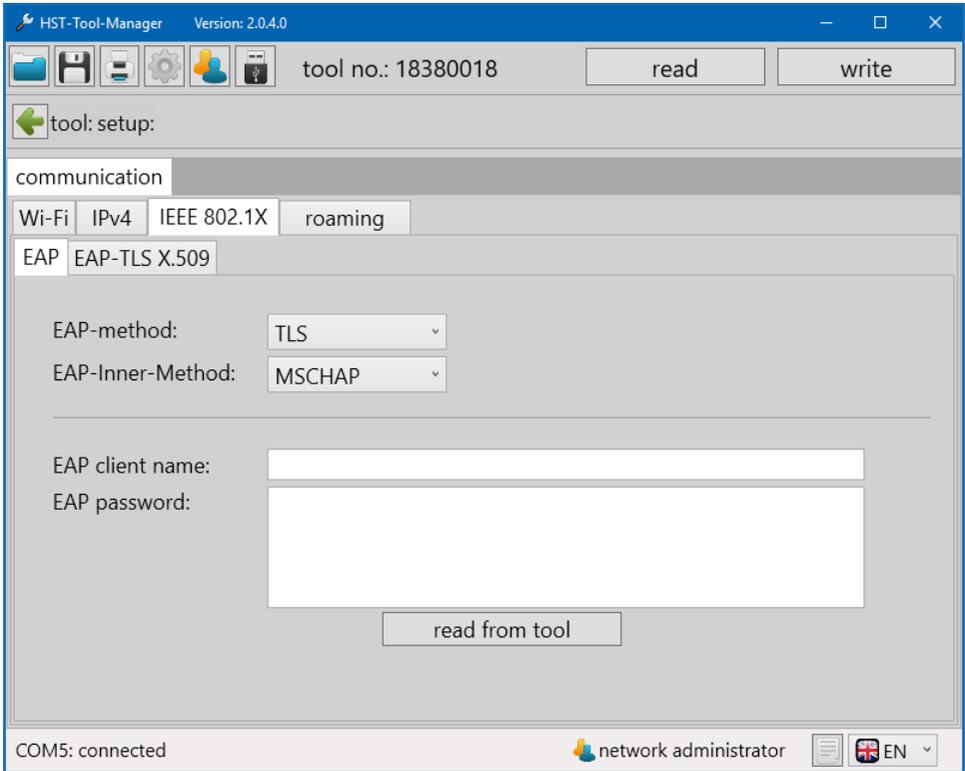
30 IPv4 Communication

In the case of IPv4 you can select between the network protocol TCP or UDP.

“network protocol”	A selection can be made between the protocol type TCP and the older version UDP. We recommend using the TCP protocol.
“own IP-address / Port”	IP address of the tool and associated port. Here there is the option to specify an area. With each new connection set-up the port number is increased by one.
“server IP-address / Port”	IP address of the controller (control e.g. HST-MCU) and associated port.

“subnet mask”	Subnet mask, belonging to IP network.
“default gateway”	The IP address of the router. Relevant in the event the control and tool are located in different IP networks.
“MAC”	MAC address of the tool.

5.4.3 IEEE 802.1X EAP



31 EAP Communication

“EAP-method” Encryption methods:
- TLS
- TTLS
- FAST
- PEAP

“EAP-Inner-Method” Encryption methods:
- MSCHAP
- MSCHAPV2

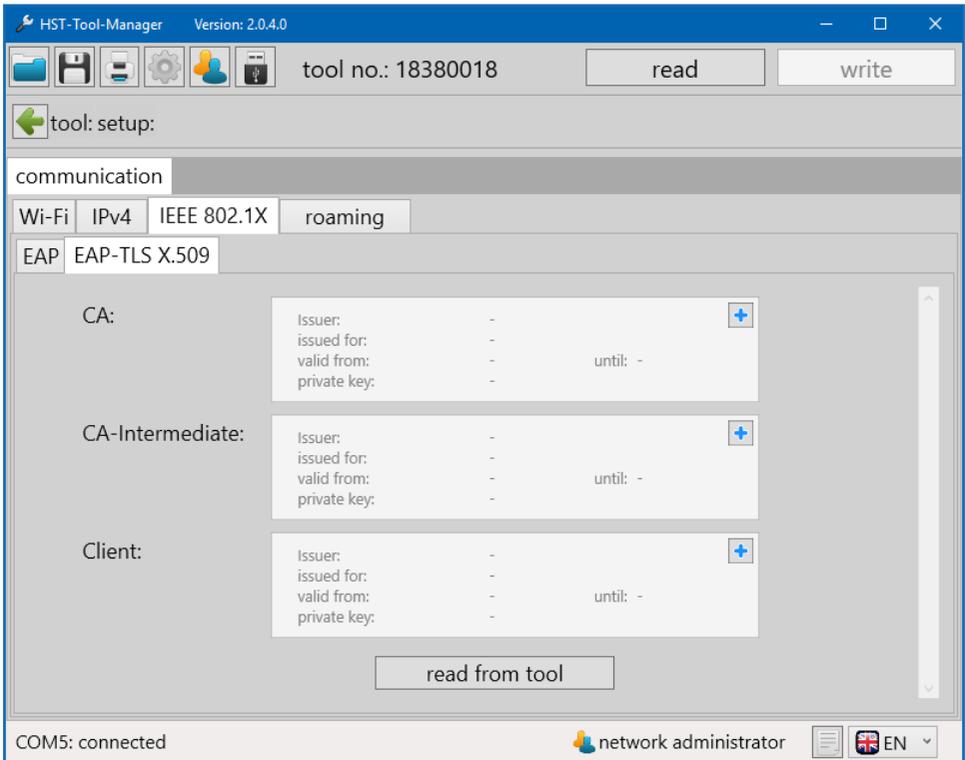
“EAP Client name” Client name for EAP encryption.

“EAP password” Password for the EAP encryption.



Assumes the changes in the tool. The green check mark only appears if something is entered in the fields “EAP client name” and “EAP password”.

“Read out of the tool” Reads the EAP settings from the tool.

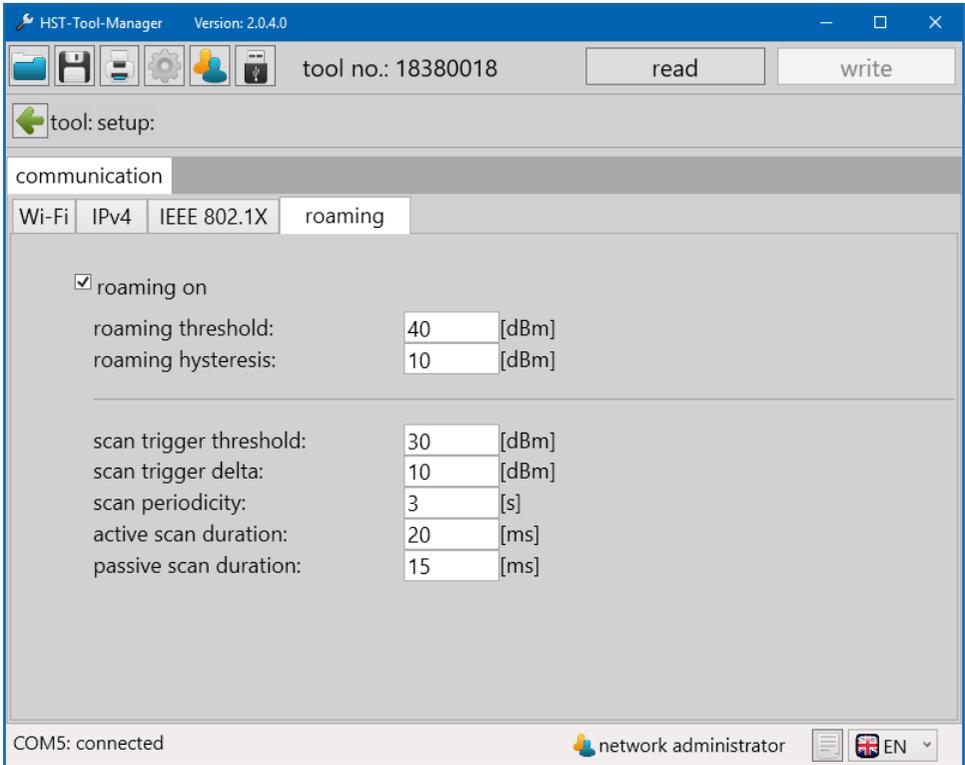


32 Communication EAP TLS X.509

In the EAP-TLS encryption it is possible to load a certificate chain in the tool.

"CA"	CA certificate
"CA-Intermediate"	CA intermediate certificate: Depending on the wireless module multiple certificates can be loaded/ saved.
"Client"	Client key
	Assumes the changes in the tool. The green check mark only appears if something is entered in the fields "EAP client name" and "EAP pass- word".
"read from tool"	Reads the EAP settings from the tool.

5.4.4 ROAMING



33 Roaming Communication

When roaming is activated in the area of the same SSID an automatic change is made to the access point with the stronger signal.

5.4.5 TELEGRAMS

Under communication telegrams you can specify which data the tool should transfer to the external control. It is possible to transfer OK and NOK graphic data. In doing so whether each individual measurement value of the total measurement in the graphic evaluation should be included can be specified or, for example, whether it should only be every 3rd or 4th value (division factor) that should be transferred. What happens if the tool cannot transfer the data can also be determined. The tool can wait for an answer from the control so that the data can then be sent if there is an existing connection.

The screenshot shows the HST-Tool-Manager software interface. The title bar indicates 'HST-Tool-Manager Version: 2.0.4.0'. The main window has a blue header with icons for file operations and a 'tool no.: 18380018' label. Below the header is a 'tool: setup:' section with a back arrow. A tabbed menu includes 'general', 'management', 'signals', 'communication', 'graphics', 'system time', 'basic settings', and 'update'. The 'communication' tab is active, showing the 'telegrams' configuration. The 'send telegram' section has a dropdown set to 'TG1', an unchecked 'TG-Block-PR' checkbox, and a checked 'send ALL OK / NOK' checkbox. The 'graphics:' section contains a 'transmit data:' box with checked 'OK' and 'NOK' checkboxes, and an unchecked 'reverse' checkbox. Below this is a 'divisor:' field with the value '1'. The 'spool:' section has a checked 'record in spool' checkbox, 'trials:' set to '10', 'periode:' set to '1,00 [s]', an unchecked 'block tool until answer' checkbox, and a checked 'abort telegram' checkbox. The bottom status bar shows 'COM5: connected', the user 'administrator', and a language dropdown set to 'EN'.

34 Communication telegrams

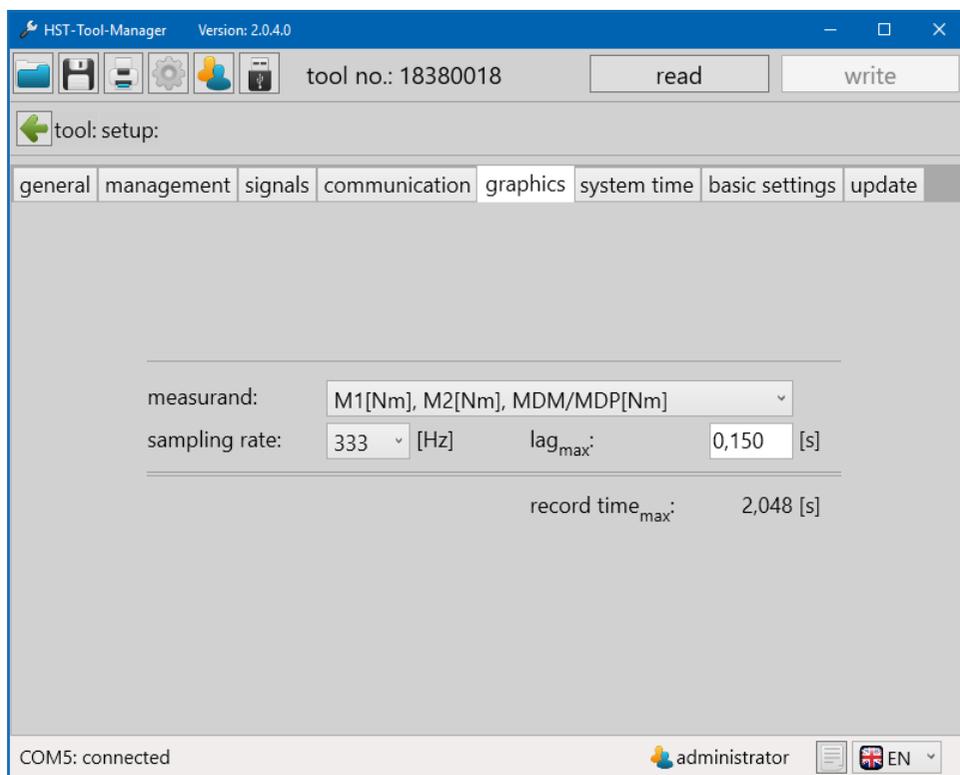


NOTE

The communication telegrams tab only opens if the configuration “Wi-Fi” has been activated in the basic settings tab as well as the “external control” release under “general”.

“send telegram”	Select the communication protocol TG1/TG2 “TG Block-PR” Security function. While the motor is turning no incoming telegrams from the tool will be answered. “send ALL OK /NOK” After the completed screw connection order an additional telegram about the overall result will be sent.
“graphics”	“transmit data” Refers to the sending of the graphic data. - <i>OK</i> : OK graphics are being sent. - <i>NOK</i> : NOK graphics are being sent. - <i>Reverse</i> : Graphics from the loosening program are being sent. “divisor” Determines the number of graphic values which should be transferred. <i>For example</i> : If a graphic contains 1000 values and the division factor is “2”, 500 values are transferred.
“spool”	“record in spool” activates/deactivates the repetition of results telegrams if these could not be sent due to transmission problems. “trials” Sets the number of repetitions, per telegram, in the event of an error. “periode” Determines the time between the repeated sending of the telegrams. “block tool until answer” Tool stops until the answer to a telegram sent is received.
“abort telegram”	If a screw connection order is cancelled by the user (user cancellation) a telegram is sent to control.

5.5 TAB "GRAPHICS"



35 Graphics

Over 150,000 curves can be stored in the tools. In this tab you can define the length, type and quality of the curve.

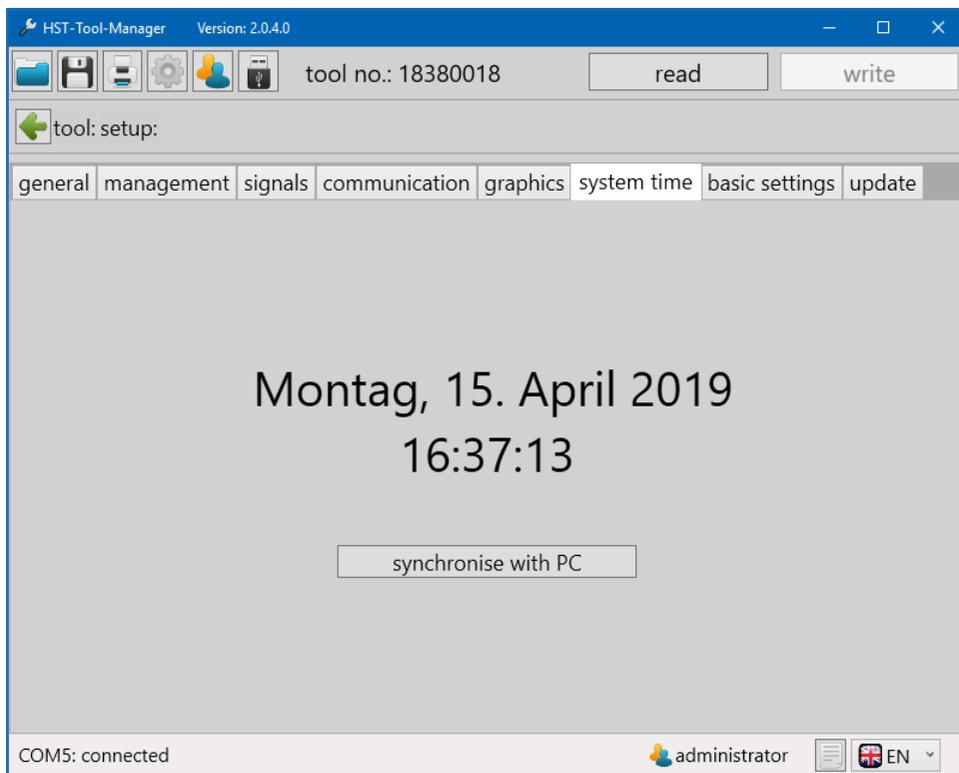
Depending on the number of parameters selected the maximum recording time changes. If the recording period is not long enough for the entire screw connection procedure the front part of the graphic will be cut off.

<p>“measurand”</p>	<p>Selection of the physical parameters of the curve display depending on the tool type.</p> <ul style="list-style-type: none"> - Torque, angle, current, voltage - Torque, angle, current - Torque, angle - Torque <p>Torque 1, torque 2, MDM/MDP¹ Torque 1, torque 2, angle 1, angle 2²</p>
<p>“sampling rate”</p>	<p>Determines the resolution of the graphics recording, 50 - 1000 Hertz</p> <p>High quality (sampling rate) = low recording time Low quality (sampling rate) = high recording time</p>
<p>“lag_{max}”</p>	<p>Input of the recording time after reaching the switching condition.</p>
<p>“record time_{max}”</p>	<p>Specifies the recording time which is possible as a result of the settings selected.</p>

¹ Is only available with the EC2 tool type and enables graphic recording of the redundant torque incl. the permissible tolerance (MDM/MDP).

² Is only available with the EC2 tool type and enables graphic presentation of the redundant torque and the redundant angle.

5.6 TAB “SYSTEM TIME”

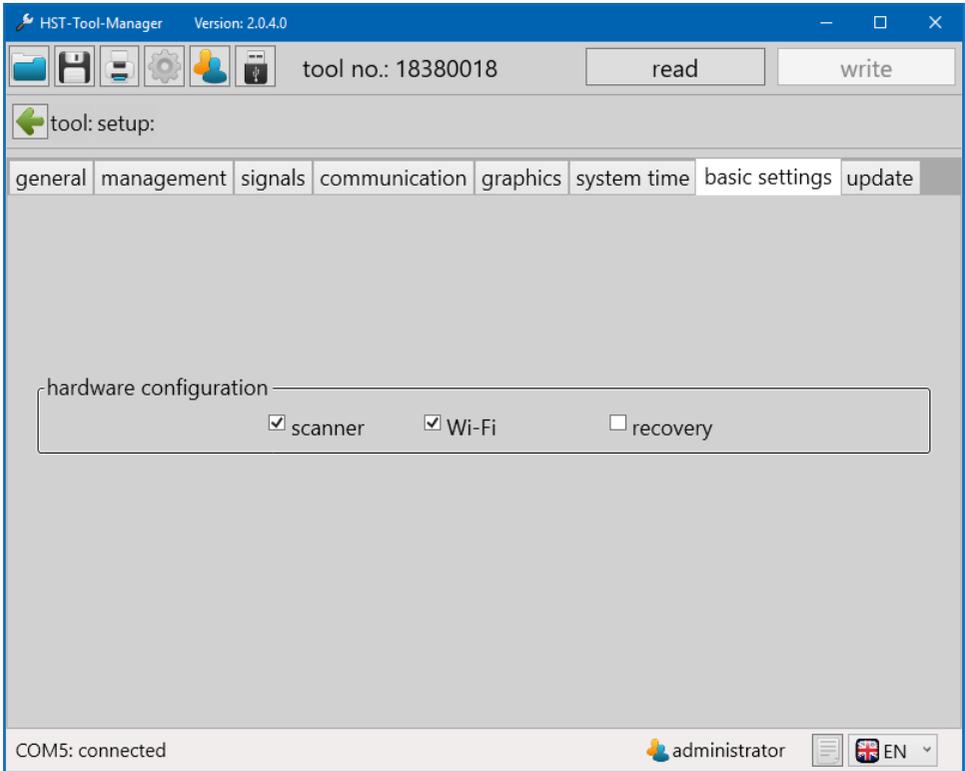


36 System time

In the system time tab the system time can be synchronised with the time of the computer connected. This function is required in order to correctly record the time stamp of the wrenching process.

If the system time and the time on the tool amount to a difference of more than 30 seconds a notification will appear during the read out of the tool.

5.7 TAB “BASIC SETTINGS”



37 Basic settings

Selection of the connected hardware options.

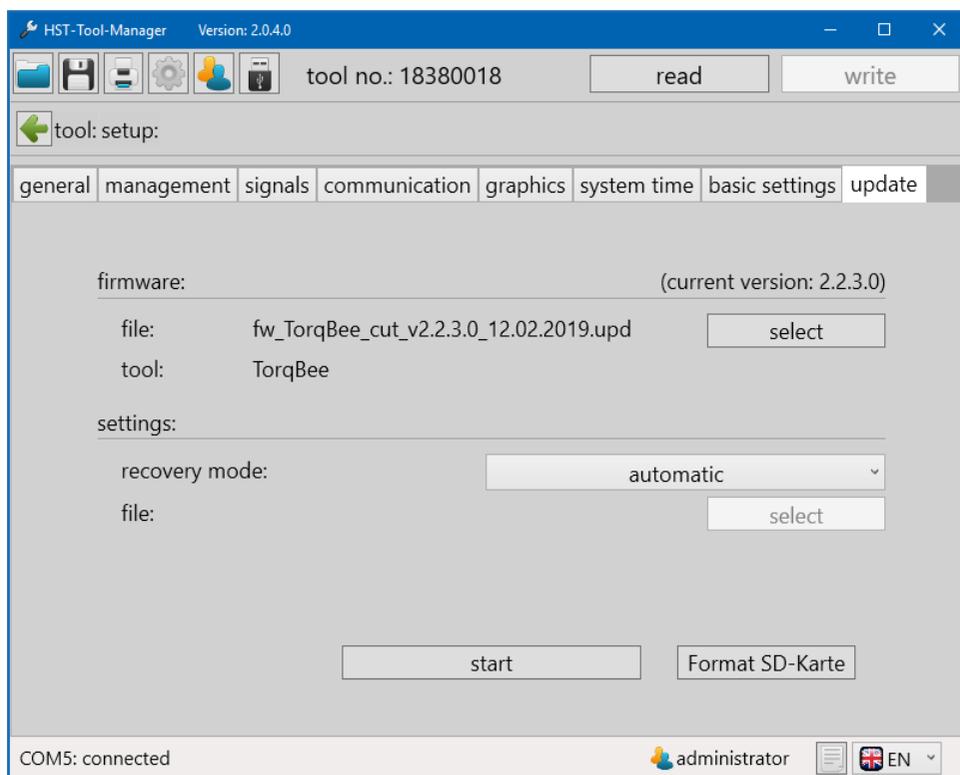
“hardware
configuration”

“scanner”
Activated / Deactivated

“Wi-Fi”
Wi-Fi Activated / Deactivated

“recovery”
Activated / Deactivated
The recovery function enables the continuation of a job/sequence after a battery change. This enables a battery change during an ongoing job/sequence without any loss of data.

5.8 TAB “UPDATE”



38 Update



NOTE

Before every update a data backup of the tool should be conducted manually using the “save” symbol on the top left.

The firmware of the tool can be updated with an “update”.

"firmware"	<p data-bbox="342 201 422 225">"select"</p> <p data-bbox="342 235 672 259">Select firmware file(.upd format).</p> <p data-bbox="342 300 402 324">"tool"</p> <p data-bbox="342 334 1040 389">Tool type of the firmware file is displayed. The type from the file must be identical to the current one, otherwise an update is not possible.</p>
"settings"	<p data-bbox="342 414 512 438">"recovery mode"</p> <p data-bbox="342 448 1040 565">With "automatic" the data read out from the tool before the update is entered again after the update (not from the backup file). With "from backup file" (file must be selected) the data from the selected file is entered after the update.</p>
"start"	<p data-bbox="342 592 629 617">Starts the update procedure.</p>
"Format SD-Karte"	<p data-bbox="342 641 1040 696">Deletes all programs and screw connection results from the internal memory.</p>



NOTE

It is recommended that you select the "automatic" recovery mode. In doing so all previously read out program and settings are reloaded onto the tool again after the update.

6 TOOL PROGRAMMING

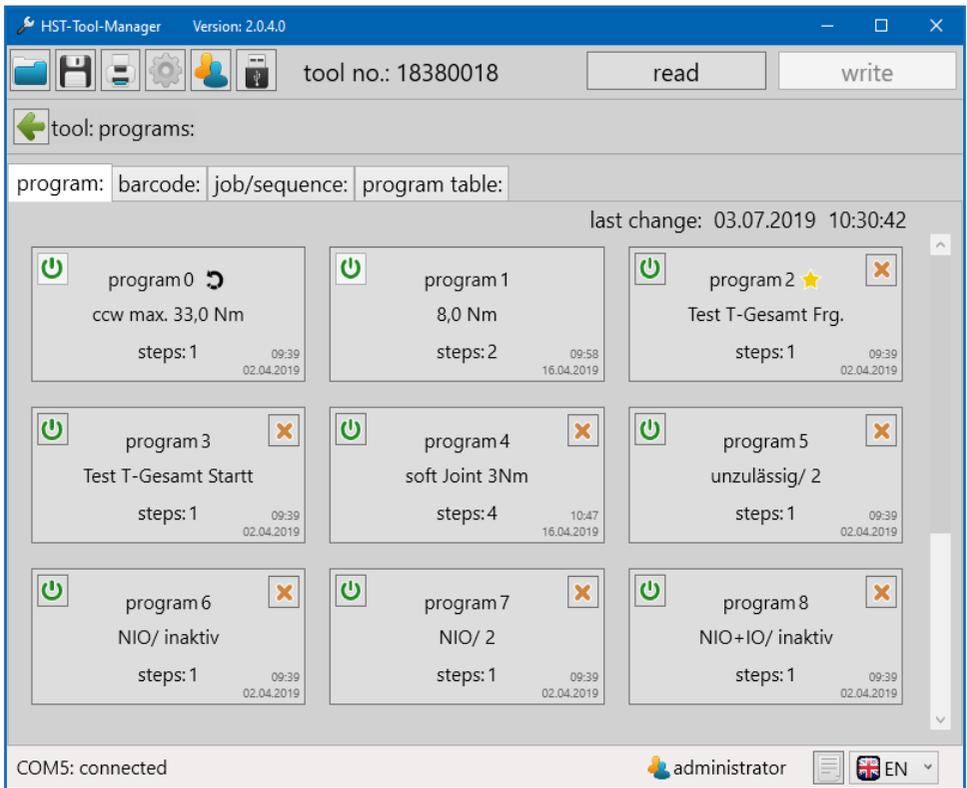
The programs stored on the tool are reached using the “programming” button on the homepage.



The current program names and numbers are listed in the program overview. In addition the following information for each program is displayed:

- Default program
- loosening program
- Program with correction factor
- Number of steps
- Time stamp
- Active / Inactive

The time stamp of the last successful change to the programs is also part of the overview. In addition access to the barcodes, processes and program table which can be selected above by clicking on the corresponding tab, is located here.



39 Programs

6.1 TAB “PROGRAM”

There are a possible 100 programs with 6 steps each.

Program 0	loosen, can not be deleted
Program 1	Programmable, can not be deleted
Program 90 - 99	MCT-Programs of the tool (preconfigured)

88 programs for individual programming are available.

Program:	With up to six steps
Step:	Per step with up to 5 possible switching conditions and up to 5 possible evaluation criteria.

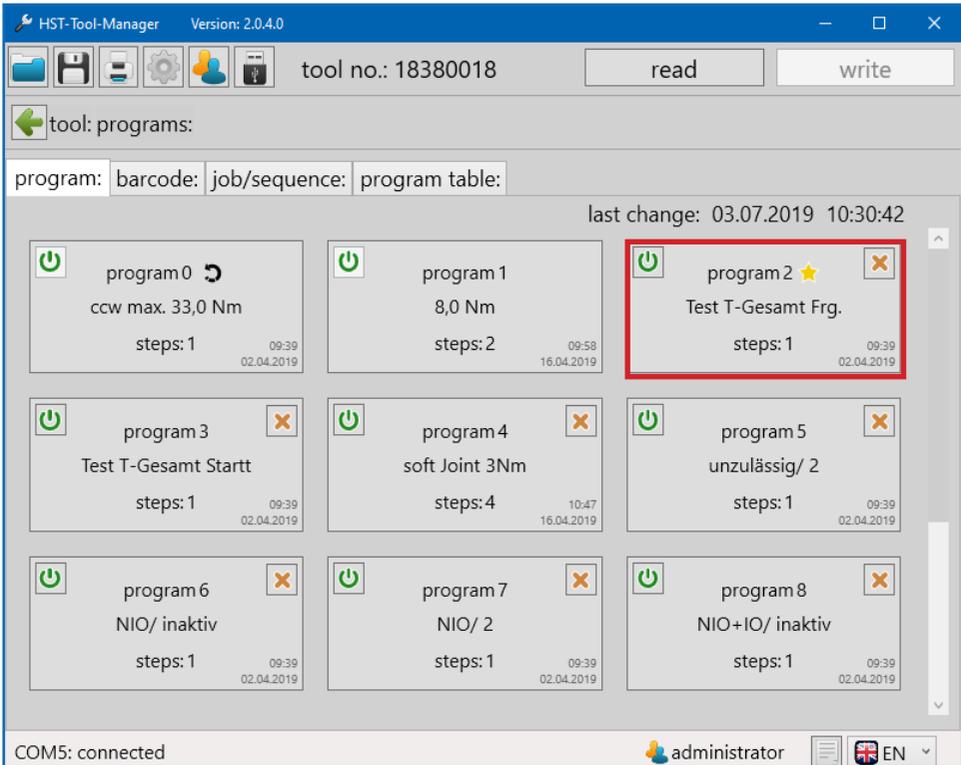
6.1.1 ACTIVATE/DEACTIVATE PROGRAM

Up to 100 programs are stored in the tool. For a better overview programs can be activated or deactivated. Deactivated programs will be ignored by the tool.

Activate program:  By “clicking” the button the “power” symbol will turn green.

Deactivate program:  By “clicking” the button the “power” symbol and the program will be greyed out.

The active program will have a yellow star (default program) in the program overview. The default program is then always executed when no explicit program specification is made via barcode or external control.



The screenshot displays the HST-Tool-Manager interface (Version: 2.0.4.0) with the following details:

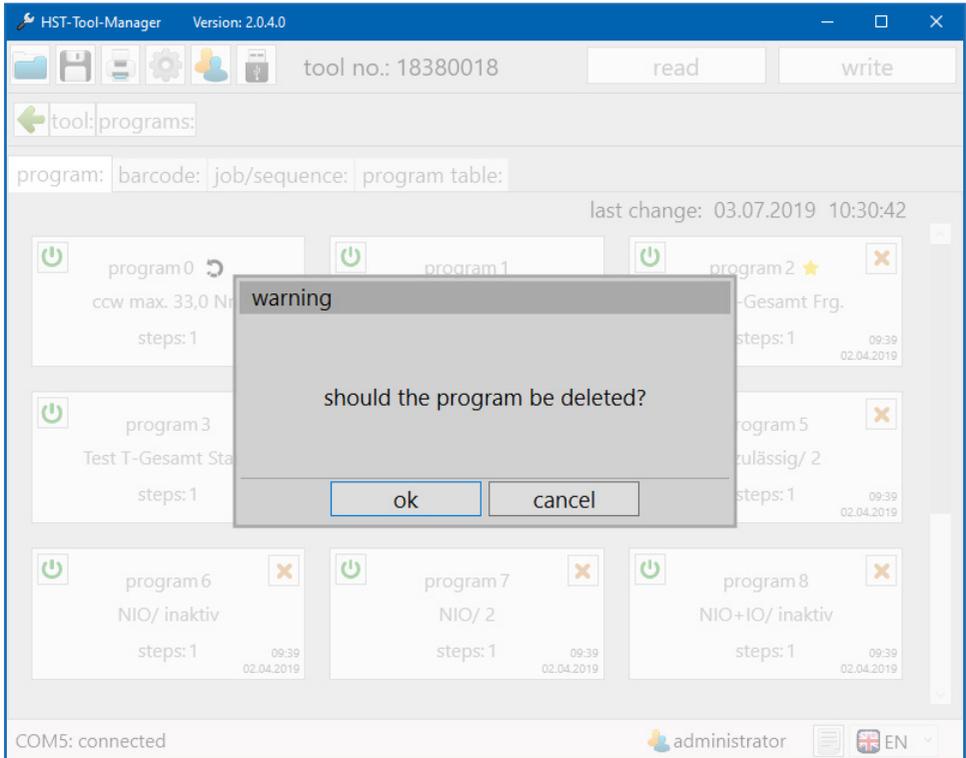
- Tool ID: 18380018
- Buttons: read, write
- Navigation: tool: programs: (back arrow)
- Search filters: program: | barcode: | job/sequence: | program table:
- Last change: 03.07.2019 10:30:42
- Program Grid (9 cards):
 - program 0: cw max. 33,0 Nm, steps: 1, last change: 02.04.2019 09:39
 - program 1: 8,0 Nm, steps: 2, last change: 16.04.2019 09:58
 - program 2 (Active):** Test T-Gesamt Frg., steps: 1, last change: 02.04.2019 09:39 (highlighted with a red box and a yellow star)
 - program 3: Test T-Gesamt Start, steps: 1, last change: 02.04.2019 09:39
 - program 4: soft Joint 3Nm, steps: 4, last change: 16.04.2019 10:47
 - program 5: unzulässig/ 2, steps: 1, last change: 02.04.2019 09:39
 - program 6: NIO/ inaktiv, steps: 1, last change: 02.04.2019 09:39
 - program 7: NIO/ 2, steps: 1, last change: 02.04.2019 09:39
 - program 8: NIO+IO/ inaktiv, steps: 1, last change: 02.04.2019 09:39
- Status: COM5: connected
- User: administrator
- Language: EN

40 Programs

6.1.2 CREATE/DELETE PROGRAM

A new program can be created with  one click.

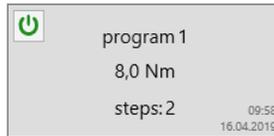
A program can be deleted on the  with one click.



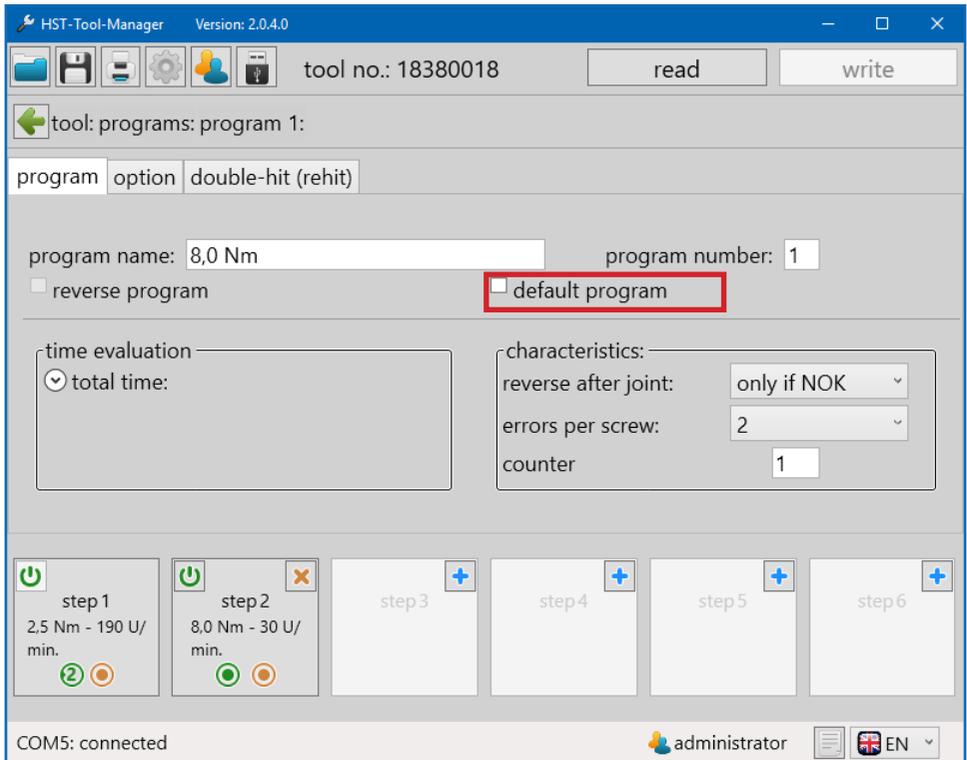
41 Warning delete program

6.1.3 SET PROGRAM AS DEFAULT PROGRAM

A program can be opened with a click on the program button.



A program can be identified as the “default program”. This is always executed if no other program is specifically activated via barcode or an external control. This takes place in the desired program with the “default program” or “default process” option.



42 Default program

6.2 CONFIGURE PROGRAM

To configure a program the corresponding program button must be clicked.

6.2.1 Program

The screenshot shows the HST-Tool-Manager software interface. The title bar indicates the version is 2.0.4.0. The main window displays the configuration for a program. At the top, there are icons for file operations and a toolbar with 'read' and 'write' buttons. The tool number is 18380018. Below this, the program is identified as 'program 1'. The configuration options include:

- program name: 8,0 Nm
- program number: 1
- reverse program
- default program
- time evaluation: total time (dropdown menu)
- characteristics: reverse after joint (dropdown menu: only if NOK)
- errors per screw: 2 (dropdown menu)
- counter: 1

At the bottom, there are six step buttons: step 1 (2,5 Nm - 190 U/min), step 2 (8,0 Nm - 30 U/min), step 3, step 4, step 5, and step 6. The status bar shows 'COM5: connected', the user 'administrator', and the language 'EN'.

Settings for the program which apply across steps.

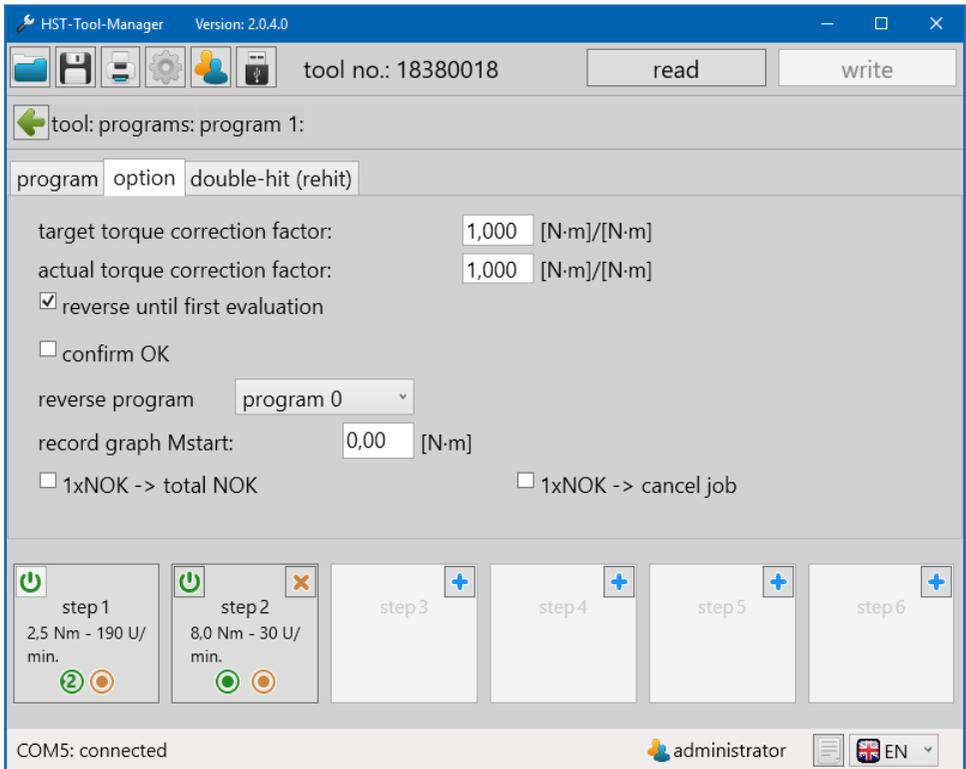
“program name”	Empty text field for the description of the program.
“program number”	Input field for the program number.
“reverse program”	Defines the program as a loosening program.
“default program”	Defines the program as the default program.
“time evaluation”	<ul style="list-style-type: none">- “<i>T total</i>”: Input of the maximum time for this program for the entire screw connection order.- “<i>start at</i>”: Criteria for the start of the time measurement.
“characteristics”	<p>Determines in which cases the last activated screw connection may be loosened. This characteristics is also dependent upon the function “NOK acknowledgement” under the tab functions (see Chapter 5.1.3 Page 40). Prohibited: Screw connection may not be loosened.</p> <ul style="list-style-type: none">- <i>only if NOK</i>: Loosening is only possible in the event of NOK.- <i>if NOK or OK</i>: It can be loosened after an OK, or NOK screw connection. <p>“errors per screw”</p> <p>Input how often a NOK screw connection may be repeated.</p> <ul style="list-style-type: none">- <i>disabled</i>: NOK screw connection can be corrected without limitation.- <i>0...9</i>: NOK screw connection may be repeated as often as is specified. <p>“counter”</p> <p>Number of screw connections which should take place with one enabling. In manual mode the screw count number function is inactive.</p>



NOTE

The time evaluation is made for the entire screw connection order (all enabled screws). After expiry of the specified time the work order is interrupted, regardless of whether all the screw connections have been completed.

6.2.2 Option



44 Tab Option

“target torque correction factor”

The correction factor is needed primarily in the event of extremely difficult screw connections. In order to reduce exceeding the desired torque value the stop point can be adjusted. A value lower than 1 leads to an earlier stop of the tool.

<p>“actual torque correction factor”</p>	<p>This correction factor is used in order to compensate for friction losses of different drives (flat drives), or extensions. If the torque values of the measurement system and the tool are different these can be adjusted using the correction factor. To this end the torque value of the tool can be divided by the measured torque value of the reference system. The result is then entered as the correction factor.</p> $(\text{Nm tool})/(\text{Nm reference system}) = \text{factor}$ <p>If you set a current torque correction factor this program will be identified directly in the program overview with a small exclamation point </p>
<p>“reverse until first evaluation”</p>	<p>Loosen is permissible up to the first evaluation in the assembly direction.</p> <p><i>For Example:</i> In an already pre-installed part all the screws need to be loosened so that an additional component can be inserted. In the next step all screws are retightened and evaluated.</p>
<p>“confirm OK”</p>	<p>The OK screw connection must then be confirmed in the prescribed time using the yellow key in the display. After expiry of the time and without a confirmation the screw connection is automatically assessed as NOK and documented.</p>
<p>“reverse program”</p>	<p>Assignment of the loosening program for this screw program.</p>
<p>“record graph M_{Start}”</p>	<p>Start torque for the graphic recording. The data points before M_{Start} will not be recorded.</p>
<p>“1xNOK ⇔ total NOK”</p>	<p>If a single screw connection of the screw job is evaluated as NOK, the whole job will be evaluated as NOK at the end.</p>
<p>“1xNOK ⇨ cancel job”</p>	<p>If a screw connection of the screw job is evaluated as NOK the job is immediately interrupted and evaluated as NOK.</p>

HST-Tool-Manager Version: 2.0.4.0

tool no.: 18380018 read write

← tool: programs:

program: barcode: job/sequence: program table:

last change: 21.08.2019 10:35:26

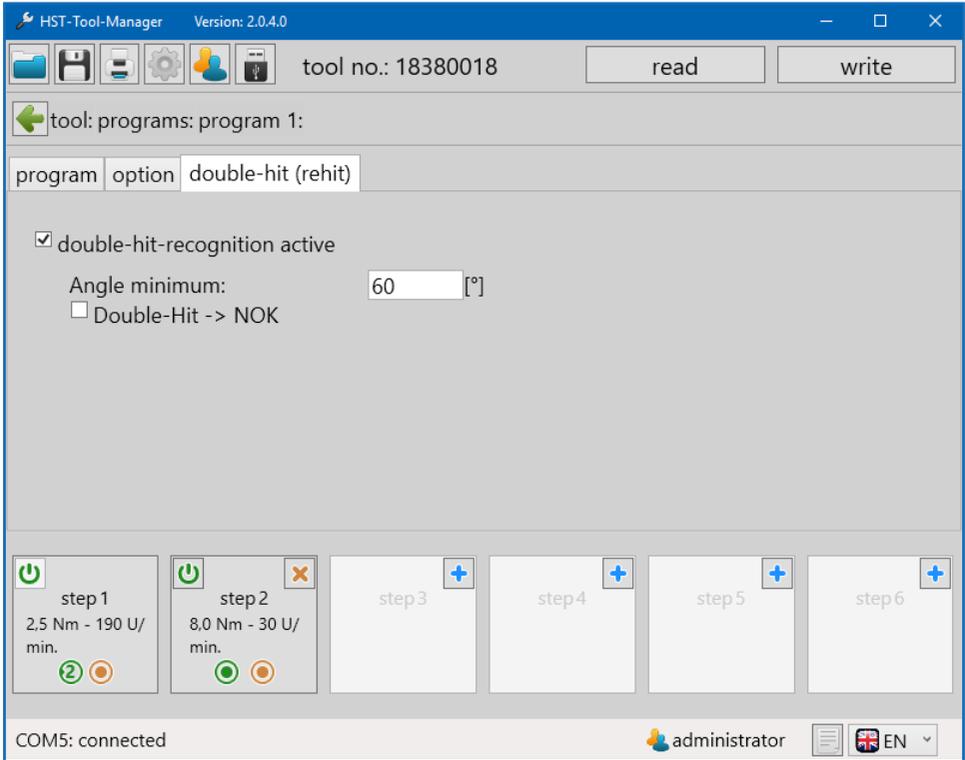
program 0 ccw max. 33,0 Nm steps: 1 <small>09:39 02.04.2019</small>	program 1 8,0 Nm steps: 2 <small>10:35 21.08.2019</small>	program 2 ★ Test T-Gesamt Frg. steps: 1 <small>09:39 02.04.2019</small>
program 3 Test T-Gesamt Startt steps: 1 <small>09:39 02.04.2019</small>	program 4 soft Joint 3Nm steps: 4 <small>10:47 16.04.2019</small>	program 5 unzulässig/ 2 steps: 1 <small>09:39 02.04.2019</small>
program 6 NIO/ inaktiv steps: 1 <small>09:39 02.04.2019</small>	program 7 NIO/ 2 steps: 1 <small>09:39 02.04.2019</small>	program 8 NIO+IO/ inaktiv steps: 1 <small>09:39 02.04.2019</small>

COM5: connected administrator EN

45 Correction factor active

6.2.3 Double-Hit (Rehit)

The function double-hit (rehit) serves to identify already tighten screw connections. If the target torque within the set angle value is reached this screw connection is assessed as a double-hit (rehit). The screw connection process ends. If the “Double-Hit ⇔ NOK” function is also activated the screw connection process is ended and assessed as NOK.



46 Tab Double-Hit (Rehit)

“double-hit-
recognition active”

“Angle minimum”

Determines the maximum angle up to which the achievement of the target torque will be identified as a double-hit (rehit).

“Double-Hit ⇔ NOK”

Double-Hit (Rehit) is assessed as NOK.

6.3 THE STEPS

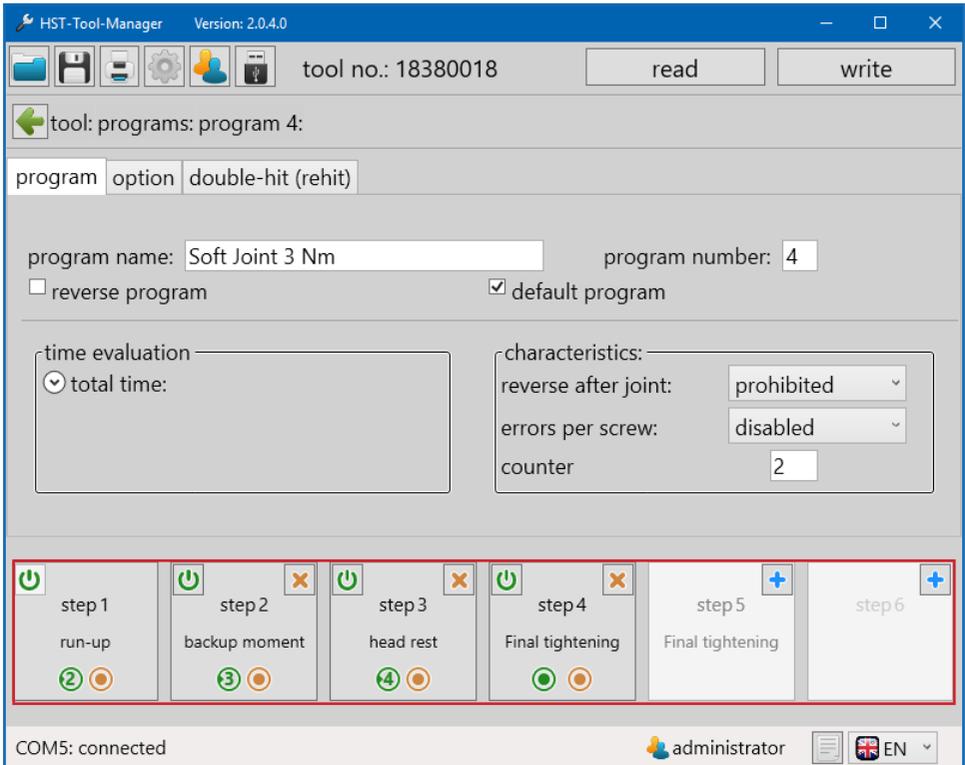
A program can consist of up to 6 steps.

Each step can be occupied with different strategies:

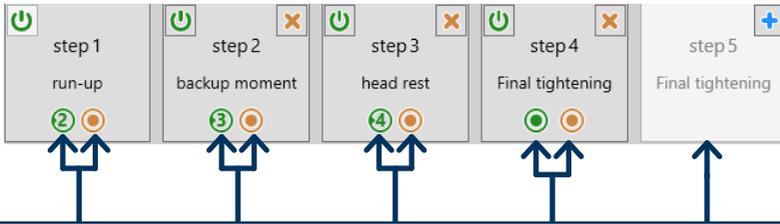
- Torque strategy
- Angle strategy
- Yield point screw connection
- Torque screw connection with locking torque, or friction coefficient calculation

For all strategies the corresponding torque - angle or time monitoring can be generated:

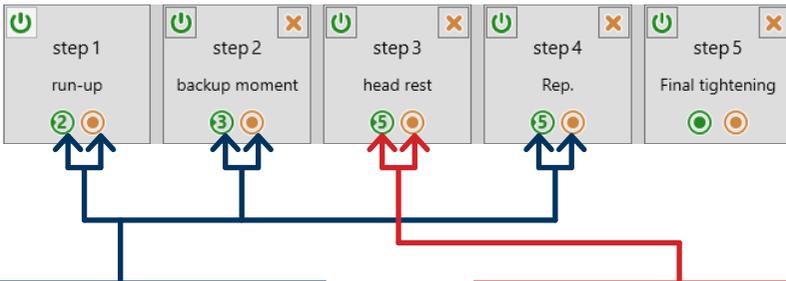
- Torque controlled with rotation angle monitoring
- Rotation angle controlled with torque monitoring



47 Steps



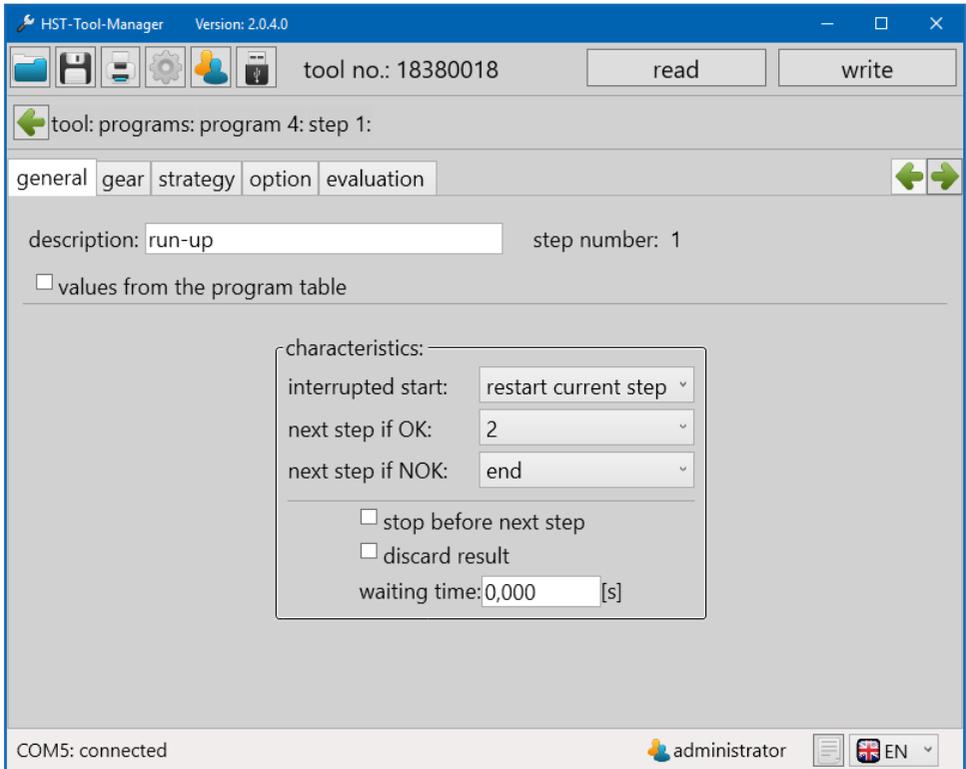
When the step is successfully completed the tool moves into the next step. If the step is not successfully complete the screw connection is assessed as NOK. In addition a new step may be added by clicking on .



When the step is successfully completed the tool moves into the next step. If the step is not successfully complete the screw connection is assessed as NOK.

When the step is successfully completed the tool switches into the final tightening. If the step is not successfully completed an intermediate step is activated in order to, for example, slightly loosen the screw and then retighten it.

6.4 Tab “general”



48 Tab general

“description”	Name of the step (free input), max. 20 characters.
“step number”	Number of the current displayed program step.
“values from the program table”	The shut-off parameters in the program step will be replaced by the values entered in the program table. This function must be activated by the manufacturer.

“characteristics”

“interrupted start”

Behaviour when activating the start key prior to reaching the switch condition.

- *Prohibited*: if the start key is released this leads to a NOK assessment.
- *Restart current step*: if the start key is released the current step will be restarted upon repeated activation of the start key.
- *Back to step 1*: if the start key is released the first step will be restarted upon repeated activation of the start key.
- *Evaluate*: if the start key is released this leads to an evaluation of the step.

“next step if OK”

Determines the next step after an OK assessment.

“next step if NOK”

Determines the next step after a NOK assessment.

“stop before next step”

Pause the program after a completed step. To continue the program the start key must be reactivated.



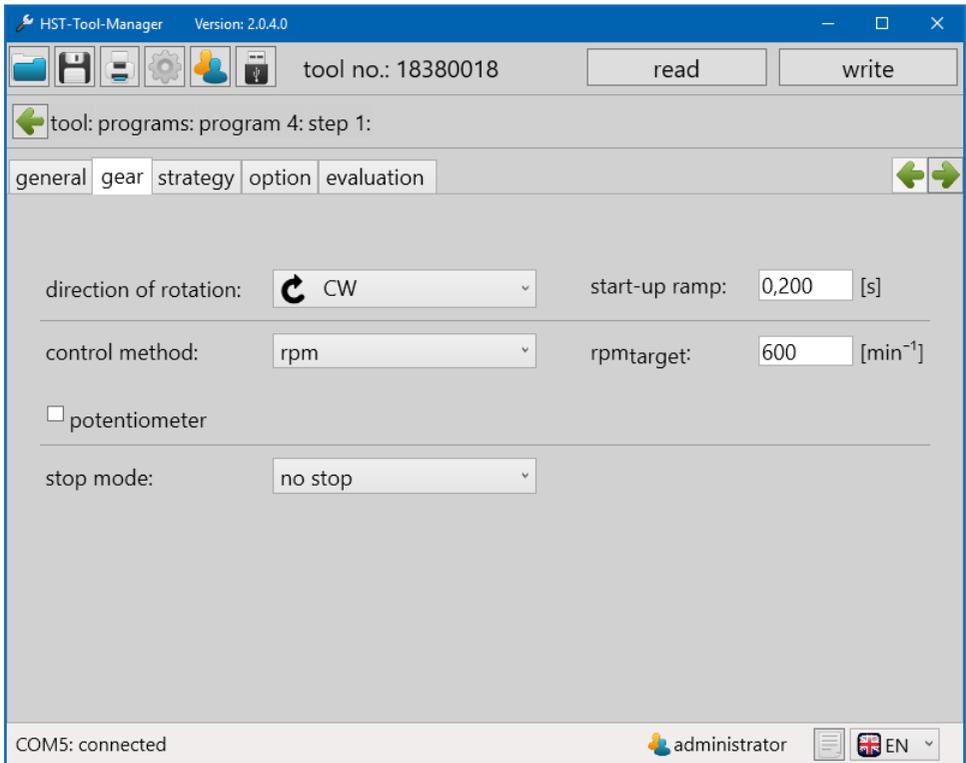
“discard result”

Results for the step will not be stored.

“waiting time”

Wait time before switching into the next step; the start key may not be released.

6.5 Tab “gear”



49 Tab gear

“direction of rotation”	Rotation direction of the output.
“start-up ramp”	Time specification within which the target number of revolutions for this step should be reached.
“control method”	<ul style="list-style-type: none">- <i>rpm</i>: Number of revolutions is regulated.- <i>Torque - rpm</i>: Number of revolutions per minute will be regulated depending on the applied torque.- <i>Angle - rpm</i>: Number of revolutions per minute will be regulated depending on the rotation angle achieved.- <i>Set - rpm</i>: Number of revolutions will not be readjusted (open loop).

"rpm _{target} "	Specification of the number of revolutions per minute for the respective control type.
"rpm _{min} "	Specification for the minimum number of revolutions per minute for the torque-rpm, or angle-rpm control methods.
"shiftdown point"	Percent value of target torque, or target angle. Starting at this value the number of revolutions per minute will be continuously decreased, until reaching the set minimum number of revolutions per minute.
"potentiometer"	Activates the regulation of the speed by the position of the trigger switch.
"stop mode"	<p>Changes the shut off behaviour in the respective screw joint.</p> <ul style="list-style-type: none"> - <i>no stop</i>: Motor will not be actively stopped. - <i>Soft-stop</i>: Torque is slowly reduced after stopping the motor. <ul style="list-style-type: none"> - <i>Stop-ramp</i>: Time in which the torque is decreased. - <i>Stop-Moment</i>: Percentage share of the end torque for the start of the stop ramp. - <i>Stop</i>: Default braking - <i>ECO Stop</i>: Stop with recuperation. Part of the kinetic energy is directed to the battery when stopping. - <i>Fast Stop 50 %</i>: Braking with reversal of current (low energy consumption). - <i>Fast Stop 75 %</i>: Braking with reversal of current (medium energy consumption). - <i>Fast Stop 100 %</i>: Braking with reversal of current (high energy consumption). - <i>Stop & release</i>: Braking and turn 2° in opposite direction. (The drive is released for comfortable removal of the tool.)

6.6 Tab “strategy”

HST-Tool-Manager Version: 2.0.4.0
tool no.: 18380018
read write
tool: programs: program 4: step 1:
general gear strategy option evaluation
-shifting conditions:
torque: Mtarget 1,00 [N-m], Mstart 0,50 [N-m], Mlimit* 0,00 [N-m]
angle: []
current: []
gradient: []
time: []
evaluation:
torque: 0,93 ≤ Mactual ≤ 1,07 [N-m] %
angle: 25 ≤ α actual ≤ 500 [°]
current: []
COM5: connected administrator EN

torque [N-m]
current [A]
M_{max} 1,07
M_{target} 1,00
M_{min} 0,93
α_{min} 25 α_{max} 500
angle [°]
time [s]

50 Tab Strategy



DANGER

If you only set an angle or time as a target value you must program a torque limit for emergency stop in order to protect workers and the machine from too high a transmission of power.

“shifting conditions”

The tool will observe all activated shifting conditions and ends the current step upon reaching the target specification(s) or limits. When the set value is reached the step is complete.

“torque”

- M_{Target} : The target torque to be reached.
- M_{Start} : Beginning of the angle counting.
- M_{Limit} : Upper limit of the torque (only visible if no M_{target} and no torque evaluation are activated).
- M_{Limit}^- : Lower limit of the torque, defines the torque value which you may no longer fall below upon reaching M_{Start} .

“angle”

- α_{Target} : Target value of the angle.
- α_{Limit} : Upper limit of the angle (only visible if no W_{target} and no angle evaluation are activated).

“current”

- I_{Target} : Target value of the current.
- I_{Limit} : Upper limit of the current (only visible if no I_{target} and no current evaluation are activated).

“gradient”

- G_{Target} : Corresponds to a percentage value of the maximum torque rate of increase. If the torque is increasing more slowly than before the tool will shut off.

“time”

- T_{Target} : Target value for time.
- T_{Limit} : Maximum duration (only visible if no T_{Target} and no time evaluation are activated).



“& symbol”

Activates the option of combining multiple target values. (The target value reached first leads to a shift into the next step).

For example, in order to correctly record incorrect assemblies, “idle screw connections” or overruns there is the “evaluation”. Here, corresponding limits can be programmed for all parameters.

HST-Tool-Manager Version: 2.0.4.0

tool no.: 18380018

read write

tool: programs: program 4: step 1:

general gear strategy option evaluation

shifting conditions:

- torque:
 - Mtarget 1,00 [N-m]
 - Mstart 0,50 [N-m]
 - Mlimit* 0,00 [N-m]
- angle:
- current:
- gradient:
- time:

evaluation:

- torque:
 - $0,93 \leq M_{actual} \leq 1,07$ [N-m] %
- angle:
 - $25 \leq \alpha_{actual} \leq 500$ [°]
- current:

COM5: connected administrator EN

torque [N-m]
current [A]

M_{max} 1,07
M_{target} 1,00
M_{min} 0,93

α_{min} 25 α_{max} 500 angle [°]

time [s]

51 Tab Strategy

“evaluation”

Criteria for the evaluation of the actual values achieved for the current step.

“torque”

Setting the lower and upper limit of the torque. If the torque lies outside these limits the step is assessed with NOK. Using the % sign the limits can be set as percent values of the target value (target value must be activated). Reaching the upper limit automatically leads to advancement and NOK evaluation.

“angle”

Setting the lower and upper limit of the angle. If the angle lies outside these limits the step is assessed with NOK. Using the % sign the limits can be set as percent values of the target value (target value must be activated). Reaching the upper limit automatically leads to advancement and NOK evaluation.

“current”

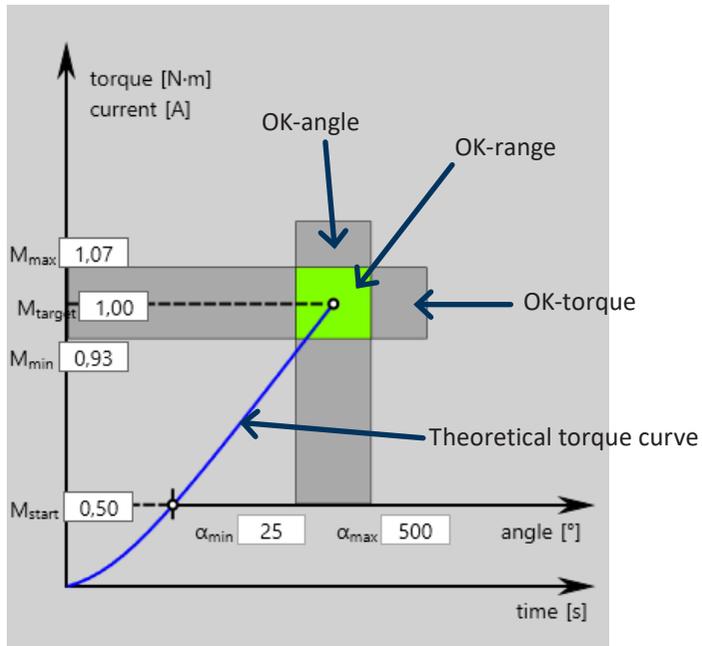
Setting the lower and upper limit of the current. If the current lies outside these limits the step is assessed with NOK. Using the % sign the limits can be set as percent values of the target value (target value must be activated). Reaching the upper limit automatically leads to advancement and NOK evaluation.

“gradient”

Setting the lower and upper limit of the gradient. If the gradient lies outside these limits the step is assessed with NOK.

“time”

Setting the lower and upper limit of the length of time. If the length of time lies outside these limits the step is assessed with NOK. Reaching the upper limit automatically leads to advancement and NOK evaluation.



52 The strategy as a graphic depiction

All limit values can also be changed directly in the graphic.

6.7 Tab “option”

HST-Tool-Manager Version: 2.0.4.0

tool no.: 18380018 read write

tool: programs: program 4: step 1:

general gear strategy **option** evaluation

correction factor angle: 1,000 [°]/[°] correction angle: 0,0 [°]

current rejection: 0,000 [s]

MDM monitoring

MTP: 0,00 [N·m]

±MDP: 0,00 [N·m]

detect securing/prevaling torque

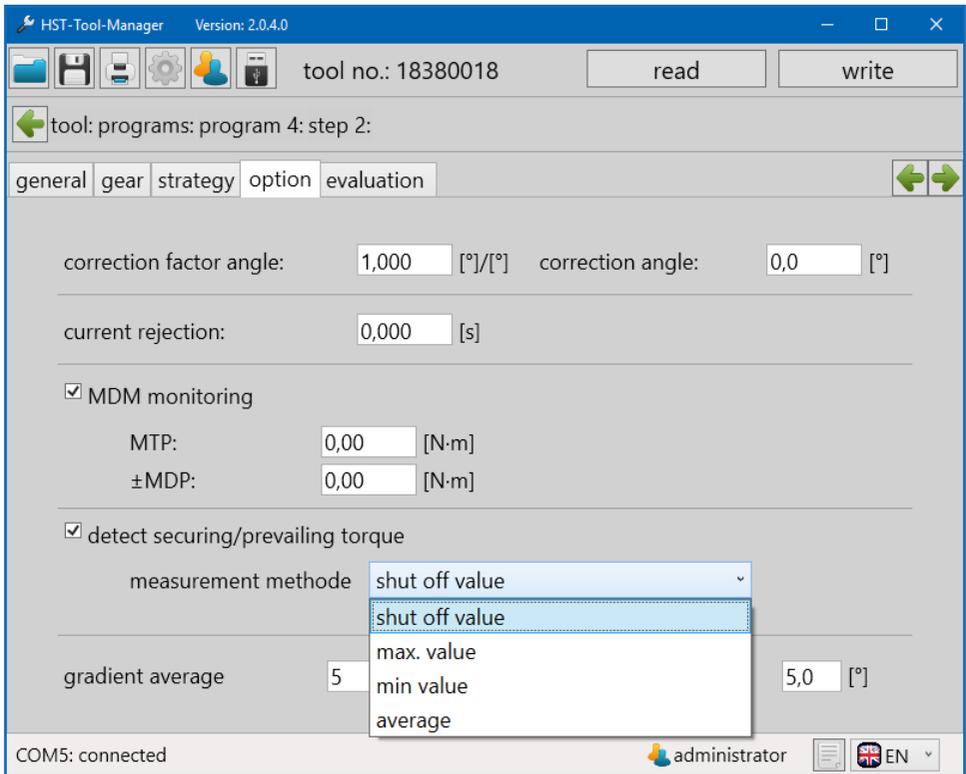
gradient average 0 [values] chord angle 2,0 [°]

COM5: connected administrator EN

53 Tab Option

“correction factor angle”	Factor for the correction of systematic deviations of the actual angle measures in the tool from the reference measurement system (measuring bench) (default value 1,000).
“correction angle”	Correction value for the target angle of the tool (default value 0.0°).
“current rejection”	The measured current will not be evaluated at the beginning of the step for the time set (elimination of the starting current).
“MDI-monitoring”	In this control method the current is measured and evaluated as a redundancy to the torque. If this lies outside the defined limits the process is interrupted and assessed as NOK.

“MDM-monitoring”	For tools in which two independent torque sensors are installed (EC2 design) the measurement of the redundancy sensors is used as the control value. If this lies outside the defined limits the process is interrupted and assessed as NOK.
“MTP”	Start torque value from which the redundancy measurement begins.
“±MDP”	Permissible deviation of the redundancy value. (Tolerance)



54 Determine locking torque

NOTE



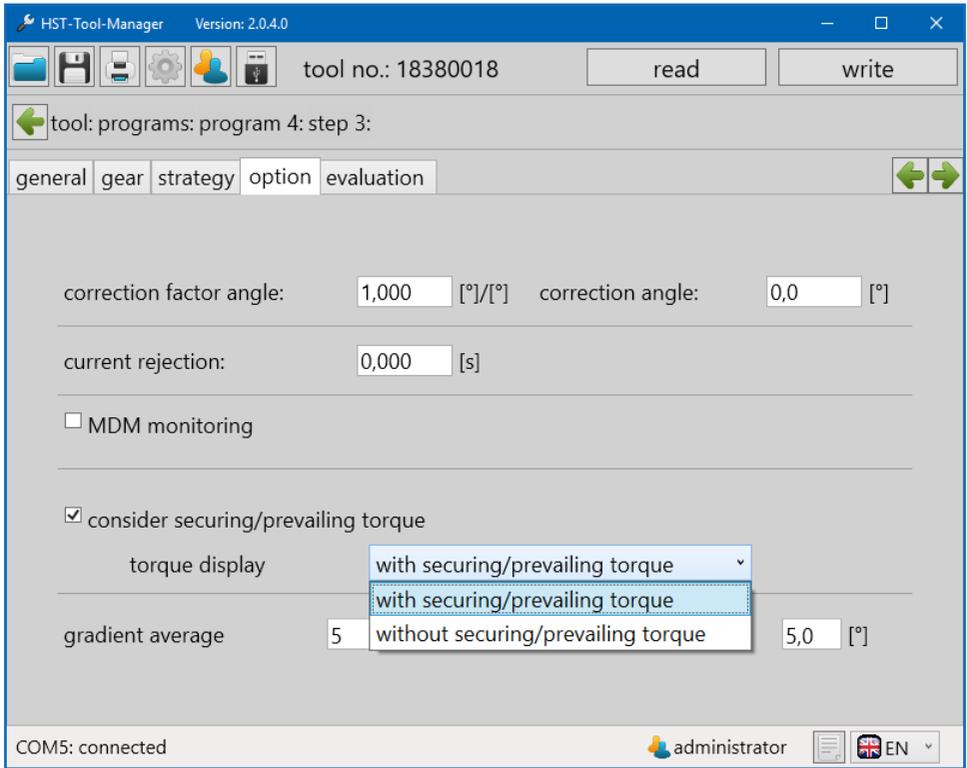
The locking torque can be determined in one step and used in a subsequent step. The locking torque can be determined in the pre-tightening, e.g. in step 2, and then taken into consideration in step 3 during end torque. In step 1 it is only possible to determine the locking torque.

“detect securing/pre-
vailing torque” Activates the determination of the locking torque.

“measurement method”

Selection of the method to determine the locking torque.

- *Switch-off value*: The last determined value of the step will be saved as the locking torque.
 - *Maximum value*: The maximum value of the step will be saved as the locking torque.
 - *Minimum value*: The minimum value of the step will be saved as the locking torque.
 - *Average*: The average of the step will be saved as the locking torque.
-



55 Use locking torque

“consider securing/
prevailing torque”

The saved locking torque will totalled with the torque target value (friction coefficient). (Is only available in the following step)

“torque display”

- *with securing/prevaling torque*: The display shows current torque reached.
- *without securing/prevaling torque*: The display shows current torque reached minus the locking torque.

“gradient average”

Number of values which are used for the average filter of the gradient.

“chord angle”

Determines across how many angle degrees the gradient will be formed.

6.8 Tab “evaluation”

HST-Tool-Manager Version: 2.0.4.0

tool no.: 18380018 read write

← tool: programs: program 4: step 3:

general | gear | strategy | option | **evaluation** ← →

element:	active:	α 1[°]:	α 2[°]:	M 1[N·m]:	M 2[N·m]:	To[%]:	type:
curve 1	<input type="checkbox"/>	220	180	2,50	1,50	20,00	≡ ▾
curve 2	<input type="checkbox"/>	220	180	2,50	1,50	20,00	≡ ▾
b-angle upper	<input type="checkbox"/>	100	50	2,50			
b-angle lower	<input type="checkbox"/>	50	0	1,50			

sampling rate: standard ▾ [Hz]

COM5: connected administrator EN ▾

56 Tab Evaluation

„curve 1
curve 2”

A curve consists of a base line which is defined across two points (torque and angle). The permissible deviation from the base line is specified using the tolerance. An OK assessment only takes place if the torque process lies within the defined limits. It is important to ensure that curves exhibit a defined direction which is identified by an arrow.

- *Active*: Checkboxes in order to activate/deactivate the windows and curves.
- $\alpha 1[^\circ]$: First point of the element on the angle axis.
- $\alpha 2[^\circ]$: Second point of the element on the angle axis.
- $M 1[Nm]$: First point of the element on the torque axis.
- $M 2[Nm]$: Second point of the element on the torque axis.
- $To[\%]$: The tolerance determines the permissible deviation from the base line of the curve.
- *Type*: Specifies whether the evaluation is made horizontally or vertically. The orientation results from the torque curve.
(Steep curve  , flat curve )

“b-angle upper
b-angle lower”

Limits the area which the screw curve may pass through. The uniqueness of this element is that the angle counting refers to the switch-off point. The switch-off point, in this sense, corresponds to the 0° angle.

- *Active*: Checkboxes in order to activate/deactivate the angle monitoring.
- $\alpha 1[^\circ]$: First point of the element on the angle axis.
- $\alpha 2[^\circ]$: Second point of the element on the angle axis.
- $M 1[Nm]$: Defines the torque that the screw curve may not exceed or fall below.

“sampling rate”

Determines the resolution of the graphics recording.

High quality (sampling rate) = low recording time

Low quality (sampling rate) = high recording time

With the “default” selection the setting from Chapter 5.5 Tab “Graphics” from page 58 is assumed.

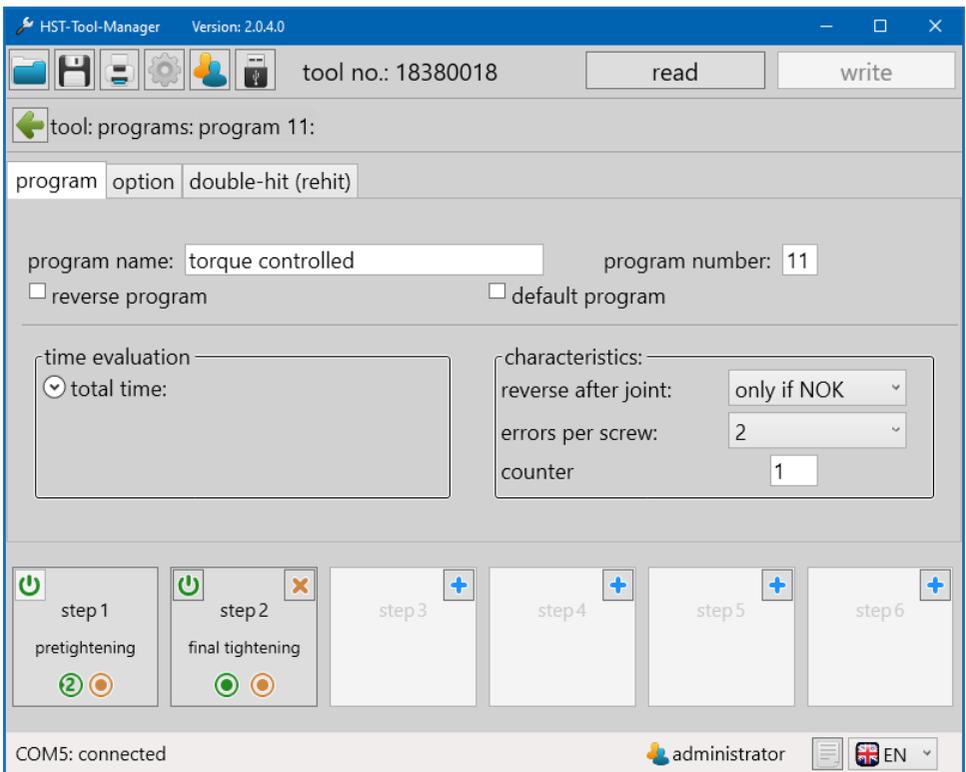
7 PROGRAM EXAMPLES

In this chapter different examples for the creation of screw programs are described. Please note that the examples are primarily intended to inform you of the numerous options for the tool and its use. It is, however, not permitted to determine which procedure is suitable for your own screw connection and how the parameters of the screw program are determined.

7.1 STRATEGY TORQUE CONTROLLED/ROTATION ANGLE MONITORED

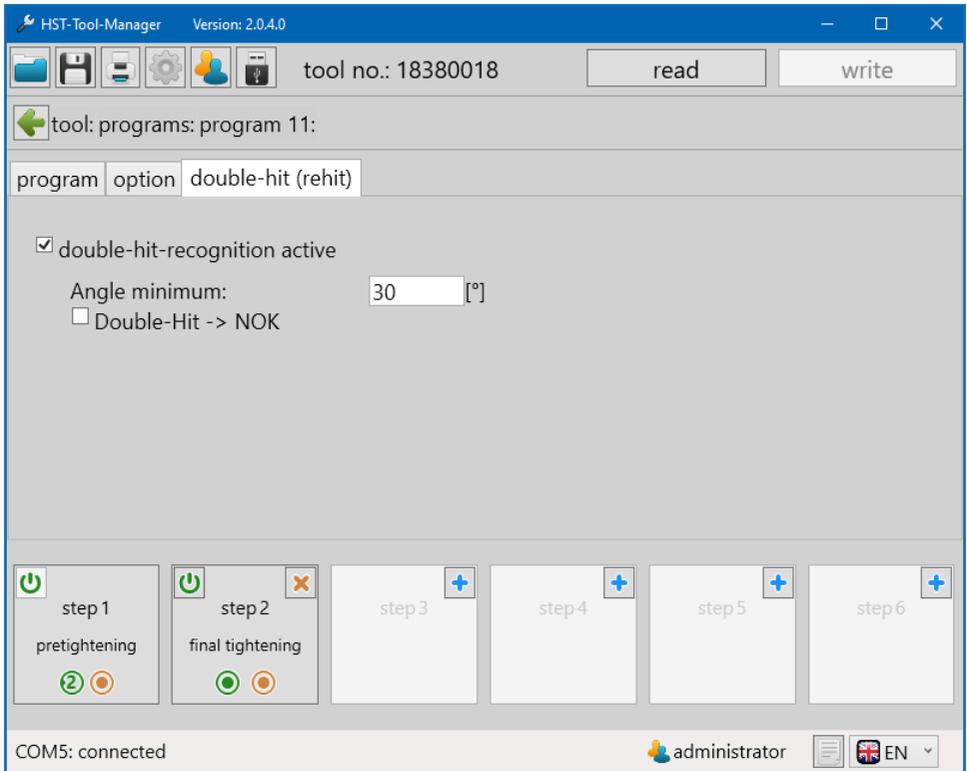
To this end a new program will be created which we have called “torque controlled”.

Under the “program” tab an additional step will be added to the standard existing step 1. In the area “characteristics” the value “only if NOK” will be set for “errors per screw”, which permits a screw connection to be loosened after a NOK screw connection. With



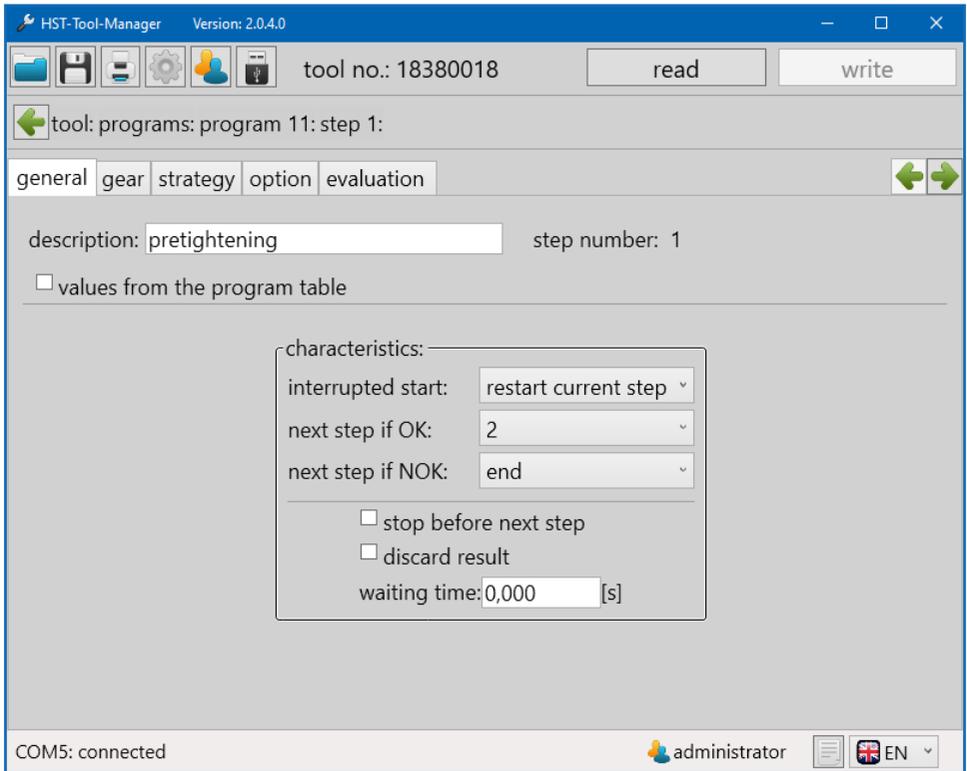
57 Sample program 1 Program

the "errors per screw" we set the parameters so that an overall NOK is only issued after the third attempt which is assessed with NOK. We have made no changes under the "option" tab.



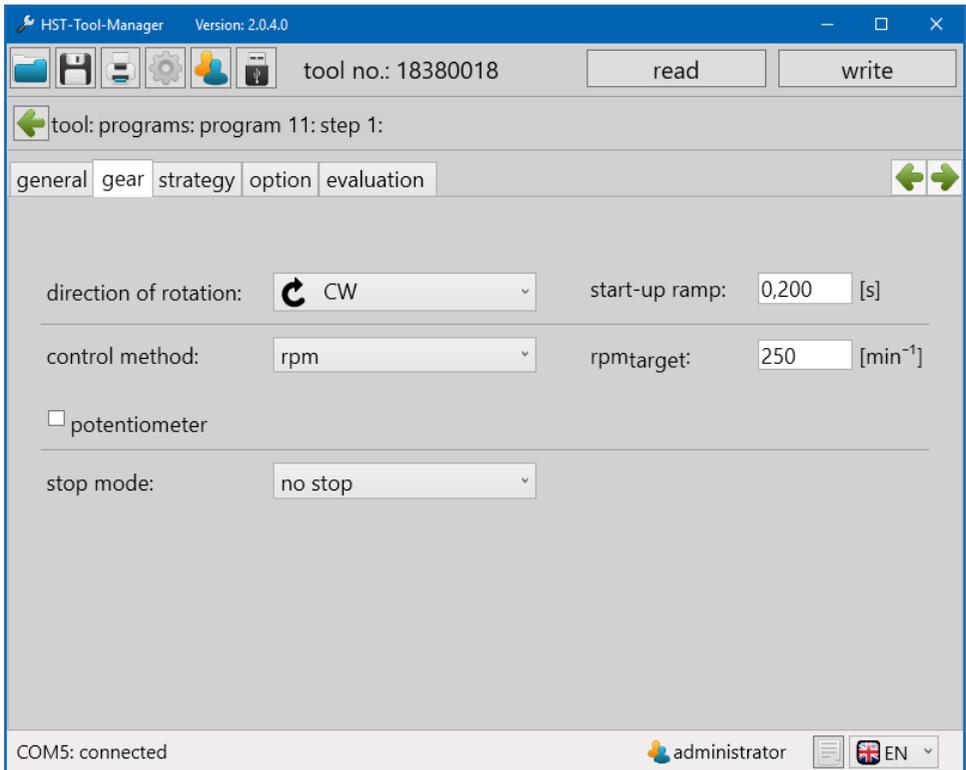
Under the "double-hit (rehit)" tab we activated the double-hit identification and entered the minimum angle of 30° so that a screw connection is assessed as a double-hit if the angle achieved is smaller than 30°.

Now we will devote our attention to the steps, beginning with step 1. Under the tab "general" nothing needs to be changed because the characteristics already corresponds to our expectations. An aborted start is not permitted in the event of an OK assessment in the first step the program jumps into the second step and in the event of a NOK assessment the program is ended.



59 Sample program 1 General 1

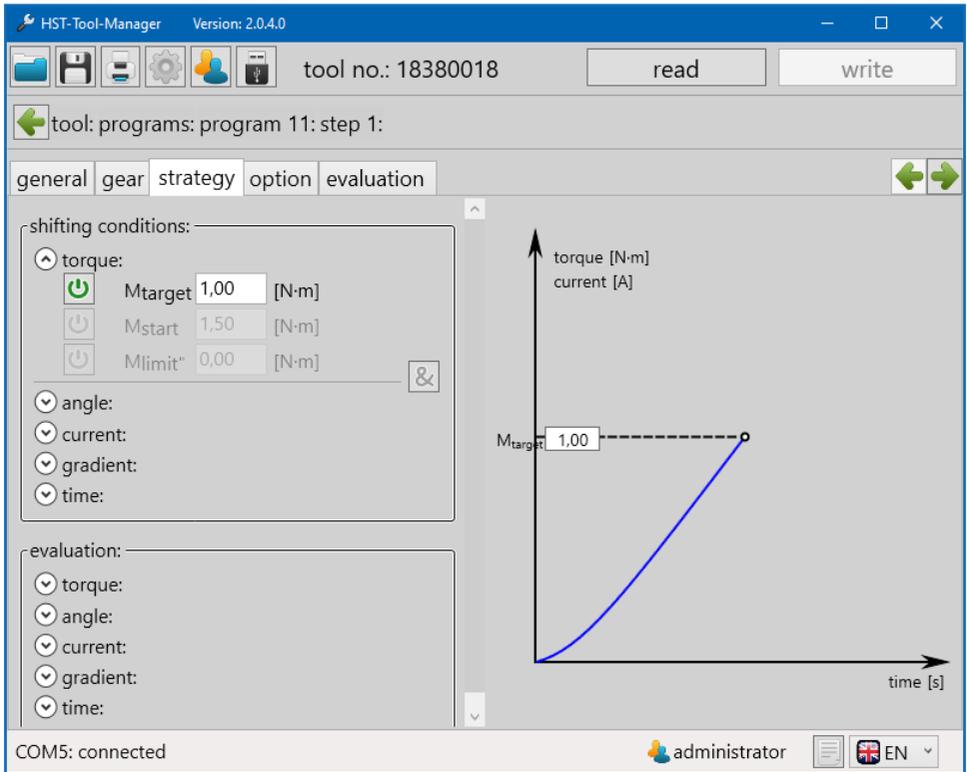
In the “gear” tab we parameterise the number of revolutions per minute and the type of control for the motor. We set 250 rpm and select "rpm" for the control method whereby the tool will try to maintain this rotation speed, even under load. In order to obtain a more engine-friendly start and reduce the starting current peak at the same time we will set another “start-up ramp” of 150ms. For stop mode we will select “no stop” because we want to achieve a fluid transfer into the second step in which the final tightening of the screw connection then takes place.



60 Sample program 1 Gear 1

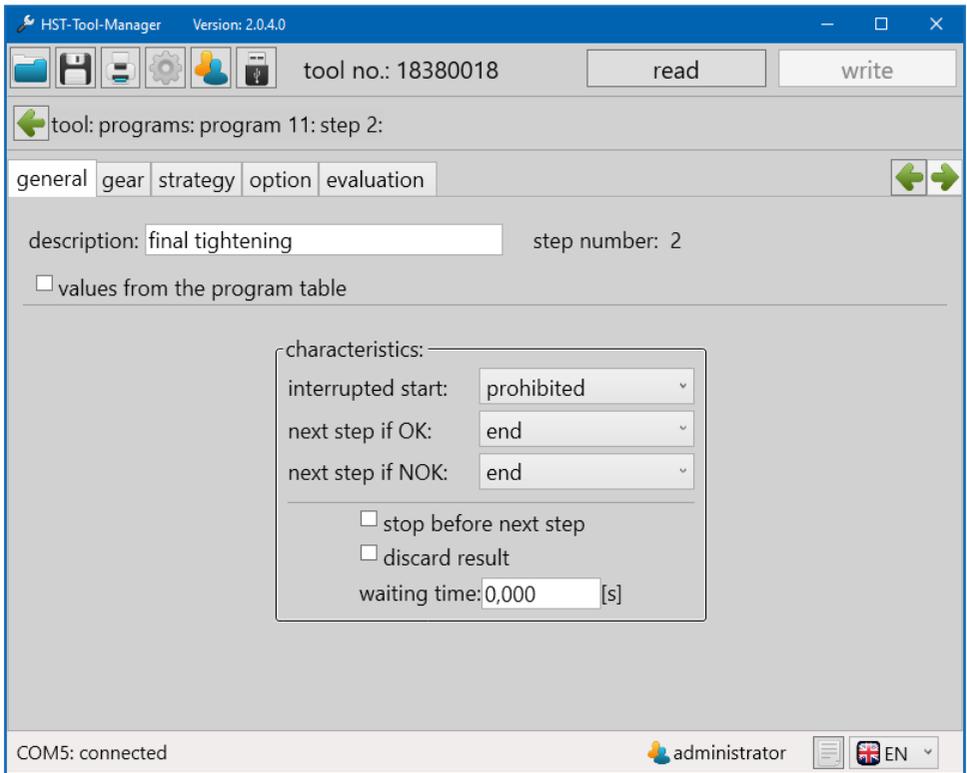
Under the “strategy” tab both shifting conditions as well as evaluation criteria can be set. In the first step, however, the condition for proceeding as soon as a torque of 1Nm is reached, which we enter at “ M_{Target} ”, is sufficient. We do not need to make any changes in the “option” and “evaluation” tabs.

The first step is parameterized and we switch into the second step, the final tightening.



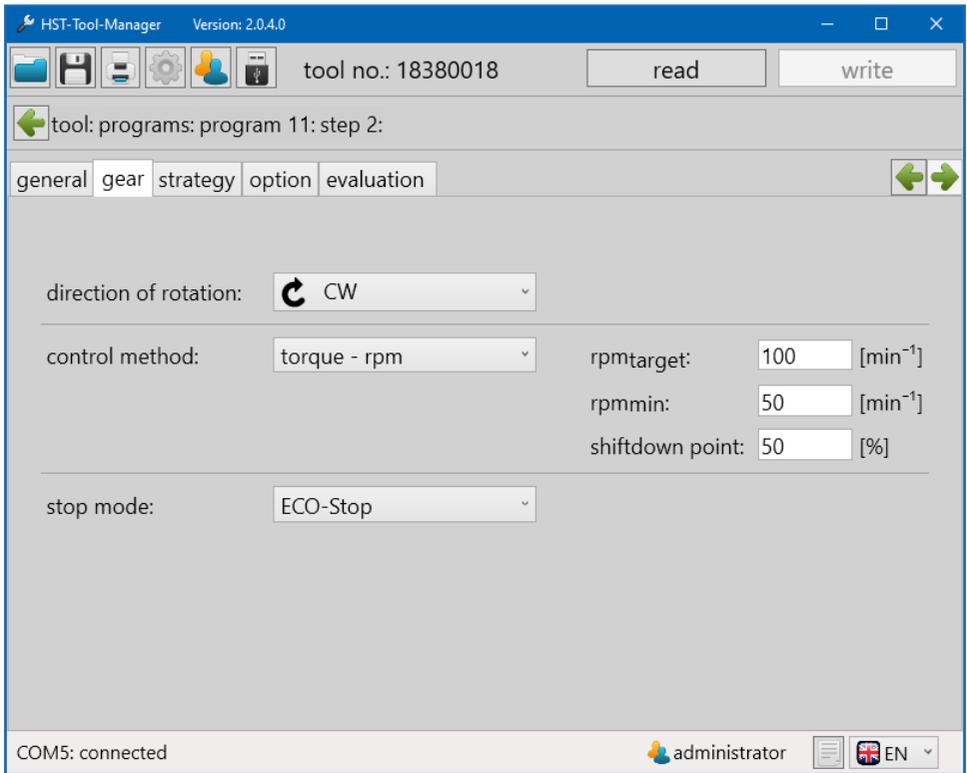
61 Sample program 1 Strategy 1

Under the “general” tab we do not need to make any more changes for the characteristics because this is already automatically set the way we want it during the creation of the step. An aborted start is not permitted and both in the event of an OK - as well as with a NOK assessment of the second step, the program will be ended.

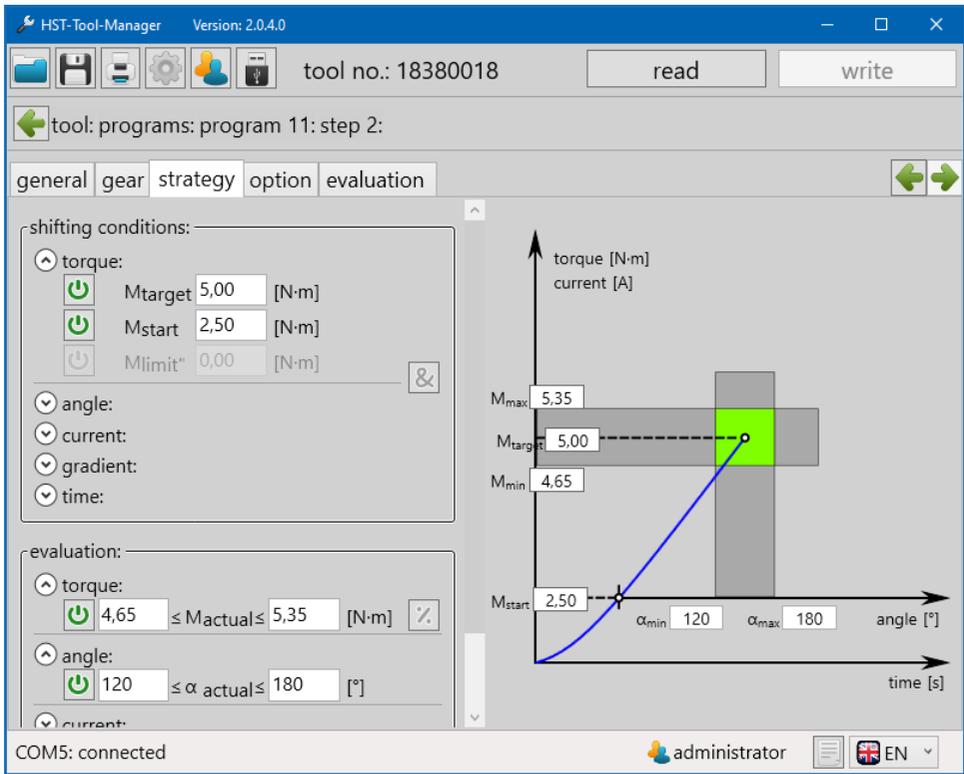


62 Sample program 1 General 2

Now we selected a different control type under the “gear” tab. With the option “torque-rpm” the rotation speed is controlled depending on the torque achieved. To this end, the rotation speed with which the step should be started with is specified under “rpm_{target}”; we slow the tool down here and set the speed at 100 rpm. The value “rpm_{min}” specifies the switch off speed; when switching off we only want to be 50 rpm. The shift-down point relates to the target torque to be reached in the program in percent. As soon as it has been reached the tool begins to regulate the speed down, but not slower than “rpm_{min}”. Because we did not set a stop in the first step and the tool is already turning when it switches into the second step we do not need a start-up ramp. However, in this step the tool should come to a stop when reaching the set torque which is why we are setting “ECO-Stop” in the stop mode, an effective and gentle method of stopping.



Under the tab “strategy” we set the parameters for the screw joint. With these switch conditions we set “ M_{target} ” at 5.00 Nm; the tool hereby switches off when reaching this torque value. With “ M_{start} ” the torque is specified from which the angle counting begins. We set it to 50% of the target torque, at 2.50 Nm. In the evaluation we set the upper and lower limits for the evaluation criteria “torque” and “angle”. For the torque we tolerate $\pm 7\%$ of the target torque. The rotation angle must lie between 120 and 180 angle degrees so that the screw connection will be evaluated as OK. In the graphic all evaluation limits are stylistically represented so that a quick overview of the screw joint is provided.



64 Sample program 1 Strategy 2

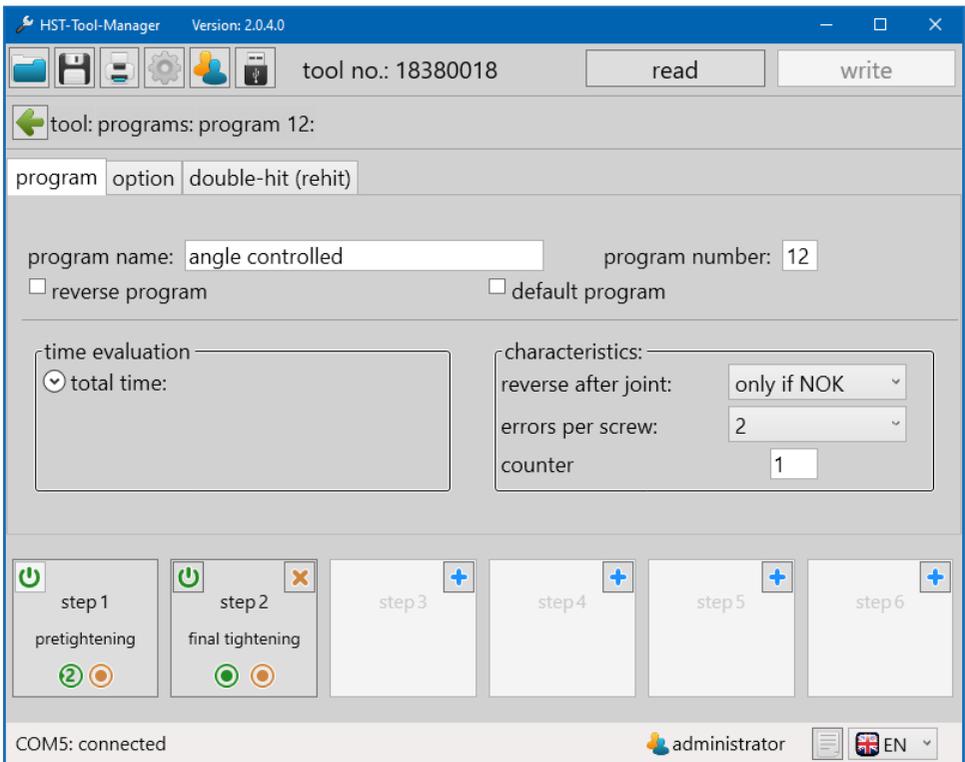
No changes needed to be made in the “option” and “evaluation” in the second step as well. The torque controlled program with torque and rotation angle monitoring is now complete.

7.2 STRATEGY ROTATION ANGLE CONTROLLED/TORQUE MONITORED

Switch-off using the rotation angle with torque monitoring.

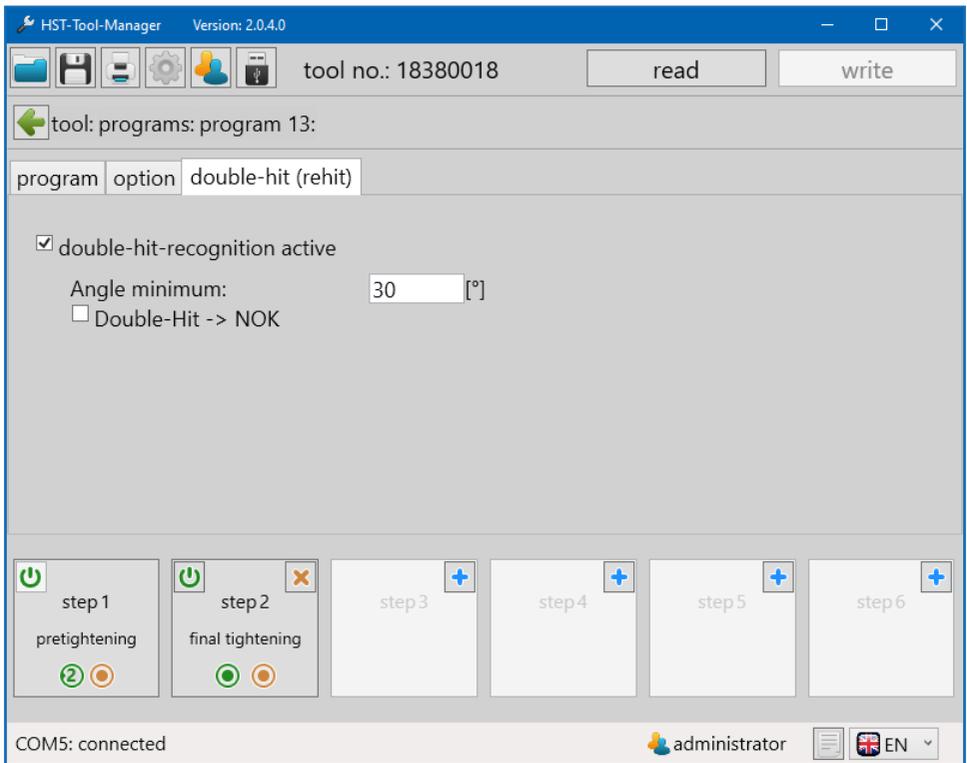
To this end a new program will be created which we have called “angle controlled”. Under the “program” tab an additional step will be added to the standard existing step 1. In the area “characteristics” the value “only if NOK” will be set for “reverse after joint”, which permits a screw connection to be loosened after a NOK screw connection. With the “error per screw” we set the parameters so that an overall NOK is only issued after the third attempt which is assessed with NOK.

We have made no changes under the “option” tab.



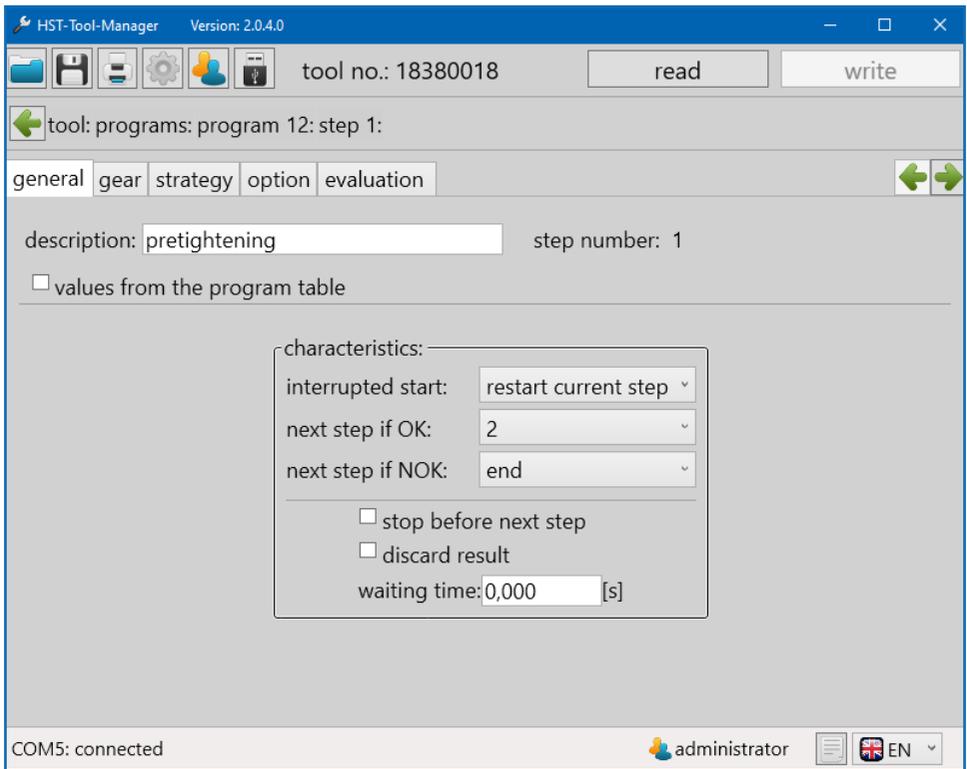
65 Sample program 2 Program

Under the “double-hit (rehit)” tab we activated the double-hit identification and entered the minimum angle of 30° so that a screw connection is assessed as a double-hit if the angle achieved is smaller than 30°.



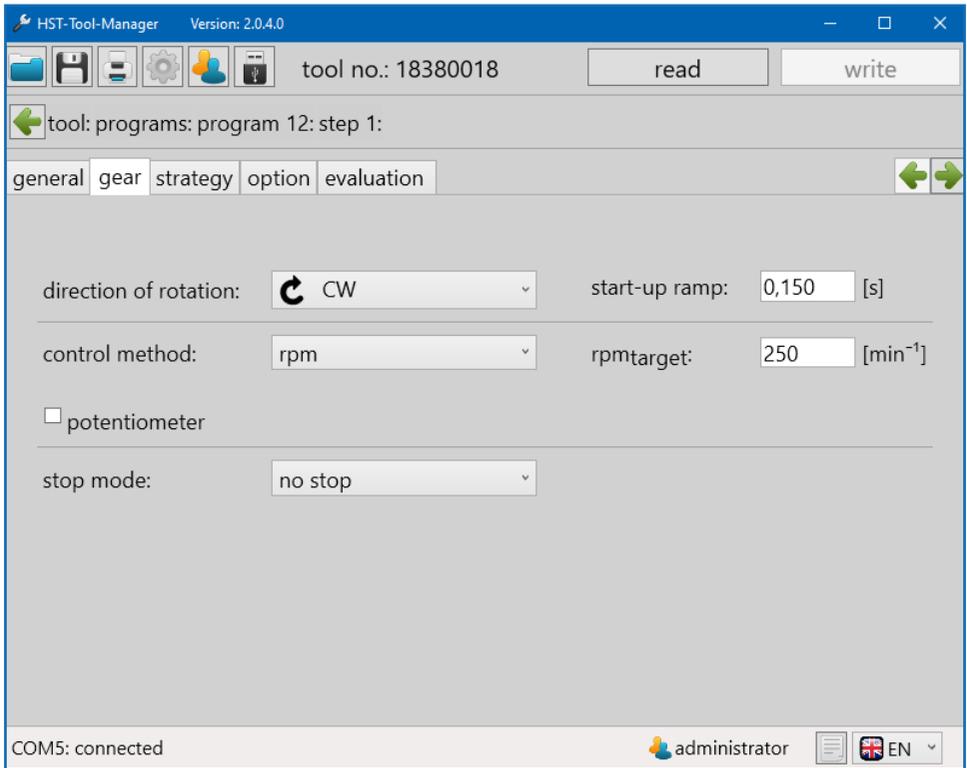
66 Sample program 2 Double-Hit (Rehit)

Now we will devote our attention to the steps, beginning with step 1. Under the tab “general” nothing needs to be changed because the characteristics already corresponds to our expectations. An aborted start is not permitted in the event of an OK assessment in the first step the program jumps into the second step and in the event of a NOK assessment the program is ended.



67 Sample program 2 General 1

In the “gear” tab we parameterise the number of revolutions per minute and the control method for the motor. We set 250 rpm and select “rpm” for the control method whereby the tool will try to maintain this rotation speed, even under load. In order to obtain a more engine-friendly start and reduce the starting current peak at the same time we will set another “start-up ramp” of 150ms. For stop mode we will select “no stop” because we want to achieve a fluid transfer into the second step in which the final tightening of the screw connection then takes place.



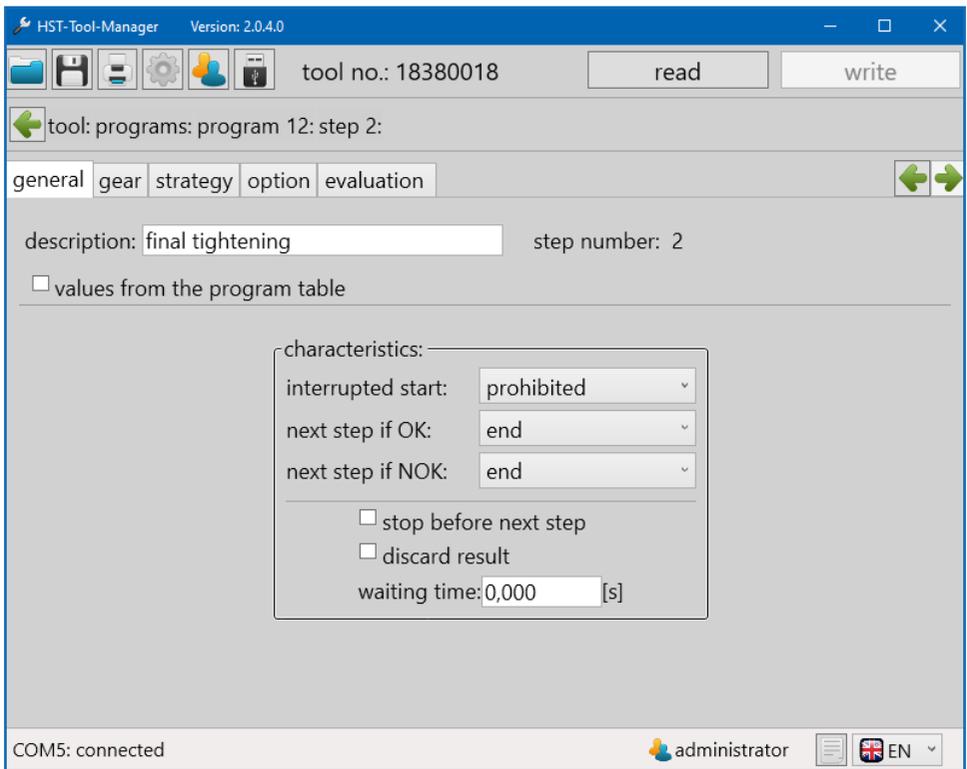
68 Sample program 2 Gear 1

Under the “strategy” tab both progression conditions as well as evaluation criteria can be set. In the first step, however, the condition for proceeding as soon as a torque of 3Nm is reached, which we enter at “ M_{Target} ”, is sufficient. We do not need to make any changes in the “option” and “evaluation” tabs.

The screenshot shows the HST-Tool-Manager software interface. The title bar indicates the version is 2.0.4.0. The main window displays the tool number 18380018 and buttons for 'read' and 'write'. The current step is 'program 12: step 1'. The 'strategy' tab is selected, showing shifting conditions and evaluation criteria. The 'shifting conditions' section includes a 'torque' section with a green power button icon and three input fields: M_{target} set to 3,00 [N-m], M_{start} set to 1,50 [N-m], and M_{limit} set to 0,00 [N-m]. Below this are sections for 'angle', 'current', 'gradient', and 'time', each with a dropdown arrow. The 'evaluation' section also has dropdown arrows for 'torque', 'angle', 'current', 'gradient', and 'time'. On the right, a graph plots torque [N-m] and current [A] against time [s]. A blue curve starts at the origin and rises to a point where a horizontal dashed line is drawn at $M_{target} = 3,00$. The y-axis is labeled 'torque [N-m]' and 'current [A]', and the x-axis is labeled 'time [s]'. The bottom status bar shows 'COM5: connected', the user 'administrator', and the language 'EN'.

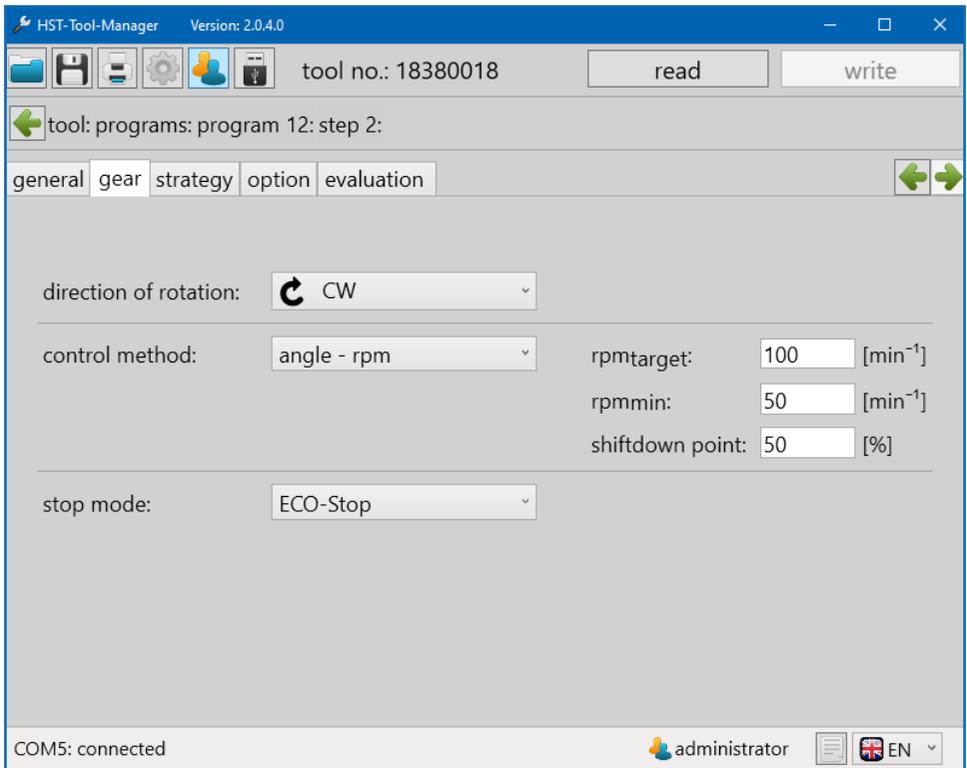
69 Sample program 2 Strategy 1

The first step is parameterized and we switch into the second step, the final tightening. Under the “general” tab we do not need to make any more changes for the characteristics because this is already automatically set the way we want it during the creation of the step. An aborted start is not permitted and both in the event of an OK - as well as with a NOK assessment of the second step, the program will be ended.



70 Sample program 2 General 2

Now we selected a different control method under the “gear” tab. With the option “angle-rpm” the number of revolutions the speed is controlled depending on the torque achieved. To this end, the number of revolutions per minute with which the step should be started with is specified under “rpm_{target}”; we slow the tool down here and set the speed at 100 rpm. The value “rpm_{min}” specifies the switch off speed; when switching off we only want 50 rpm. The “shiftdown point” relates to rotation angle to be reached for the program in percent. As soon as it has been reached the tool begins to regulate the speed down, but not slower than “rpm_{min}”. Because we did not set a stop in the first step and the tool is already turning when it switches into the second step we do not need a start-up ramp. However, in this step the tool should come to a stop when reaching the set rotation angle which is why we are setting “ECO-Stop” in the stop mode, an effective and gentle method of stopping.



71 Sample program 2 Gear 2

Under the tab “strategy” we set the parameters for the screw joint. With these switch conditions we set “ α_{target} ” at 60°; the tool hereby switches off when reaching this rotation angle. By setting “ M_{start} ” at 2.50 Nm the angle counting begins only upon reaching this torque. In the evaluation we set the upper and lower limits for the evaluation criteria “torque” and “angle”. With the torque, generous limits, from 5.00 to 8.00 Nm, because our target value is the rotation angle. The rotation angle may deviate a maximum of 5° so that the screw connection is evaluated as OK. In the graphic all evaluation limits are stylistically represented so that a quick overview of the screw joint is provided. No changes needed to be made in the “option” and “evaluation” in the second step as well. The rotation angle controlled program with torque and rotation angle monitoring is now complete.

HST-Tool-Manager Version: 2.0.4.0

tool no.: 18380018

read write

tool: programs: program 12: step 2:

general gear strategy option evaluation

shifting conditions:

torque:

- M_{target} 3,00 [N·m]
- M_{start} 2,50 [N·m]
- M_{limit} 0,00 [N·m]

angle:

- α_{target} 60 [°]

current:

gradient:

time:

evaluation:

torque:

- $5,00 \leq M_{actual} \leq 8,00$ [N·m]

angle:

- $55 \leq \alpha_{actual} \leq 65$ [°]

COM5: connected administrator EN

torque [N·m]
current [A]

M_{max} 8,00
 M_{min} 5,00
 M_{start} 2,50

α_{min} 55
 α_{target} 60
 α_{max} 65

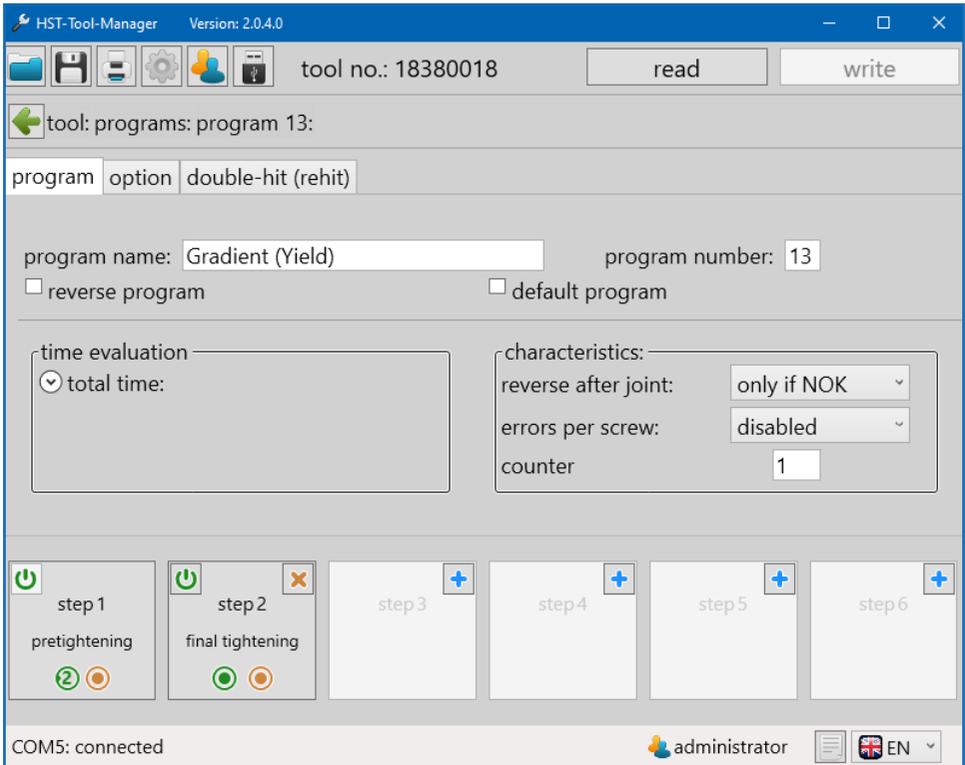
angle [°]
time [s]

72 Sample program 2 Strategy 2

7.3 STRATEGY GRADIENT CONTROLLED/ROTATION ANGLE MONITORED

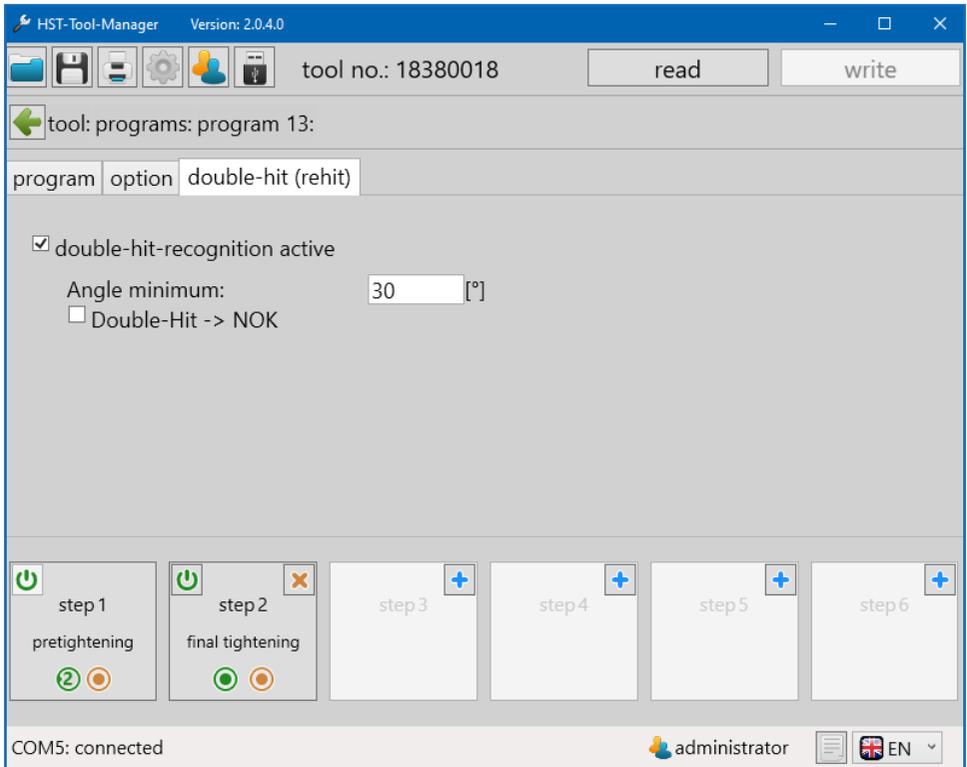
Switching off using the torque-gradient with angle monitoring.

To this end a new program will be created which we have called "Gradient (Yield)". Under the "program" tab an additional step will be added to the standard existing step 1. In the area "characteristics" the value "NOK" will be set for "reverse after joint", which permits a screw connection to be loosened after a NOK screw connection. With the "error per screw" at "disabled" we set the parameters so that an overall NOK is already issued after the first attempt which is assessed with NOK. For screw connections which are gradient controlled the yield strength of the screw material is used, therefore the effective force, starting from which the material no longer deforms elastically, but plastically. For this reason a screw which has already been stressed above its yield strength cannot be used again.



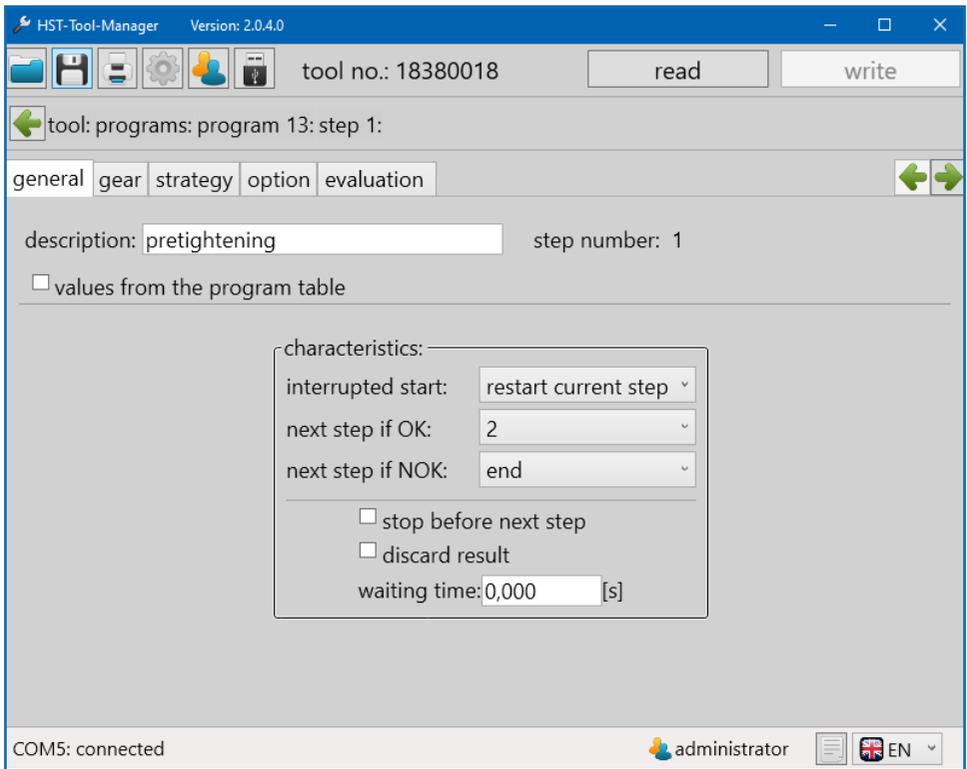
73 Sample program 3 Program

We have made no changes under the “option” tab. Under the “double-hit (rehit)” tab we activated the double-hit identification and entered the minimum angle of 30° so that a screw connection is assessed as a double-hit if the angle achieved is smaller than 30°.



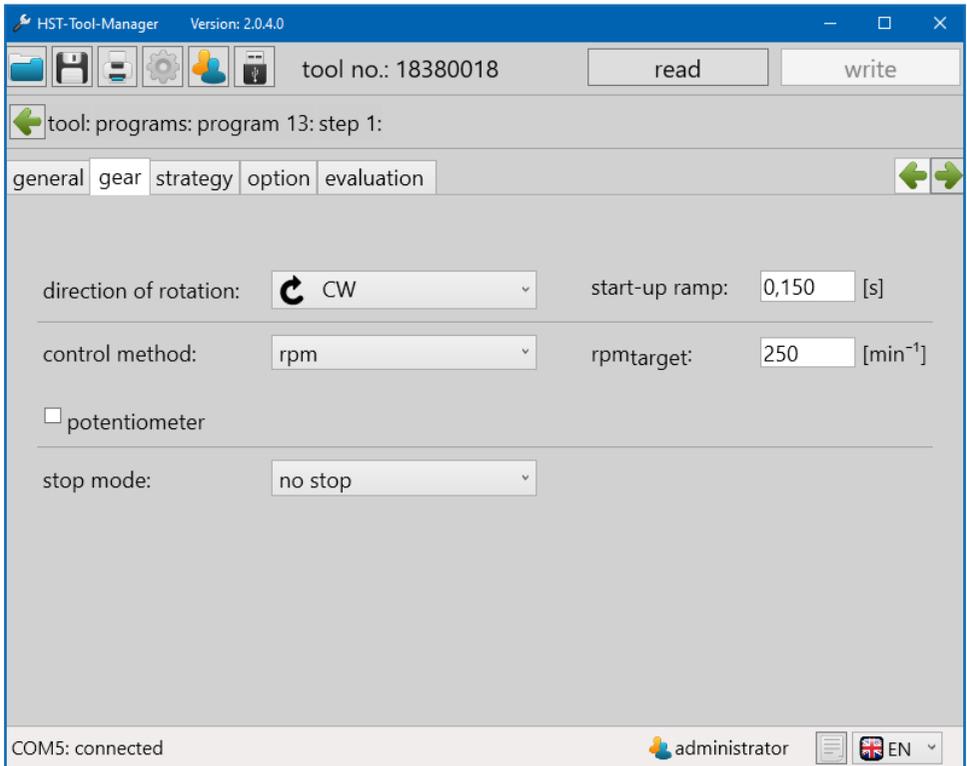
74 Sample program 3 Double-Hit (Rehit)

Now we will devote our attention to the steps, beginning with step 1. Under the tab “general” nothing needs to be changed because the characteristics already corresponds to our expectations. An aborted start is not permitted in the event of an OK assessment in the first step the program jumps into the second step and in the event of a NOK assessment the program is ended.



75 Sample program 3 General 1

In the “gear” tab we parameterise the number of revolutions per minute and the type of control method for the motor. We set 250 rpm and select “rpm” for the control method whereby the tool will try to maintain this speed, even under load. In order to obtain a more engine-friendly start and reduce the starting current peak at the same time we will set another “start-up ramp” of 150ms. For stop mode we will select “no stop” because we want to achieve a fluid transfer into the second step in which the final tightening of the screw connection then takes place.



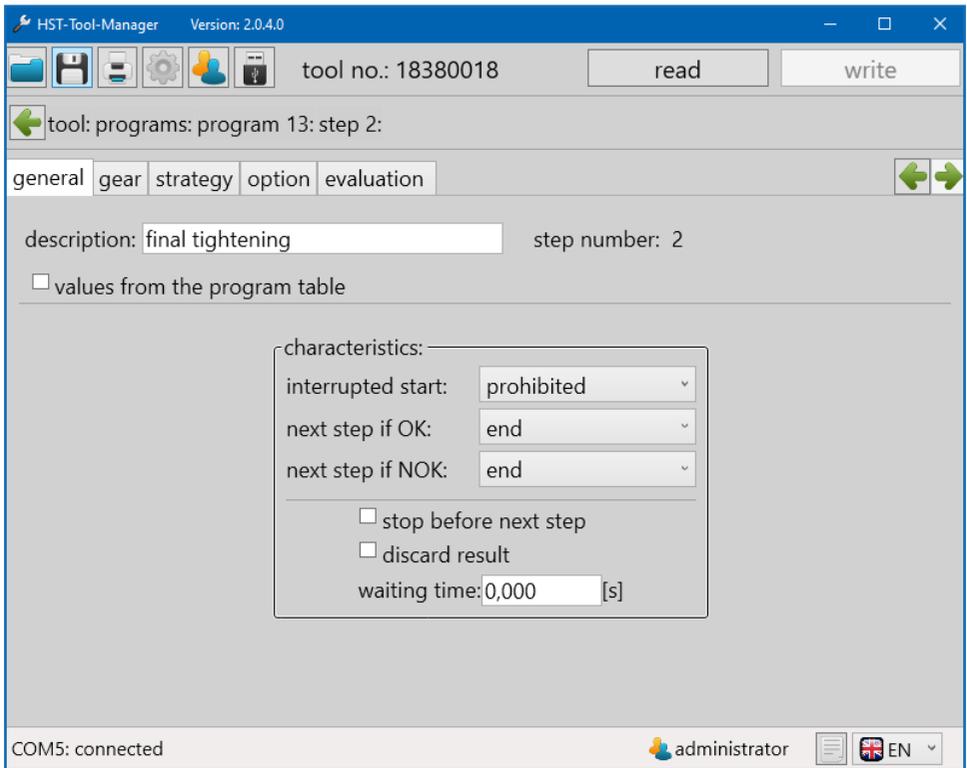
76 Sample program 3 Gear 1

Under the “strategy” tab both progression conditions as well as evaluation criteria can be set. In the first step, however, the condition for proceeding as soon as a torque of 3Nm is reached, which we enter at “ M_{Target} ”, is sufficient. We do not need to make any changes in the “option” and “evaluation” tabs.

The screenshot shows the HST-Tool-Manager software interface. The title bar indicates the version is 2.0.4.0. The main window displays the tool number 18380018 and buttons for 'read' and 'write'. The current step is 'program 13: step 1'. The 'strategy' tab is selected, showing shifting conditions and evaluation criteria. The 'shifting conditions' section includes a 'torque' section with a green power button icon and three input fields: M_{target} (3,00 [N-m]), M_{start} (1,50 [N-m]), and M_{limit} (0,00 [N-m]). Below this are sections for 'angle', 'current', 'gradient', and 'time', each with a dropdown arrow. The 'evaluation' section also has dropdown arrows for 'torque', 'angle', 'current', 'gradient', and 'time'. On the right, a graph plots torque [N-m] and current [A] against time [s]. A blue curve starts at the origin and rises to a point where a horizontal dashed line is drawn at $M_{target} = 3,00$. The y-axis is labeled 'torque [N-m]' and 'current [A]', and the x-axis is labeled 'time [s]'. The bottom status bar shows 'COM5: connected', the user 'administrator', and the language 'EN'.

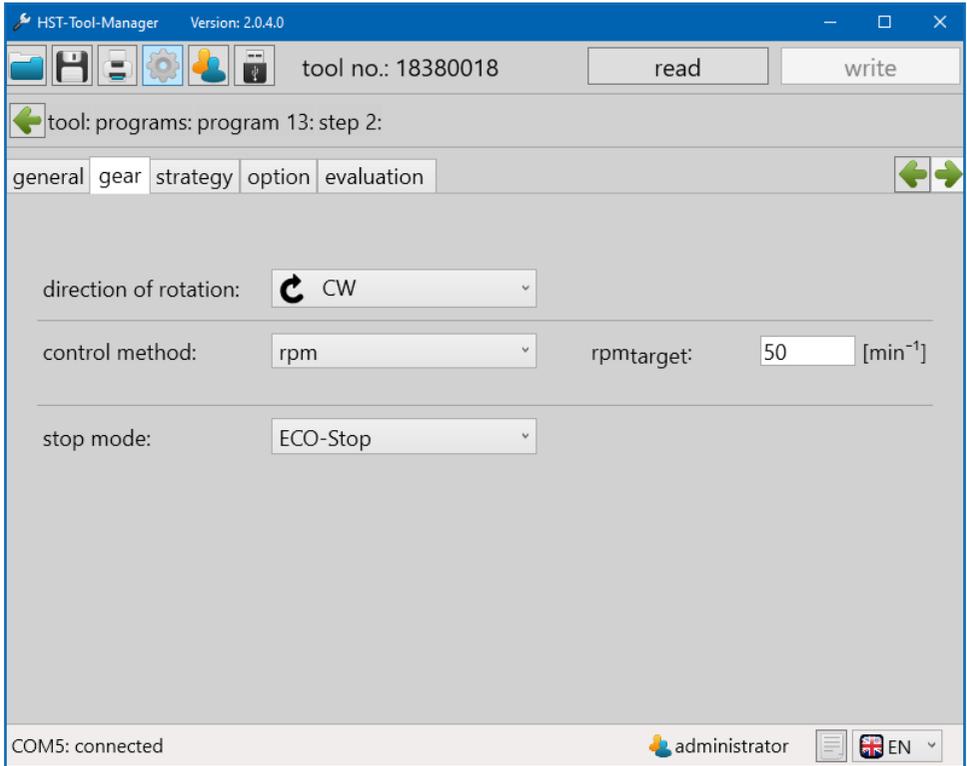
77 Sample program 3 Strategy 1

The first step is parameterized and we switch into the second step, the final tightening. Under the “general” tab we do not need to make any more changes for the characteristics because this is already automatically set the way we want it during the creation of the step. An aborted start is not permitted and both in the event of an OK - as well as with a NOK assessment of the second step, the program will be ended.



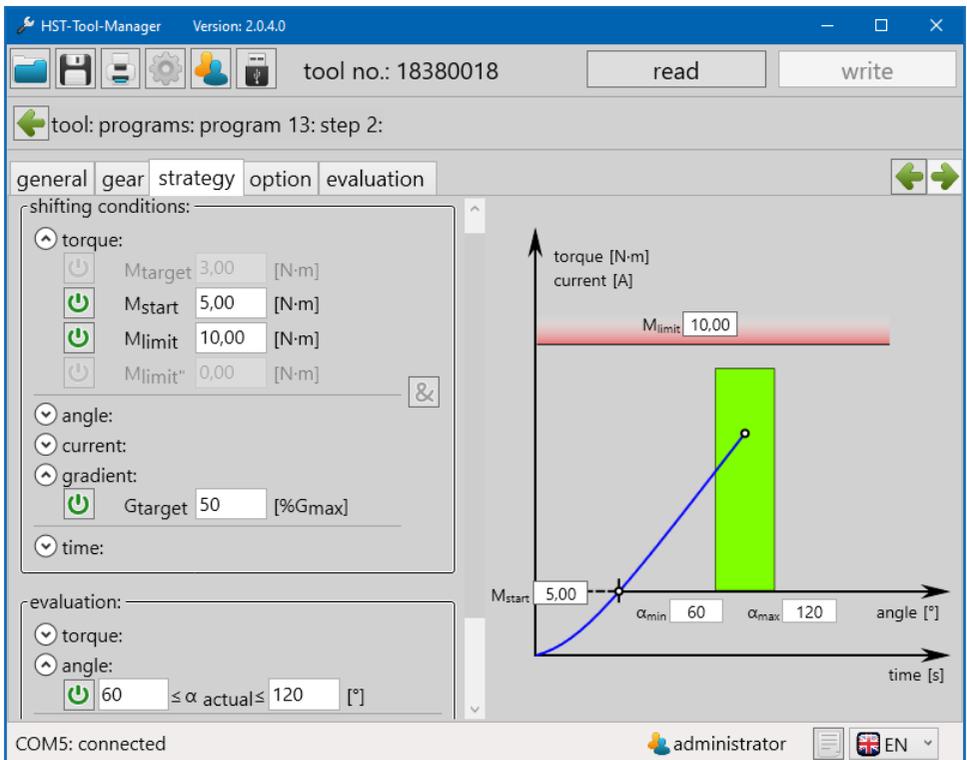
78 Sample program 3 General 2

Under the “gear” tab we retained the “rpm” control method. In order to establish a targeted torque we slow the tool down here and set the speed to 50 rpm. Because we did not set a stop in the first step and the tool is already turning when it switches into the second step we do not need a start-up ramp. However, in this step the tool should come to a stop as soon as the torque gradient drops again. For this reason we set “ECO-Stop” in the stop mode; an effective and gentle method of stopping.



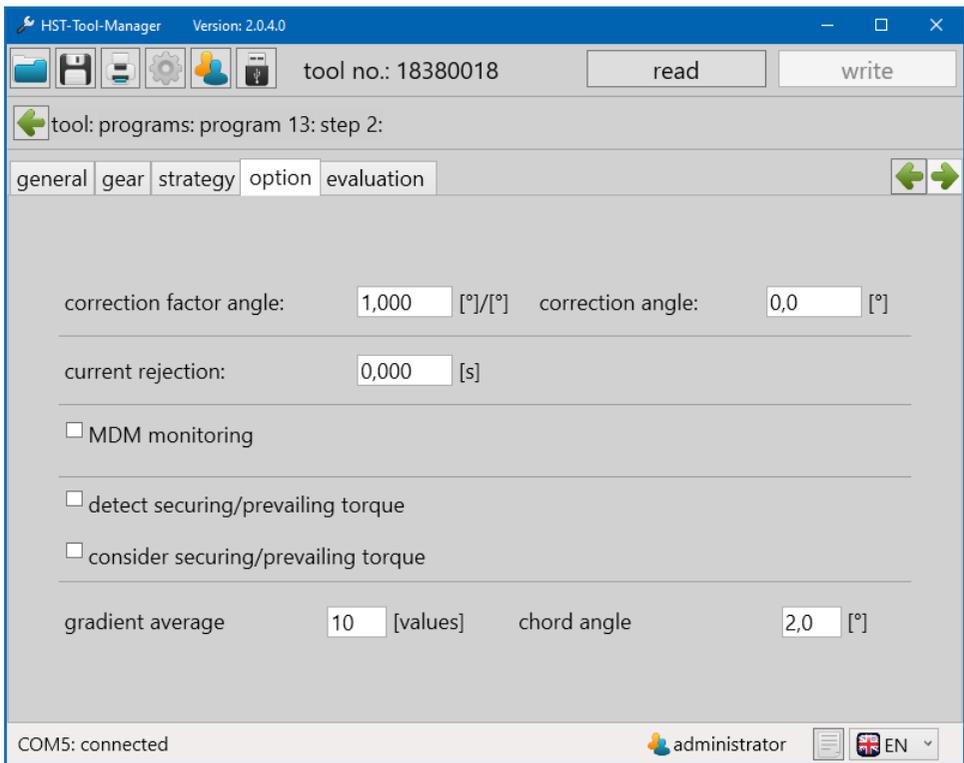
79 Sample program 3 Gear 2

Under the tab “strategy” we set the parameters for the screw joint. In the switching conditions we set “ M_{start} ” to 5 Nm so that the rotation angle counting begins starting at this torque. In addition we set an “ M_{limit} ” with 10 Nm. As soon as this torque is reached the tool also switches off. The actual desired switch off should take place via the torque gradient. This gradient is the torque rate of increase. Under “ G_{target} ” we set the value in percent of the maximum value at which a switch off should take place. The tool permanently measures the torque rate of increase during the screwing process; if this suddenly drops due to reaching the yield strength of the screw material the tool realises this and switches off. In our case the switch off occurs as soon as the torque rate of increase drops to 50% of the maximum. In the evaluations we set another rotation angle range of 60 to 120 angle degrees.



80 Sample program 3 Strategy 2

For the calculation of the torque gradients one must specify over how many measurement values the rate of increase should be calculated under the “option” tab; to this end we specify 10 values under “gradient average” so that the average is always derived from the last 10 values and the increase to the last average then results in the gradients. The “chord angle” specifies across how many angle degrees the 10 measurement values should be distributed. In our case we want to calculate the average from 10 measurement values across 2 angle degrees.



81 Sample program 3 Option 2

8 THE BARCODE

With all tools which are equipped with a barcode scanner it is possible to select programs directly using a defined barcode. It is also possible to connect multiple barcodes to one sequence. In this scenario the program is only then started when all the barcodes have been scanned in the correct order.

8.1 BASIC SETTING

Make sure that your tool is equipped with a barcode scanner. In administrator mode the program enabling can be selected via barcode at any time under “setup” ⇒ “general” ⇒ “process control”. See Chapter 5.1.1. tab “process control”, page 37.

8.2 BARCODE INTERFACE

Under “programming” ⇒ “barcode” you will find the interface in order to create a barcode and define its function.

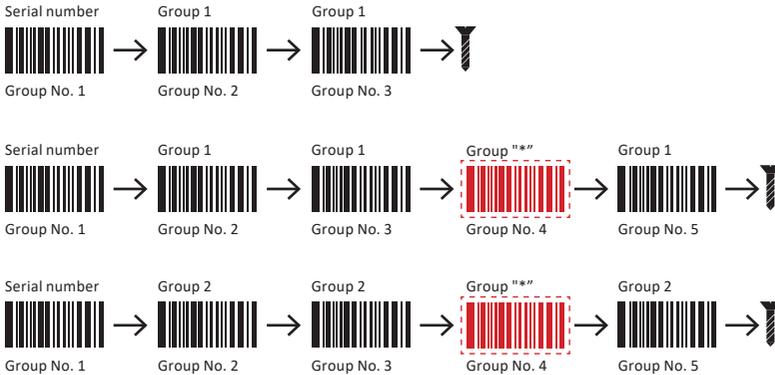


NOTE

A barcode have a maximum of 64 characters.

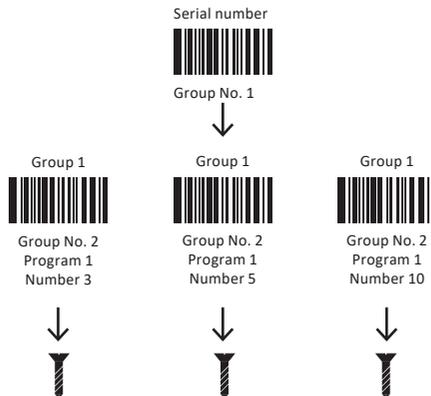
8.3 BARCODE TYPES

Depending on the application barcodes can be configured accordingly. The following graphic shows several of the options available.



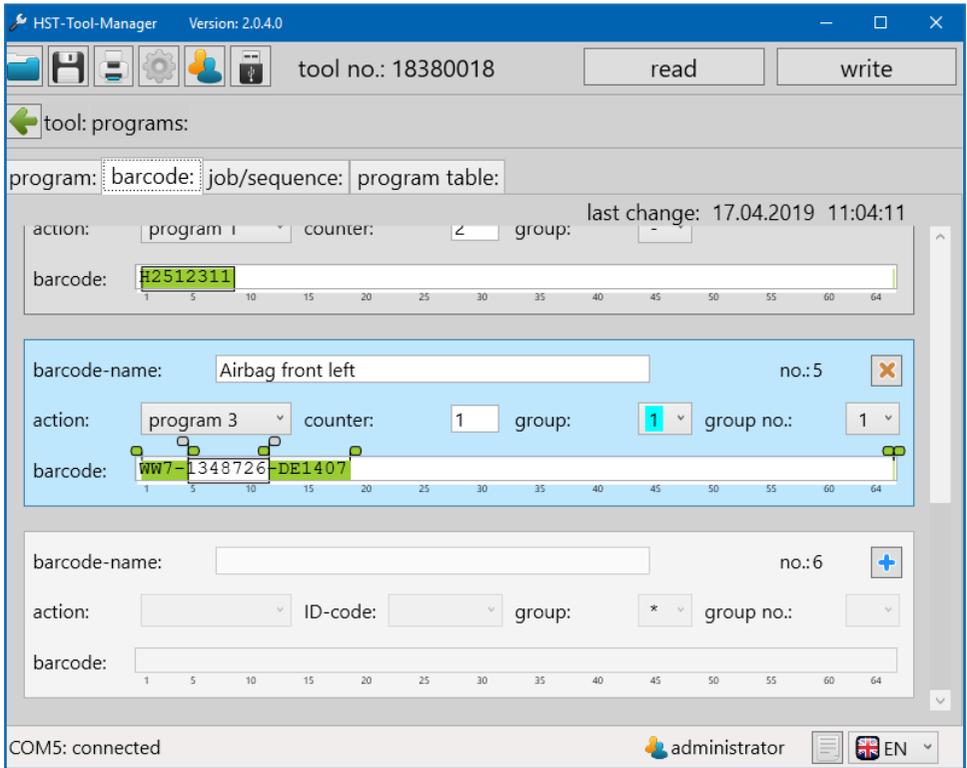
NOTE Barcodes with the group assignment "*" can be applied individually in every group. Only the position / no. must be entered.

Special grouped barcodes



Depending on which component should be processed first, the corresponding barcode can be scanned in.

The green fields define the part of the barcode for the evaluation. The grey field defines the part of the barcode to be displayed in the tool's display. A maximum of 9 characters can be displayed.



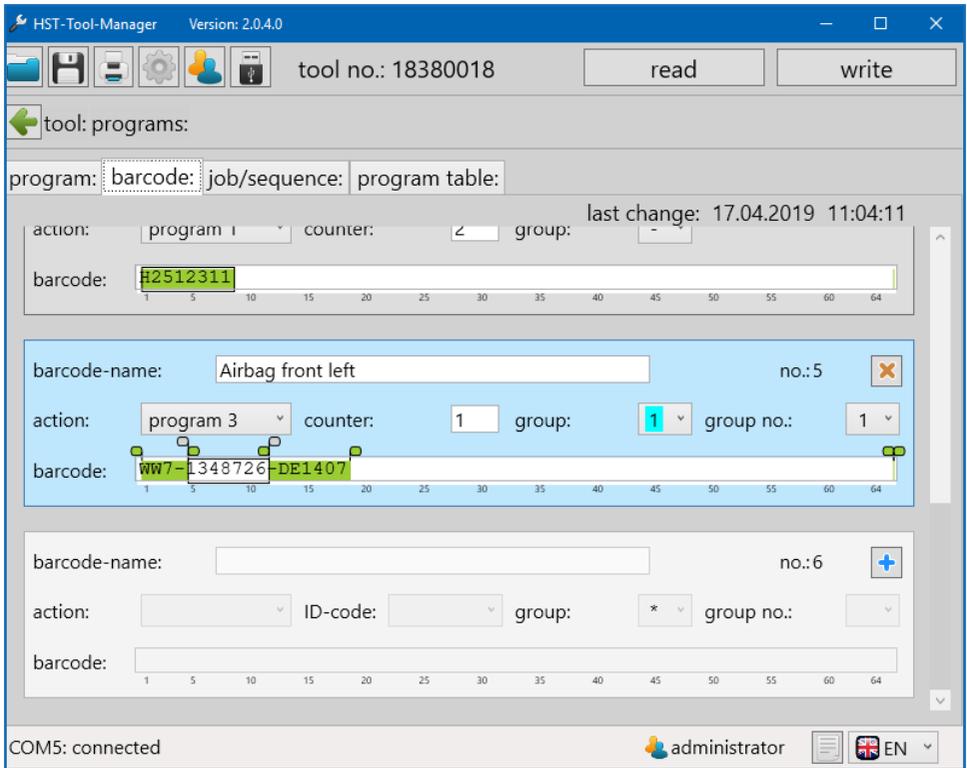
82 Create barcode

WW7-1348726-DE1407

Will not be evaluated and can be variably changed (e.g. continuous serial number). In the example: Value shown in display

The complete barcode is saved. The green fields define the area which is to be evaluated. The variable part, which is defined with the grey sliders, can be at the beginning, in the middle, or at the end of the barcode and will not be evaluated. This part will also be displayed on the display for control purposes. The green and grey sliders can be moved by pressing and holding down the left mouse key.

Activate the screen with .



83 Create barcode

Up to 99 barcodes can be stored.

8.3.1 Screen with a barcode

In order to activate a program directly using the barcode often only part of the barcode is necessary. For this selection and in order to determine the display on the tool the screen is divided into different selection fields.

barcode-name: Airbag front left no.:5

action: program 3 counter: 2 group: 1 group no.: 1

barcode: WW7-1348726-DE1407

Example WW7-1348726-DE1407

“barcode-name”	Designation of the barcode / area of application (maximum 20 characters).
“action”	If a barcode is recognised this setting determines any further action. - <i>program</i> : The program, which should be released with the barcode. - <i>Or</i> : The process number of the program process, which should be enabled with the barcode. - <i>scan</i> : An additional barcode scan is necessary.
“counter”	Number of screws which were enabled with the barcode. In our example we entered 2, i.e. the tool specifies two screw connections, of which one screw connection was already successfully completed in our display image, see tool display on page 122.
“group”	- “-”: Barcode is not assigned to a group. - “1-99”: The barcode will be assigned to one of 99 groups. - “*”: The barcode is valid for all groups.

„group no.“

“1-9”: Establishes the position in the order of the group.

“ID Code”

Becomes visible in the “scan” action. This way the ID code filed in the result can be determined. By default the last barcode is filed as the ID code.

- *Inactive*: Barcode is not filed as the ID code. Last barcode is filed as the ID code, ID2 remains empty.

- *Active*: Barcode is filed as the ID code. ID2 remains empty.

- *2x Code*: Barcode is filed as ID2 code, the last barcode is filed as the ID code.

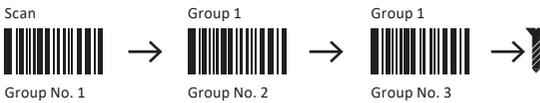


WW7-1348726-DE1407



NOTE

The last barcode in the group must ALWAYS lead to the enabling of the program or the program process.



Here, for example a serial number is being scanned in.



8.3.2 Screen with multiple barcodes

If multiple barcodes are being used for an enabling additional input screens must be activated.

Example with two barcodes:

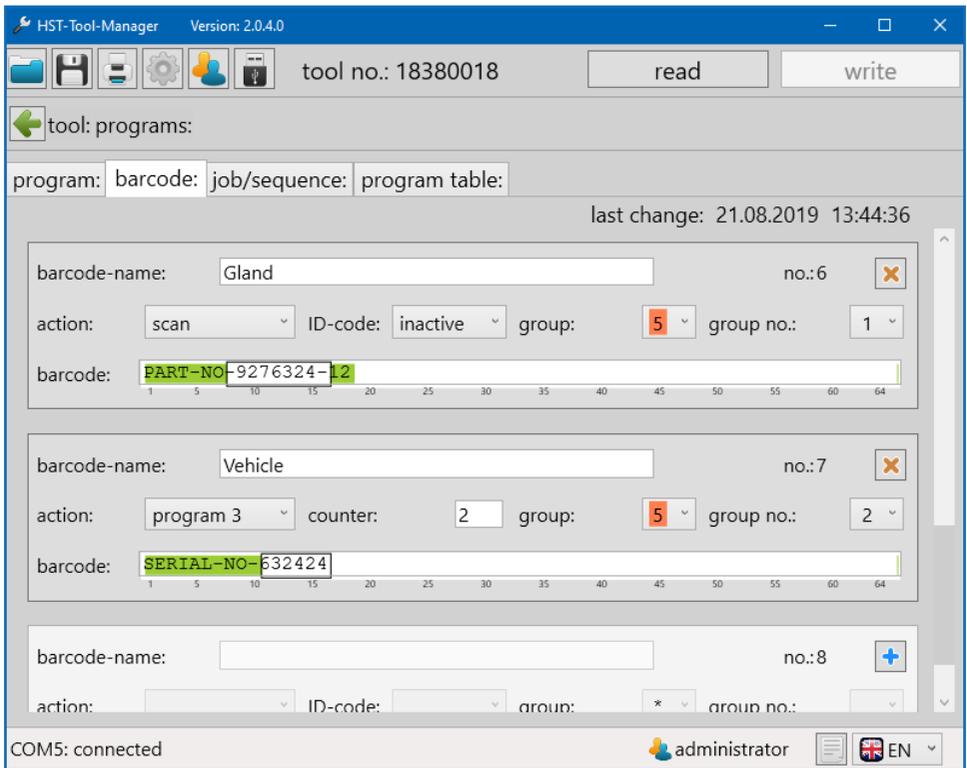
The first barcode is part number "PART-NO-9276345-12".



The second barcode is serial number "SERIAL-NO-632424".

With this the program is activated and the process data documented.





84 Create barcode 2

In our example the barcode, which must first be scanned in, so the one with the “group no.: 1”, is the component identification.

With the barcode screen the parts of the code which are preset are highlighted in green. The framed part is the component number which can vary. It is displayed in the display for monitoring purposes.

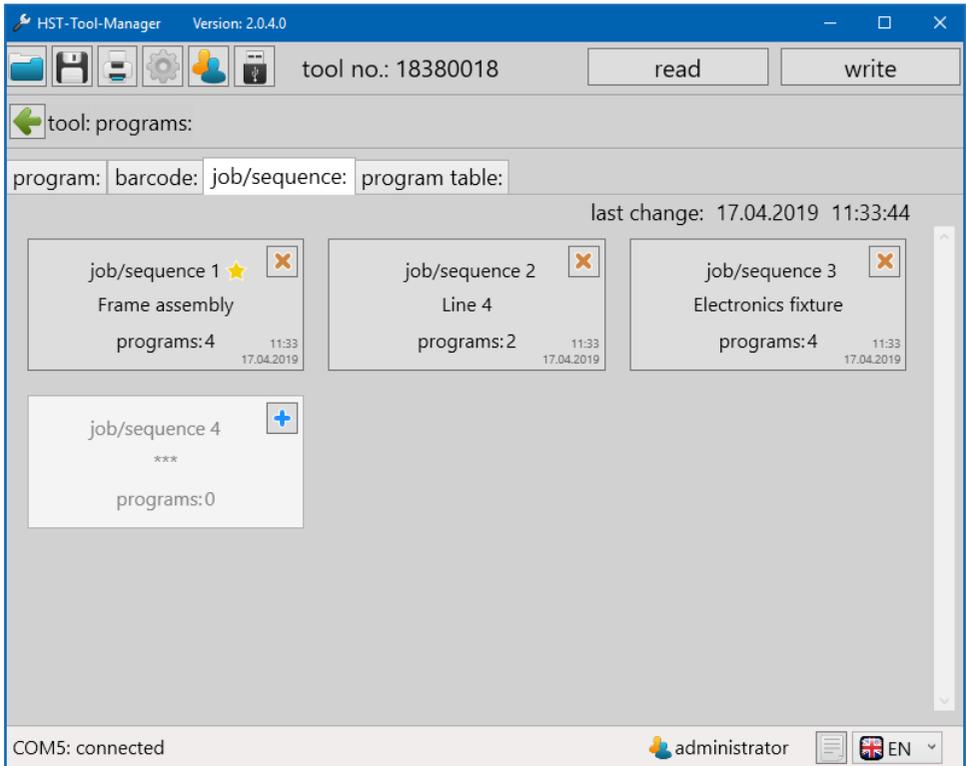
The second barcode with the serial number receives “group no.: 2”. Here too, there is a preset part.

The serial number, which constantly changes, is framed with the grey sliders as a variable part. It is also used for enable the program as well as for documentation and for display.

The sequence must comply with this configuration. Only after the component identification is scanned does a scan of the serial number lead to enabling of the program.

9 SEQUENCE (JOB)

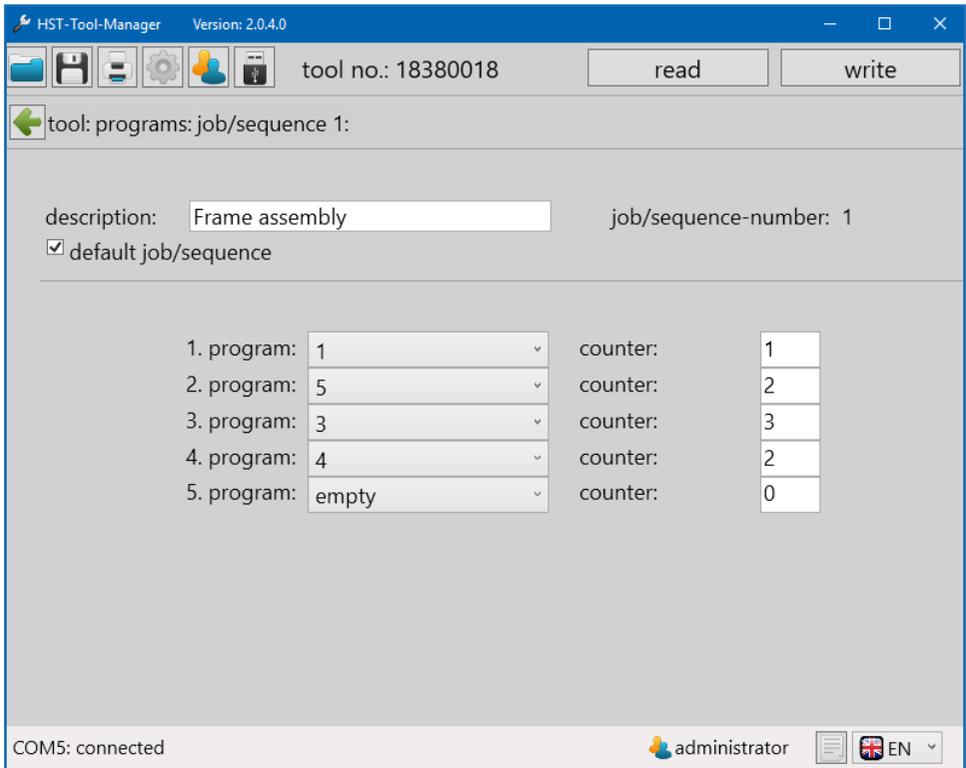
With the HST-Tool-Manager it is possible to create program sequences. In doing so the sequence of the individual programs which should be processed one after the other, is defined. Using this function it is possible to start a preset sequence of programs with one single enabling.



85 Process

In order to program a new process press the  button.

You can get to parametrization via the job/sequence 1 button. Here you can set the order of programs which should be consolidated into one sequence. For each program the number of screw connections is individually specified.



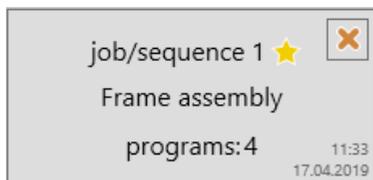
86 Process 2

“description”	Name of the job/sequence (maximum 20 characters).
“job/sequence-number”	Number of the process, max. 8 jobs/sequences are possible.
“default job/sequence”	See default program. The active job/sequence is indicated with a yellow star as with the programs. If a job/sequence is selected as the default job/sequence the tool always starts with this job/sequence in manual mode.

“1(2...n) program”	Selection of the program.
“counter”	Number of screws which will be enabled with the program. If a number of screws is specified in the program it will be ignored.

There are several ways to start a job/sequence:

1. Define the job/sequence as the default.
The tool will always start with this job/sequence in manual mode.

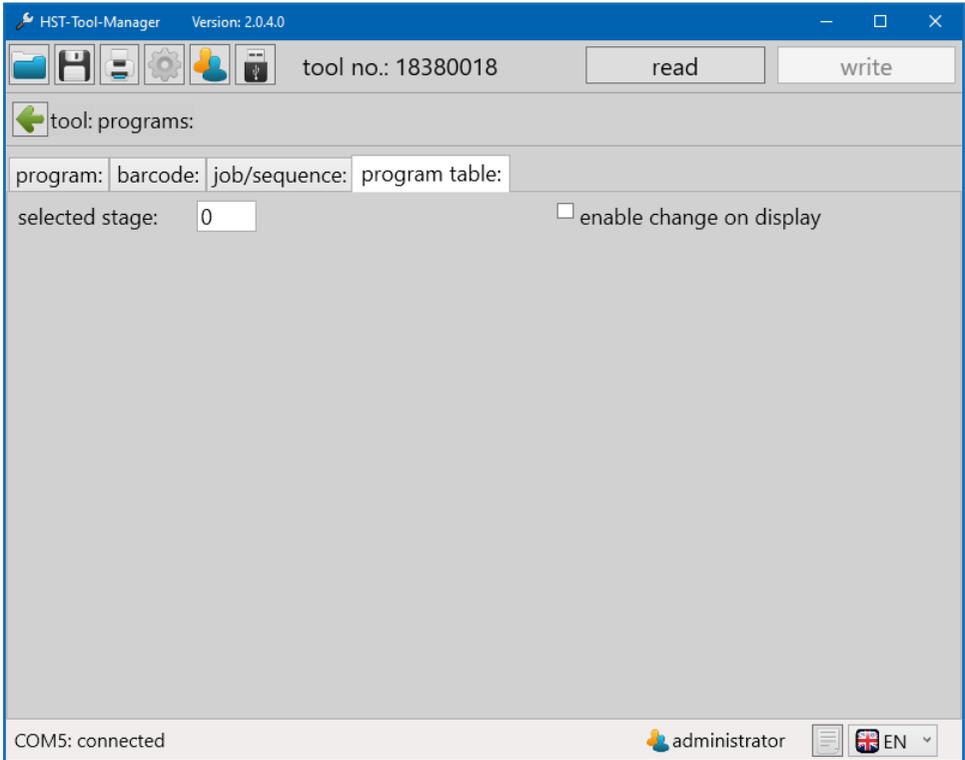


2. Start the job/sequence with a barcode.
To do this select job/sequence 1 under "action" in barcode, enter etc...

3. Enable via wireless (Wi-Fi)
4. Enable using a set time
5. Enable via confirmation of the start switch

10 PROGRAM TABLE

If the program table is activated in the tool, the values from the active line overwrite the values in the last program step.



87 Program table

“selected stage”	Determines from which line (1-100) the values will be used.
“enable change on display”	Activates/deactivates the option of adjusting the active line directly on the tool’s display.



NOTE

The “program table” function can only be activated by the manufacturer. In this case please contact our support service service@hs-technik.com | Telephone: +49 7628 9111-57

11 STATISTICS AND GRAPHICS

11.1 STATISTICS

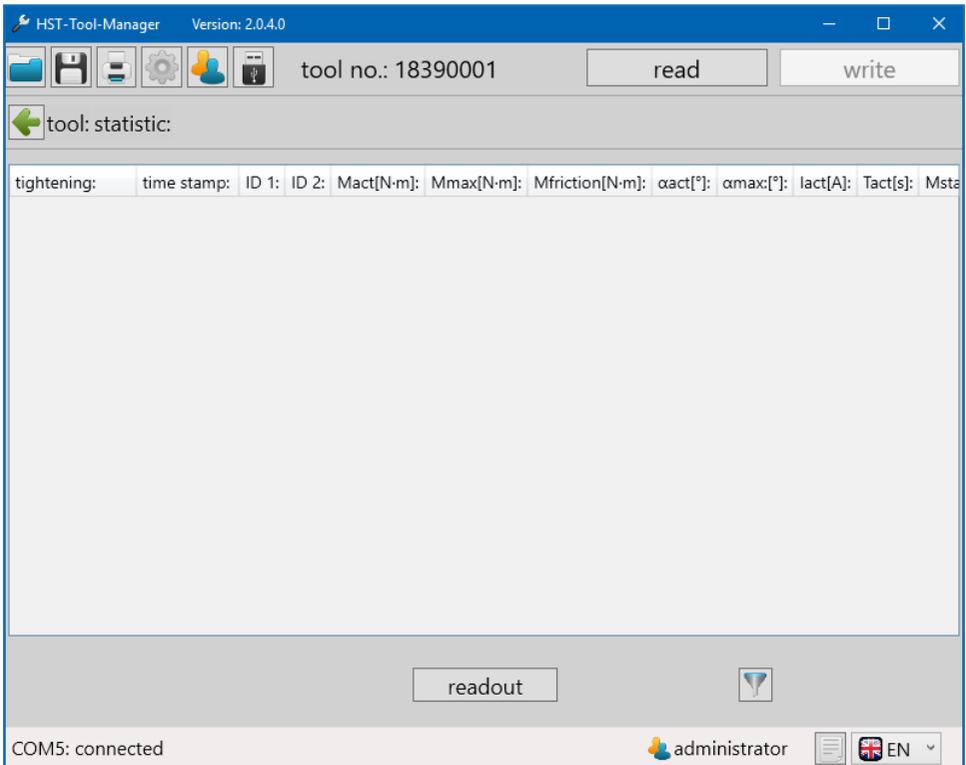
The tool stores at least 150,000 results on the internal data storage (micro SD card: 8 GB) which can be read out using the HST-Tool-Manager.



NOTE

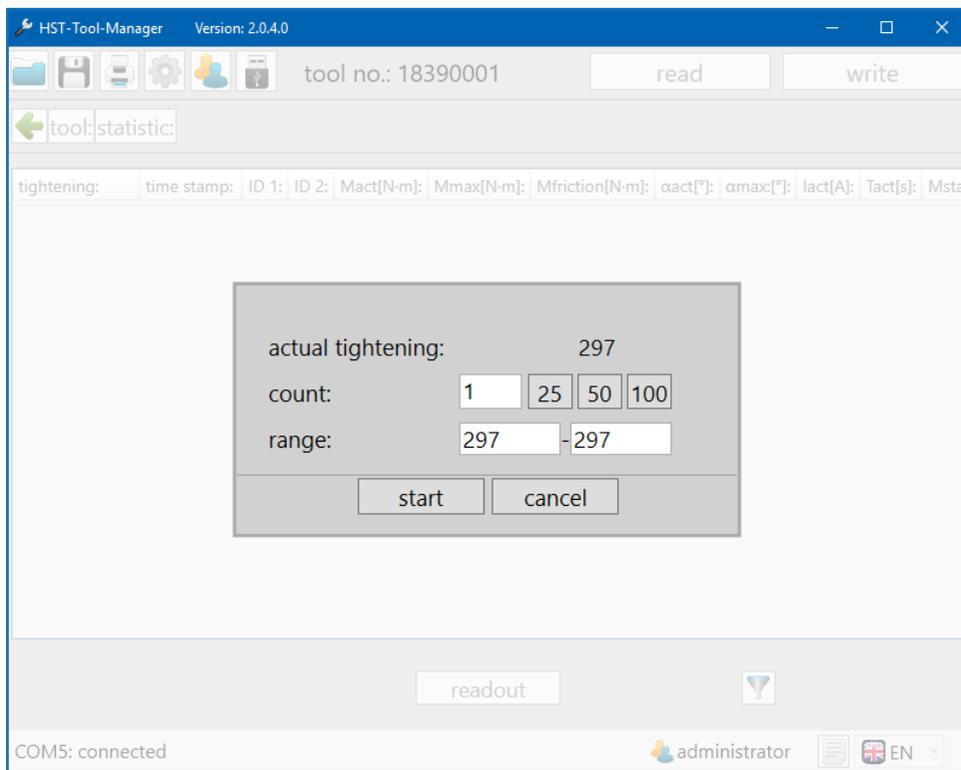
The tool must be connected with the computer via Wi-Fi or USB in order to be read.

The statistics can be retrieved on the homepage using the  button.



88 Statistics

In order to read statistical data from the tool click on the “readout” button. Then a pop-up window will open in which the desired data for reading can be entered.



89 Statistics 2

“actual tightening”	The total number of saved results.
“count”	Number of results to be read out.
“25/50/100”	Buttons for quick selection for the last 25, 50 or 100 results. By selecting one of the buttons the read out process will begin directly.
“range”	Selection of the results from a specific area. For example: Screw connection No. 448 - 467.



NOTE

The more screw connections you read out the longer your computer will need in order to display the data.

The HST-Tool-Manager loads the data and lists it as a table.

HST-Tool-Manager Version: 2.0.4.0

tool no.: 18390001 read write

tool: statistic:

	tightening:	time stamp:	ID 1:	Mact[N-m]:	Mmax[N-m]:	αact[°]:	Mfriction[N-m]:	αmax[°]:	lact[A]:	T _e
10	282	17.12.2018 14:20:46	HandMode	14,07	14,07	368,30	0,00	368,30	18,63	1,...
11	283	17.12.2018 14:21:31	HandMode	14,02	14,02	355,90	0,00	355,90	19,05	1,...
12	284	17.12.2018 14:22:15	HandMode	14,01	14,01	379,20	0,00	379,20	19,57	1,...
13	285	17.12.2018 14:23:00	HandMode	14,03	14,03	369,30	0,00	369,30	18,58	1,...
14	286	17.12.2018 14:23:44	HandMode	14,02	14,02	349,70	0,00	349,70	19,14	1,...
15	287	17.12.2018 14:24:29	HandMode	14,02	14,02	360,60	0,00	360,60	19,13	1,...
16	288	17.12.2018 14:25:14	HandMode	14,03	14,03	355,20	0,00	355,20	18,69	1,...
17	289	17.12.2018 14:25:58	HandMode	14,03	14,03	353,80	0,00	353,80	18,03	1,...
18	290	17.12.2018 14:26:42	HandMode	14,02	14,02	324,20	0,00	324,20	17,57	1,...
19	291	17.12.2018 14:27:27	HandMode	14,04	14,04	361,90	0,00	361,90	17,86	1,...
20	292	17.12.2018 14:28:12	HandMode	14,03	14,03	361,70	0,00	361,70	17,71	1,...
21	293	17.12.2018 14:28:56	HandMode	14,02	14,02	345,80	0,00	345,80	17,71	1,...
22	294	17.12.2018 14:29:41	HandMode	14,06	14,06	343,50	0,00	343,50	17,65	1,...
23	295	17.12.2018 14:30:25	HandMode	14,00	14,00	378,40	0,00	378,40	17,89	1,...

readout

COM5: connected administrator EN

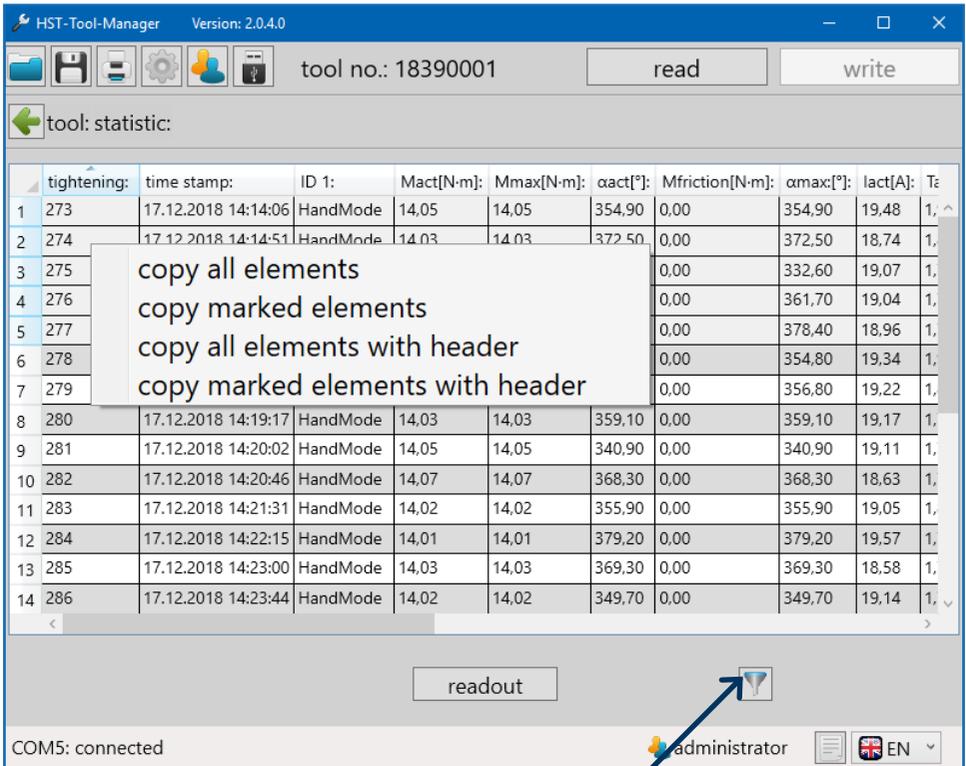
90 Statistics 3

“tightening”	Number of screw results.
“time stamp”	Date and time when the screw connection was conducted.
“ID 1”	Identification number. Is specified via wireless (FRZ max. 64 characters) or barcode (1 x barcode-ID max. 49 characters, 2 x barcode-ID each max. 30 characters).

"ID 2"	Additional identification number when using a double barcode ID (each max. 30 characters).
"M _{act} "	Tightening torque of the screw connection.
"M _{max} "	Maximum torque which was achieved during screwing.
"M _{friction} "	Friction coefficient determined (locking torque).
"α _{act} "	Total angle of the final tightening step.
"α _{max} "	Angle at maximum torque.
"I _{act} "	Current reached at tightening torque.
"M _{start} "	Start torque for the angle evaluation.
"α _{total} "	Total angle achieved across all steps.
"T _{start} "	Start time of the last step.
"TM _{start} "	Time upon achieving the starting torque (M _{start}).
"n"	Current number of revolutions at switch-off time.
"t _{MOT} "	Current temperature of the motor at switch-off time.
"t _{FET} "	Current temperature of the engine control at switch-off time.
"Program"	Program number for screw result.
"Step"	Step number for screw result.
"No. in program"	Serial number in the screw order.
"Result"	Evaluation of the screw connection.
"Event"	Reason for switch off for the step.
"NOK event"	Reason for the NOK evaluation in the step.

11.1.1 FILTER

In order to apply the filter function click on the button with the filter symbol  on the bottom right.

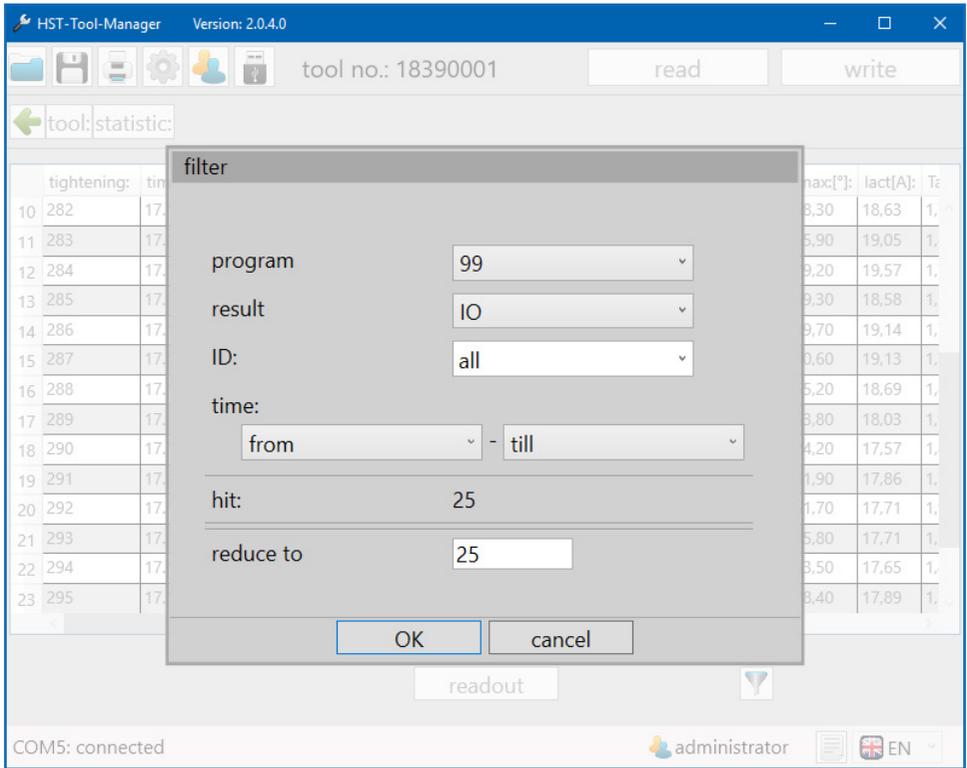


The screenshot shows the HST-Tool-Manager interface. At the top, it displays 'HST-Tool-Manager Version: 2.0.4.0' and 'tool no.: 18390001'. Below this are buttons for 'read' and 'write'. A section labeled 'tool: statistic:' contains a table with 14 rows of data. A context menu is open over the table, listing options: 'copy all elements', 'copy marked elements', 'copy all elements with header', and 'copy marked elements with header'. At the bottom of the interface, there is a 'readout' button, a user profile for 'administrator', and a language dropdown set to 'EN'. A blue arrow points from the word 'Filter' below to the filter icon on the right side of the bottom bar.

	tightening:	time stamp:	ID 1:	Mact[N-m]:	Mmax[N-m]:	αact[°]:	Mfriction[N-m]:	αmax[°]:	lact[A]:	T _e
1	273	17.12.2018 14:14:06	HandMode	14,05	14,05	354,90	0,00	354,90	19,48	1,
2	274	17.12.2018 14:14:51	HandMode	14,03	14,03	372,50	0,00	372,50	18,74	1,
3	275						0,00	332,60	19,07	1,
4	276						0,00	361,70	19,04	1,
5	277						0,00	378,40	18,96	1,
6	278						0,00	354,80	19,34	1,
7	279						0,00	356,80	19,22	1,
8	280	17.12.2018 14:19:17	HandMode	14,03	14,03	359,10	0,00	359,10	19,17	1,
9	281	17.12.2018 14:20:02	HandMode	14,05	14,05	340,90	0,00	340,90	19,11	1,
10	282	17.12.2018 14:20:46	HandMode	14,07	14,07	368,30	0,00	368,30	18,63	1,
11	283	17.12.2018 14:21:31	HandMode	14,02	14,02	355,90	0,00	355,90	19,05	1,
12	284	17.12.2018 14:22:15	HandMode	14,01	14,01	379,20	0,00	379,20	19,57	1,
13	285	17.12.2018 14:23:00	HandMode	14,03	14,03	369,30	0,00	369,30	18,58	1,
14	286	17.12.2018 14:23:44	HandMode	14,02	14,02	349,70	0,00	349,70	19,14	1,

91 Copy statistics elements

Filter

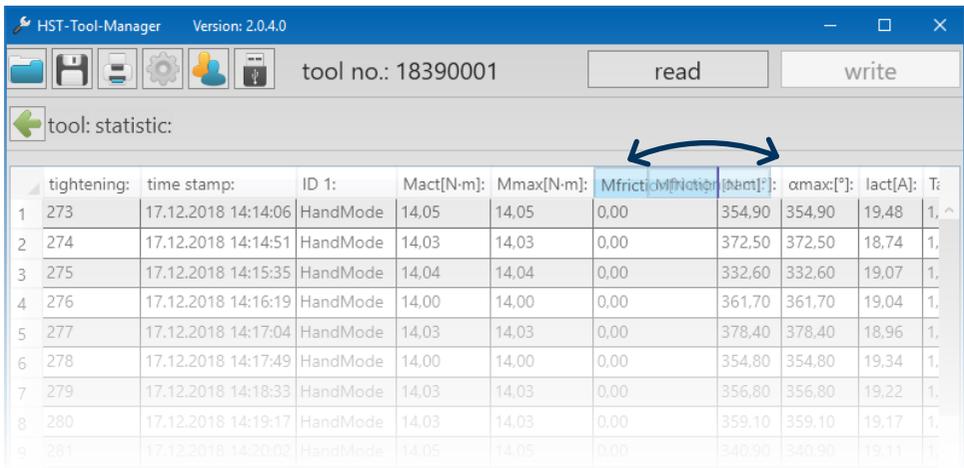


92 Statistics Filter

“program”	Filter results by program.
“result”	Filter results by evaluation.
“ID”	Filter results by ID.
“time”	Filter results by time.
“hit”	Number of results found.
“reduce to”	Reduce results found to desired number.

11.1.2 DRAG & DROP

All column widths can be adjusted as desired in order to get a better overview (similar operating principle to Microsoft® Excel). In addition each column can be sorted in ascending or descending order. To do this click on the column head. Enlarge/shrink the column width by pulling and dragging on the edge of the column. The whole column can also be moved using drag & drop. To do this drag while holding down the left mouse key at the top on the column header. As a result these can be arranged in front or in back.



HST-Tool-Manager Version: 2.0.4.0

tool no.: 18390001 read write

tool: statistic:

	tightening:	time stamp:	ID 1:	Mact[N-m]:	Mmax[N-m]:	Mfrict:	Mfrict [mm]:	amax[*]:	lact[A]:	Ti
1	273	17.12.2018 14:14:06	HandMode	14,05	14,05	0,00	354,90	354,90	19,48	1.
2	274	17.12.2018 14:14:51	HandMode	14,03	14,03	0,00	372,50	372,50	18,74	1.
3	275	17.12.2018 14:15:35	HandMode	14,04	14,04	0,00	332,60	332,60	19,07	1.
4	276	17.12.2018 14:16:19	HandMode	14,00	14,00	0,00	361,70	361,70	19,04	1.
5	277	17.12.2018 14:17:04	HandMode	14,03	14,03	0,00	378,40	378,40	18,96	1.
6	278	17.12.2018 14:17:49	HandMode	14,00	14,00	0,00	354,80	354,80	19,34	1.
7	279	17.12.2018 14:18:33	HandMode	14,03	14,03	0,00	356,80	356,80	19,22	1.
8	280	17.12.2018 14:19:17	HandMode	14,03	14,03	0,00	359,10	359,10	19,17	1.
9	281	17.12.2018 14:20:02	HandMode	14,05	14,05	0,00	340,90	340,90	19,11	1.

11.1.3 COPY ELEMENTS

In order to copy elements they can be individually marked. Multiple lines can be marked by holding down the left mouse key. All the elements can be copied by right clicking. In addition you can select whether the header should be copied as well or not. This data can be directly inserted into Excel and other programs.

HST-Tool-Manager Version: 2.0.4.0

tool no.: 18390001 read write

tool: statistic:

	tightening:	time stamp:	ID 1:	Mact[N-m]:	Mmax[N-m]:	αact[°]:	Mfriction[N-m]:	αmax[°]:	lact[A]:	T _e
1	273	17.12.2018 14:14:06	HandMode	14,05	14,05	354,90	0,00	354,90	19,48	1, ^
2	274	17.12.2018 14:14:51	HandMode	14,03	14,03	372,50	0,00	372,50	18,74	1, ^
3	275						0,00	332,60	19,07	1, ^
4	276						0,00	361,70	19,04	1, ^
5	277						0,00	378,40	18,96	1, ^
6	278						0,00	354,80	19,34	1, ^
7	279						0,00	356,80	19,22	1, ^
8	280	17.12.2018 14:19:17	HandMode	14,03	14,03	359,10	0,00	359,10	19,17	1, ^
9	281	17.12.2018 14:20:02	HandMode	14,05	14,05	340,90	0,00	340,90	19,11	1, ^
10	282	17.12.2018 14:20:46	HandMode	14,07	14,07	368,30	0,00	368,30	18,63	1, ^
11	283	17.12.2018 14:21:31	HandMode	14,02	14,02	355,90	0,00	355,90	19,05	1, ^
12	284	17.12.2018 14:22:15	HandMode	14,01	14,01	379,20	0,00	379,20	19,57	1, ^
13	285	17.12.2018 14:23:00	HandMode	14,03	14,03	369,30	0,00	369,30	18,58	1, ^
14	286	17.12.2018 14:23:44	HandMode	14,02	14,02	349,70	0,00	349,70	19,14	1, ^

readout

COM5: connected administrator EN

93 Copy statistics elements

NOTE

By holding down the STRNG key you can copy various elements into different lines (with empty lines) by clicking on the left.

11.2 GRAPHICS

The tool stores at least 150,000 curves on the internal data storage (8 GB) which can be read out using the HST-Tool-Manager.



NOTE

The tool must be connected with the computer via USB or Wi-Fi in order to be read.

Click on the button  on the homepage.
The interface of the “graphic” will open.

HST-Tool-Manager Version: 2.0.4.0

tool no.: 18390001 read write

tool: graph:

ID1: 22.20.2018 11:50:55 file of graph

values:

step	Mact[N-m]	Mmax[N-m]	Mfriction[N-m]	α act[*]	α max[*]	Iact[A]	Tact[s]	Tmax[s]	Mstart[N-m]	α total[*]	Tstart[s]
------	-----------	-----------	----------------	-----------------	-----------------	---------	---------	---------	-------------	-------------------	-----------

evaluation: setup modus

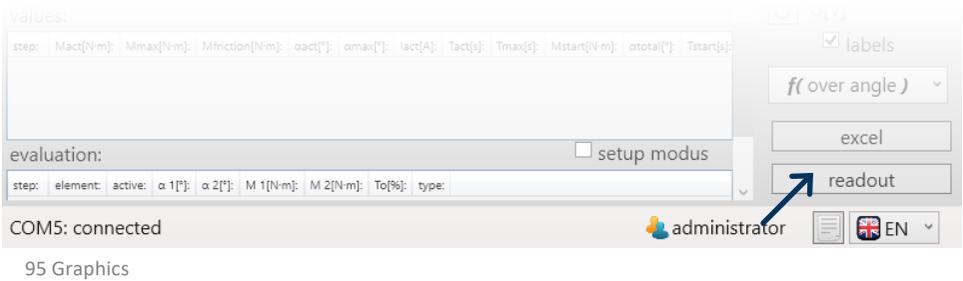
step	element	active	α 1[*]	α 2[*]	M 1[N-m]	M 2[N-m]	To[%]	type
------	---------	--------	---------------	---------------	----------	----------	-------	------

COM5: connected administrator EN

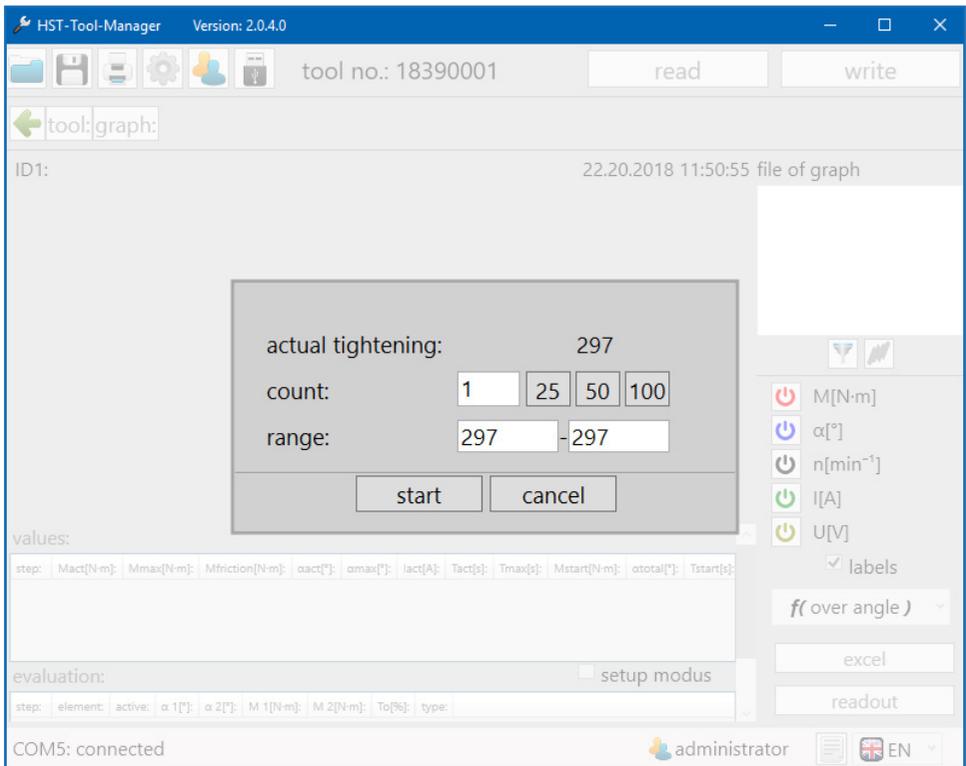
94 graphics

11.2.1 READ OUT DIAGRAMS

The graphics data from the tool can be read out using the “readout” button.



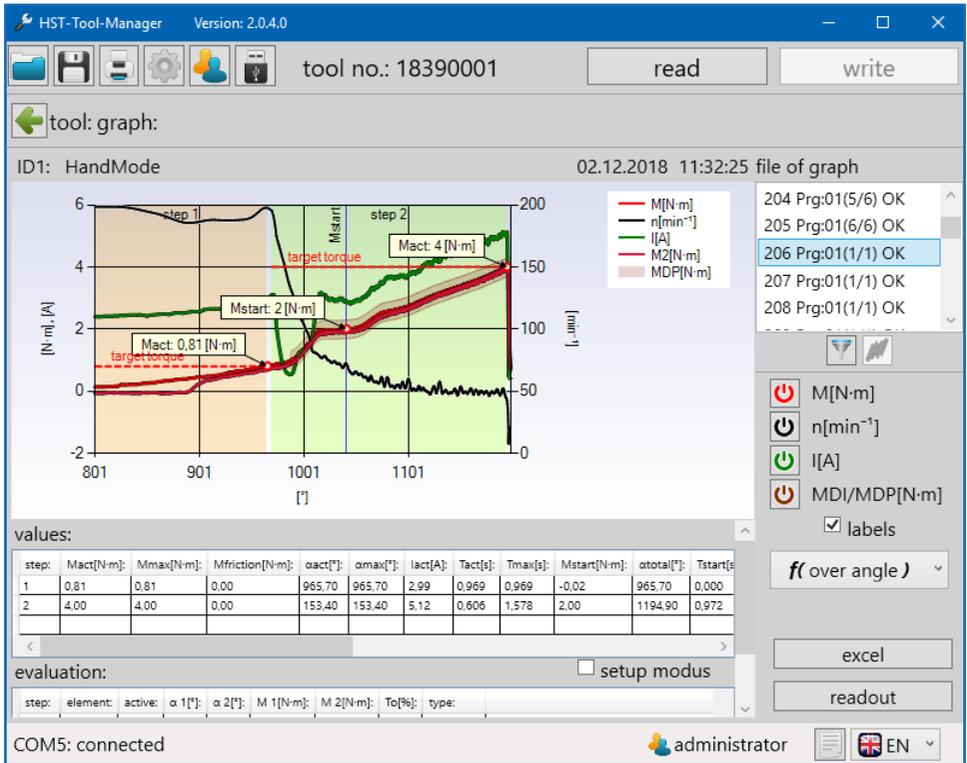
95 Graphics



96 Read graphics

<i>“actual tightening”</i>	The total number of saved results.
<i>“count”</i>	Number of results to be read out.
<i>“25/50/100”</i>	Buttons for quick selection for the last 25, 50 or 100 results. By selecting one of the buttons the read out process will begin directly.
<i>“range”</i>	Selection of the results from a specific area, e.g. screw connection NO. 448 - 467.

11.2.2 GRAPHICS INTERFACE



97 Graphics curve

“ID 1”

Identification number of the screw connection in the graphics file.
ID 2 (only available with 2xID)

“date/time”

Time stamp for graphics file.

“file of graph”

204 Prg:01(5/6) OK
205 Prg:01(6/6) OK
206 Prg:01(1/1) OK
207 Prg:01(1/1) OK
208 Prg:01(1/1) OK

Consisting of the screw connection number (206), the program (Prg:01), the number of the screw order (1/1) and the evaluation of the screw connection (OK/NOK).

“Parameter selection”



Only the parameters which were defined before the screw connections under “Setup - Graphics - Evaluation” are shown in the diagram.

The following parameters are available:

- Torques (M1, M2)
- Angle (α_1 , α_2)
- Number of revolutions per minute (is always recorded)
- Current
- Voltage
- MDM/MDP (see Chapter 6.7 page 86)

By clicking on the button  these can be added, or deleted from the display in the graphic.

“labels”

Activates/deactivates the designation elements in the graphic.

“f(over angle)”

Graphic presentation using the angle as a reference value.

“f(over time)”

Graphic presentation using time as the reference value.

“excel”

Export selected graphic to Microsoft® Excel.

“values”

- *Stage*: Screw stage of the program.
 - $M_{act}[Nm]$: Torque (final value) achieved in the step.
 - $M_{max}[Nm]$: Maximum torque achieved in the step.
 - $M_{friction}[Nm]$: The locking torque achieved in the step.
 - $\alpha_{act}[^\circ]$: Angle (final value) achieved in the step.
 - $\alpha_{max}[^\circ]$: Maximum angle achieved in the step.
 - $I_{act}[A]$: Current (final value) achieved in the step.
 - $T_{act}[s]$: Time (final value) achieved in the step.
 - $T_{max}[s]$: The maximum time achieved in the step.
 - $M_{start}[Nm]$: The starting torque registered in the step.
 - $\alpha_{total}[^\circ]$: The total angle achieved in the step.
 - $T_{start}[s]$: Start time of the step.
 - $T_{mstart}[s]$: Start time of achieving Mstart.
 - $\alpha_{start}[^\circ]$: Starting angle in the step (absolute).
 - $U[V]$: The voltage measured in the step (final value).
 - G_{act} : The torque rate achieved in the step (final value with regard to the maximum torque rate).
 - G_{max} : Maximum torque rate achieved in the step.
 - $n[min-1]$: Number of revolutions (final value) achieved in the step.
 - $t_{MOT}[^\circ C]$: Engine temperature in the step (final value).
-

"values"	<ul style="list-style-type: none"> - $t_{FET}[^{\circ}C]$: Electronics temperature in the step (final value). - $T_{total}[s]$: Total time of the step. - <i>OK/NOK</i>: Evaluation of the step. - <i>Event</i>: Step enabling condition entered. - <i>NOK event</i>: Reason for the NOK evaluation of the step (only in the event of a NOK).
"setup mode"	<p>Activates/deactivates the setup mode for the direct adjustment of evaluation criteria of the graphics read out. (Only possible with the graphic representation of angles)</p>
"evaluation"	<p>Evaluation criteria</p>
"α"	<ul style="list-style-type: none"> - <i>Element α</i>: Setting the lower and upper limit of the angle evaluation. - <i>Active</i>: Activates/deactivates the angle evaluation, the limits can be entered using α1 and α2 in the table, or be adjusted directly in the graphic. - α1: Lower limit value for angle evaluation. - α2: Upper limit value for angle evaluation.
"M"	<ul style="list-style-type: none"> - <i>Element M</i>: Setting the lower and upper limit of the torque evaluation. - <i>Active</i>: Activates/deactivates the torque evaluation, the limits can be entered using M1 and M2 in the table, or be adjusted directly in the graphic. - M1: Lower limit value for torque evaluation. - M2: Upper limit value for torque evaluation.
"Curve1" "Curve2"	<p>A curve consists of a base line which is defined across two points (torque and angle). The permissible deviation from the base line is specified using the tolerance. This can be done either in the table or directly in the graphic. It is important to ensure that curves exhibit a defined direction which is identified by an arrow.</p> <ul style="list-style-type: none"> - <i>Active</i>: Checkboxes in order to activate/deactivate the windows and curves. - α 1[°]: First point of the element on the angle axis. - α 2[°]: Second point of the element on the angle axis. - M 1[Nm]: First point of the element on the torque axis. - M 2[Nm]: Second point of the element on the torque axis.

“Curve1”

“Curve2”

- $To[\%]$: The tolerance determines the permissible deviation from the base line of the curve.
- *Type*: Specifies whether the evaluation is made horizontally or vertically. The orientation results from the torque curve.
(Steep curve , flat curve)

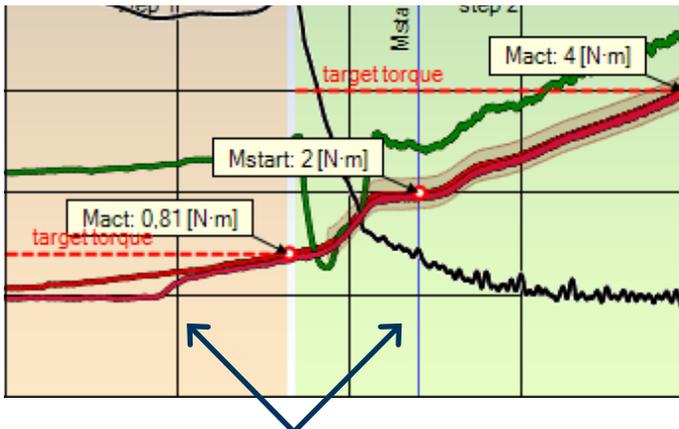
“B-angle upper”

“B-angle lower”

- Limits the area which the screw curve may pass through. This can be done either in the table, or directly in the graphic. The uniqueness of this element is that the angle counting refers to the switch-off point. The switch-off point, in this sense, corresponds to the 0° angle.
- *Active*: Checkboxes in order to activate/deactivate the angle monitoring.
 - $\alpha 1[^\circ]$: First point of the element on the angle axis.
 - $\alpha 2[^\circ]$: Second point of the element on the angle axis.
 - $M 1[Nm]$: Defines the torque that the screw curve may not exceed or fall below.

NOTE

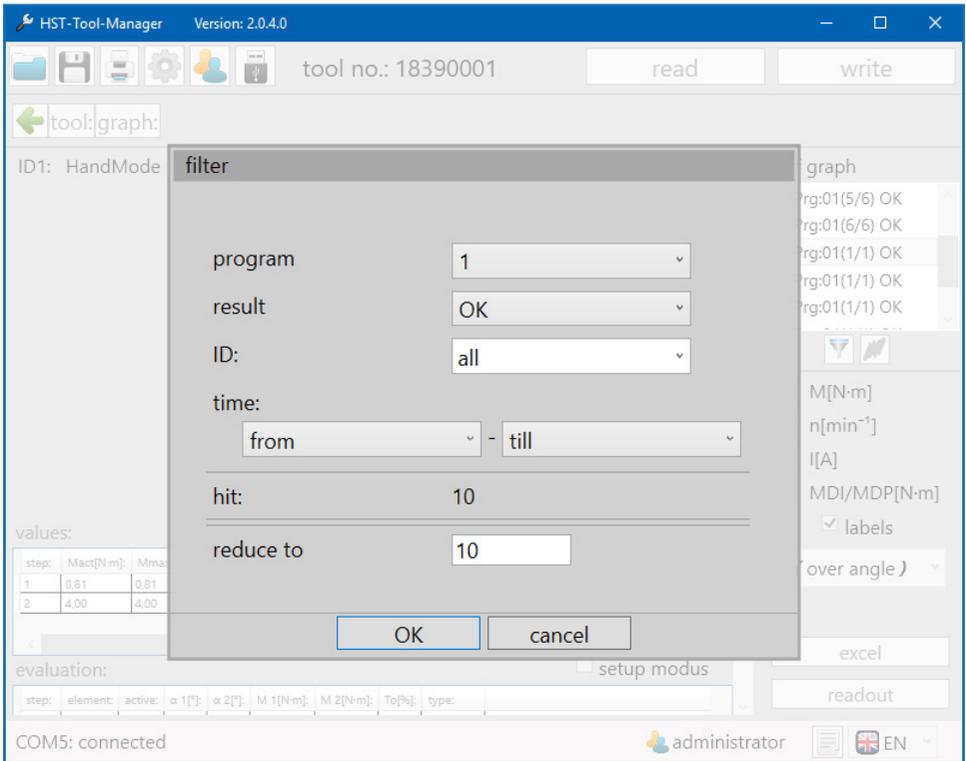
Take into consideration the settings under “setup - graphics - evaluation”. Measurement values not set will not be depicted in the graphic and can not be added.



Within the graphic the programmed steps will also be displayed with different coloured backgrounds.

11.2.3 FILTER

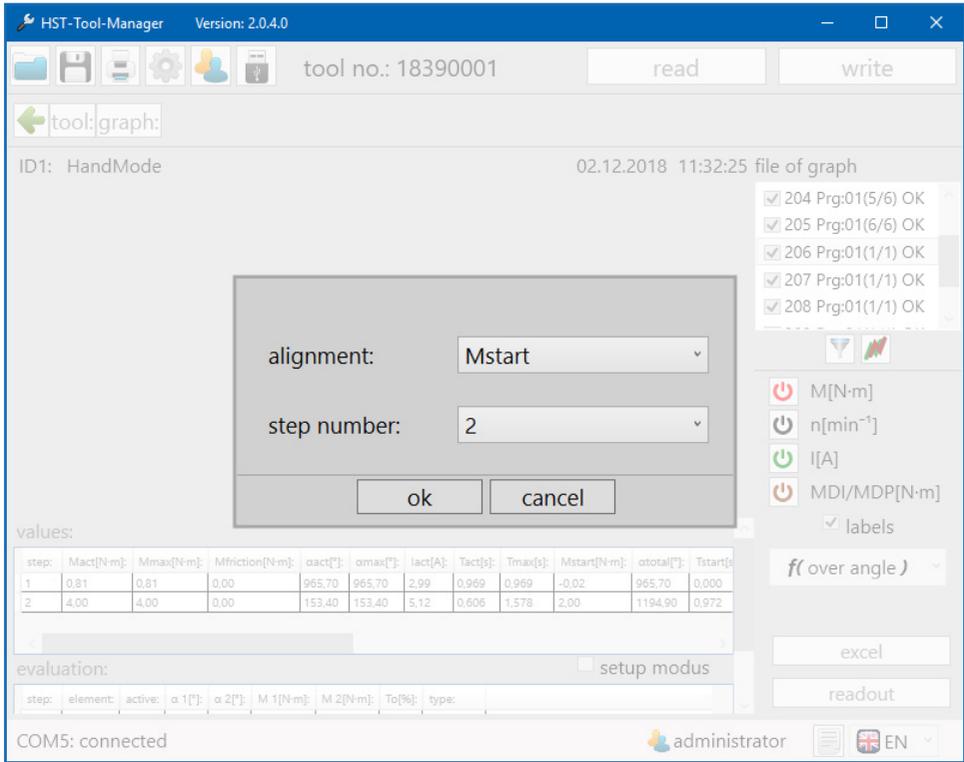
The graphic files read out can also be filtered and superimposed according to different criteria. A pop-up window with the filter options will open using the button with the filter symbol  .



98 Filter

“program”	Filter results by program.
“result”	Filter results by evaluation.
“ID”	Filter results by ID.
“time”	Filter results by time.
“hit”	Number of results found.
“reduce to”	Reduce results found to desired number.

After the filter procedure the button for the curve overlay gets active . The overlay of different graphics data enables an excellent analysis of screw data. So that the decisive points of the screw curve can be compared there is the option of aligning the screw curves with one another.



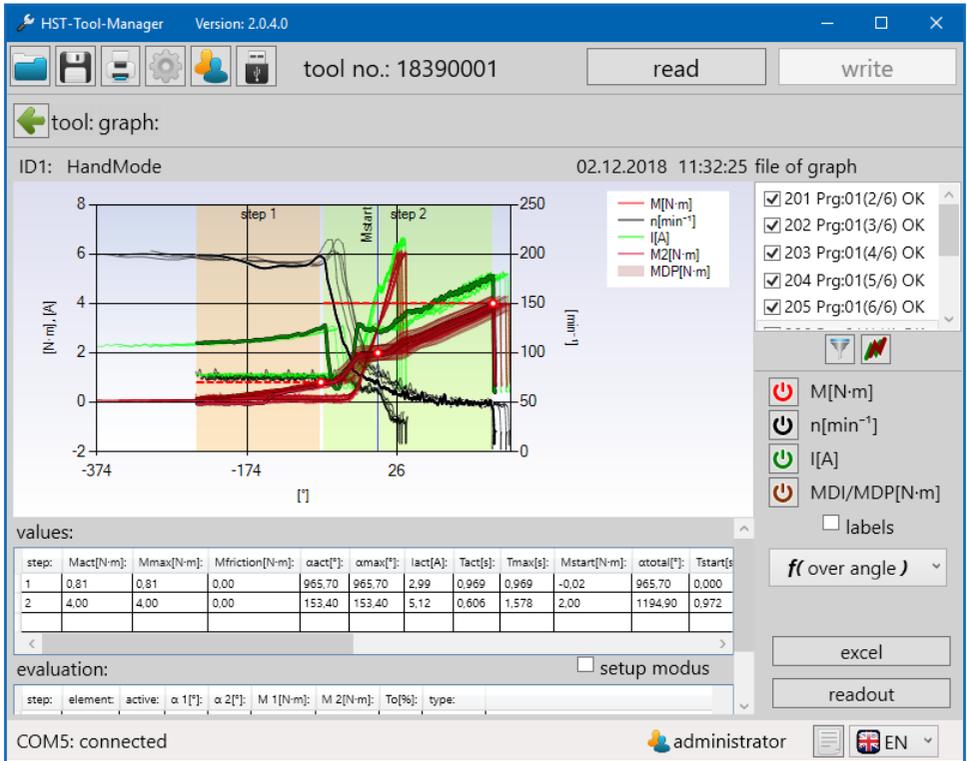
99 Curve overlay

“alignment”

- *M_{start}*: Overlays the selected curves, aligned by the respective starting torque.
- *M_{act}*: Overlays the selected curves, aligned by the respective final torque.
- *Step begin*: Overlays the selected curves, aligned by the respective beginning of the step.
- *Step end*: Overlays the selected curves, aligned by the respective end of the step.

“step number”

Specifies the step number from which the curves will be overlaid.



100 Curve overlay 2

11.3 EXCEL EXPORT

In order to export the data to Excel you must click on the excel button.

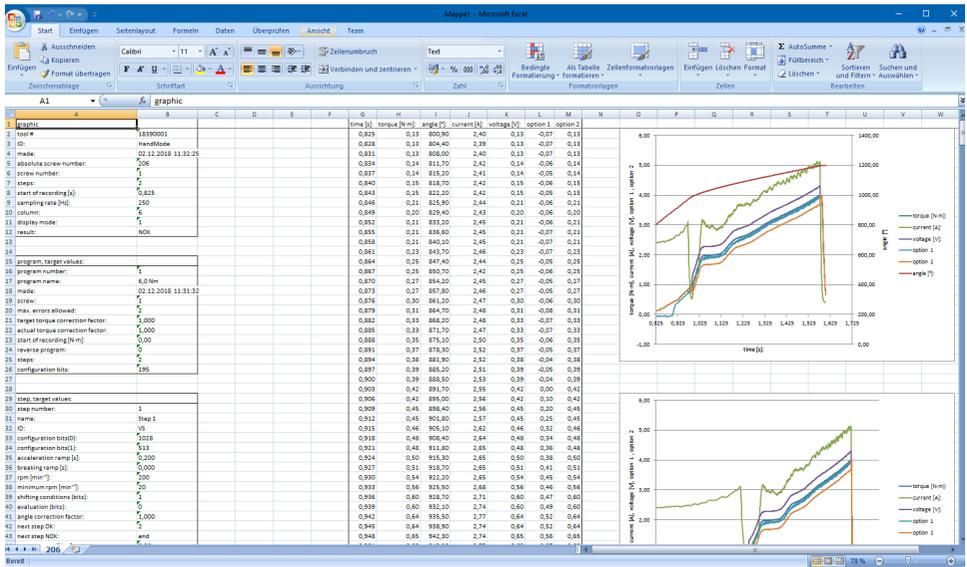
The screenshot shows the HST-Tool-Manager interface. At the top, it displays 'HST-Tool-Manager Version: 2.0.4.0' and 'tool no.: 18390001'. Below this is a 'read' and 'write' button area. The main area is titled 'tool: graph:' and shows a graph for 'ID1: HandMode' dated '02.12.2018 11:32:25 file of graph'. The graph plots torque (N·m) and speed (n) against time (s). It features two steps: 'step 1' (orange background) and 'step 2' (green background). Key values on the graph include 'Mact: 0,81 [N·m]', 'Mstart: 2 [N·m]', and 'Mact: 4 [N·m]'. A legend on the right identifies the data series: M[N·m] (red), n[min^{-1}] (black), I[A] (green), M2[N·m] (blue), and MDP[N·m] (grey). Below the graph is a 'values:' table with columns for step, Mact, Mmax, Mfriction, oact, omax, lact, Tact, Tmax, Mstart, ottotal, and Tstart. The 'evaluation:' section includes a 'setup modus' checkbox and a table for step, element, active, α 1, α 2, M 1, M 2, To, and type. At the bottom, it shows 'COM5: connected', a user 'administrator', and a language dropdown set to 'EN'. A blue arrow points to the 'excel' button in the bottom right corner.

step:	Mact[N·m]:	Mmax[N·m]:	Mfriction[N·m]:	oact[*]:	omax[*]:	lact[A]:	Tact[s]:	Tmax[s]:	Mstart[N·m]:	ottotal[*]:	Tstart[s]:
1	0,81	0,81	0,00	965,70	965,70	2,99	0,969	0,969	-0,02	965,70	0,000
2	4,00	4,00	0,00	153,40	153,40	5,12	0,606	1,578	2,00	1194,90	0,972

101 Graphic Excel Export

Export

After clicking on the Excel button Excel opens with the corresponding screw connection. At the same time a “save as” window opens in which you can now specify whether to save the file. The file name automatically contains the absolute screw number. However, this can be renamed or added to.



102 Graphic Excel Export 2

12 SAVING AND LOADING OF PARAMETERS

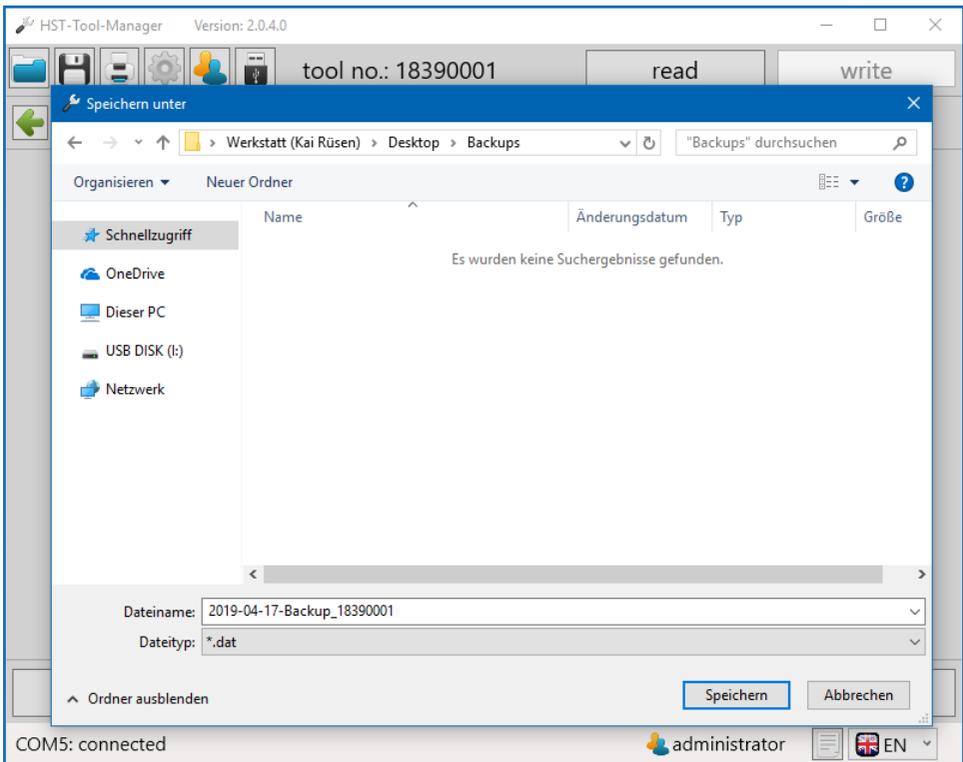
12.1 SAVING / LOADING

In the HST-Tool-Manager it is possible to save all configuration data for the tool in an “xml” or “dat” file. The current status of the tool is frozen in the file and can, in this way, be used for analysis. A duplicate of the tool can also be created using this file. Individual programs or Wi-Fi settings can also be copied. In order to save statistics and graphics data as well these must be read out beforehand. Click on the  button in the start window. The storage location is displayed, selected the desired storage location and the desired file type (.xml or .dat). Then click save. The file will be stored in your folder.



NOTE

When saving screw results in the .dat format less storage space is required than in the .xml format.



103 Save backup file

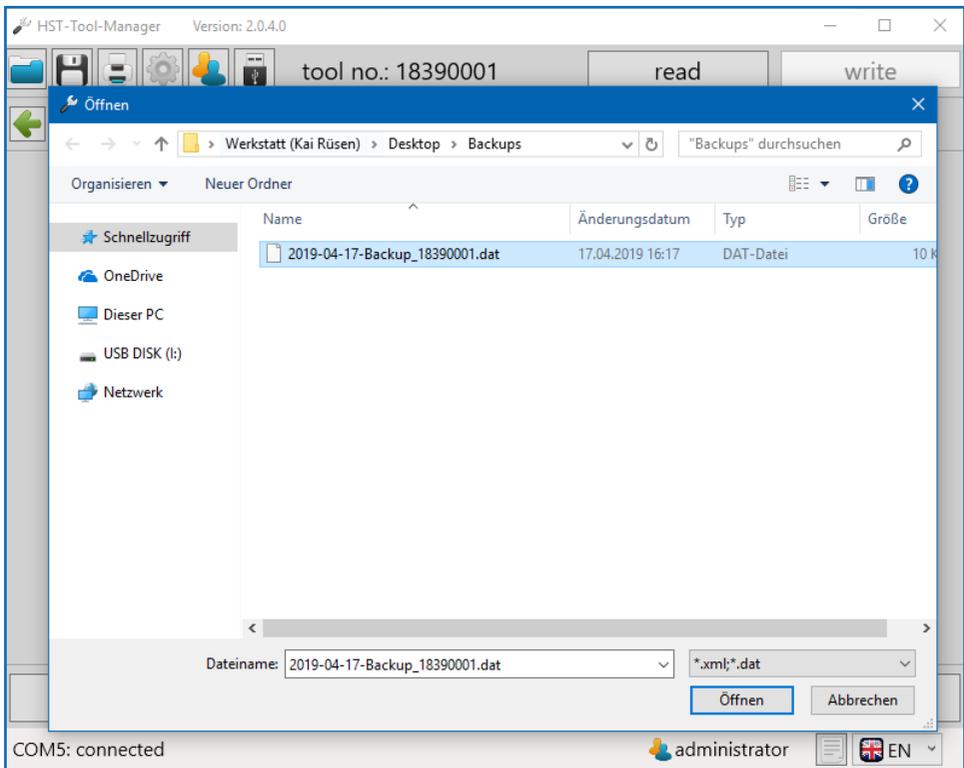
12.2 LOADING / RETRIEVING

The HST-Tool-Manager offers you the option to load complete or individual settings and programs into the tool. For this work you require the administrator user level.

First the tool must be read out, in which changes, an import of files or a restoration is to be completed. Then open the file from which the data is supposed to be overwritten.

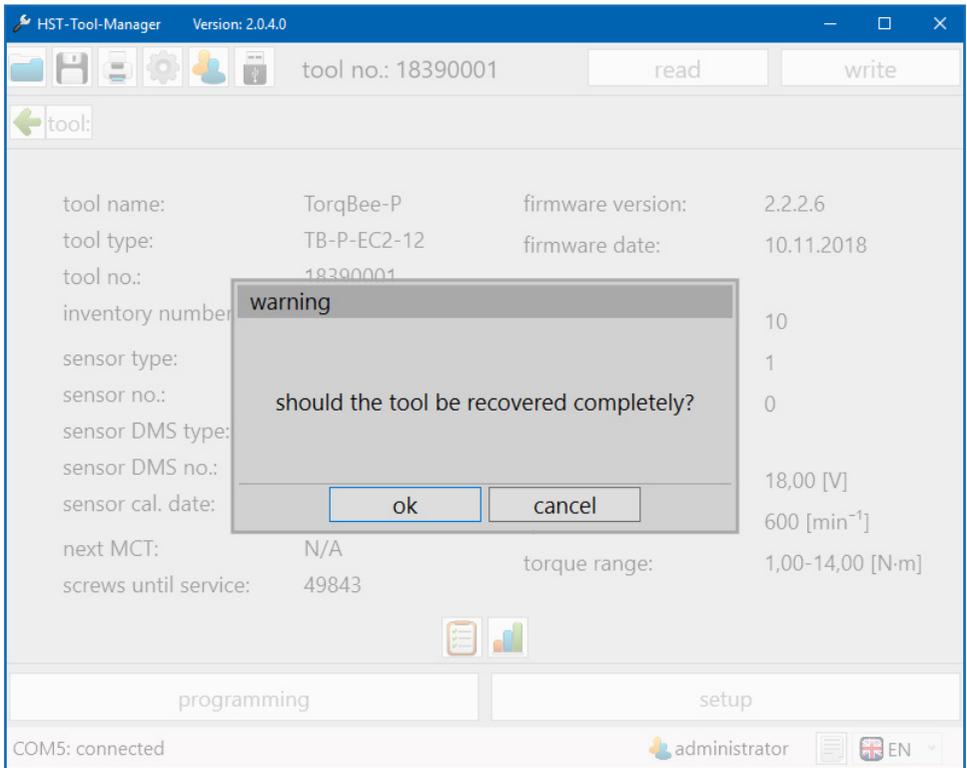
Click on the button  in the start window.

The dialogue window for selecting the file will open.



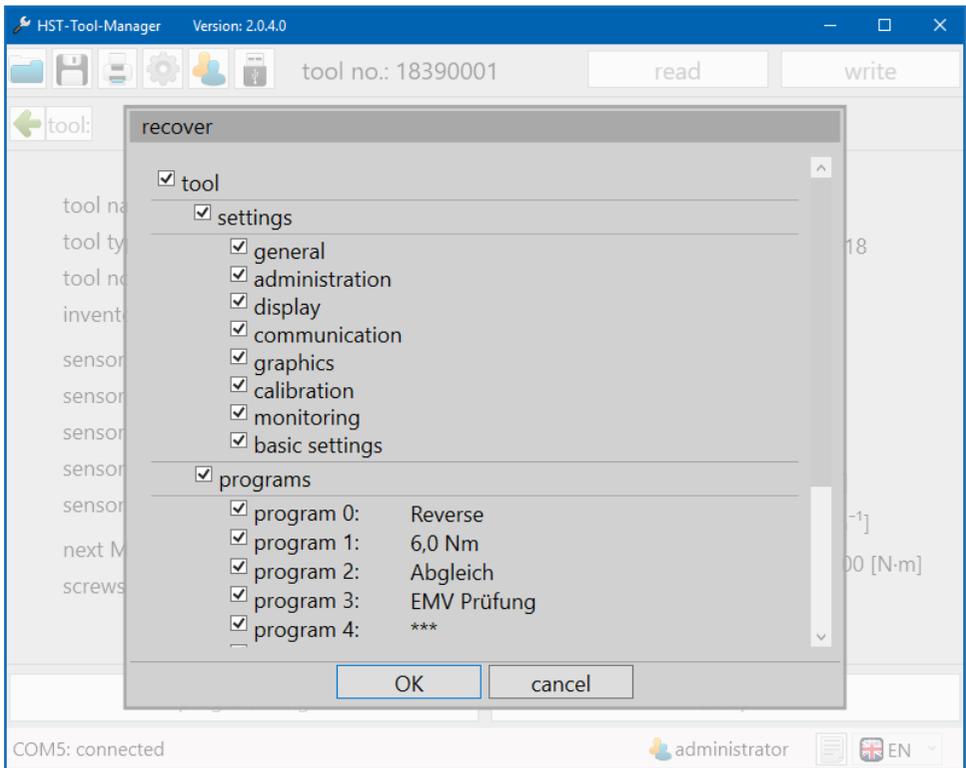
104 Open backup file

Select file and click “open”
A pop-up window will open.



105 Completely restore the tool

If the same serial number is entered in the loaded tool file as in the tool that has been read out the software will recognise this and ask whether the tool should be restored completely. Using the pop-up window you can select whether you want to restore, or import the whole tool or only part of the tool. When you click on “ok” the tool file will be overwritten. If you click “cancel” the import window will open in order to import individual components such as: settings, programs, barcodes or processes.



106 Do not completely restore the tool

If a different serial number from the connected tool is entered in the tool file the import query window will appear. By selecting or deselecting you can load individual data or all data. Then click on “OK”. Then click on the “write” button. Now the data will be transferred to the tool connected.

13 SERVICE & CALIBRATION

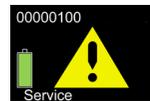
13.1 USER GROUP SERVICE

The relevant maintenance employee will decide after how many screw connections service on the tool is necessary.

As soon as that number is reached (e.g. 500,000) the tool will display the service symbol in the display. The tool will automatically be locked and must go for service.

Service should serve as a complete inspection of the tool. HS-Technik GmbH also offers this as an external service.

On the display of the tool the “service” symbol will appear when the set service interval has been reached.



On the display of the tool the “MCT” symbol will appear when the set MCT interval has been reached.



The service defined by the maintenance department for this tool must be completed.

For example:

Cleaning, inspection for damage, replacement of defective or damaged parts.

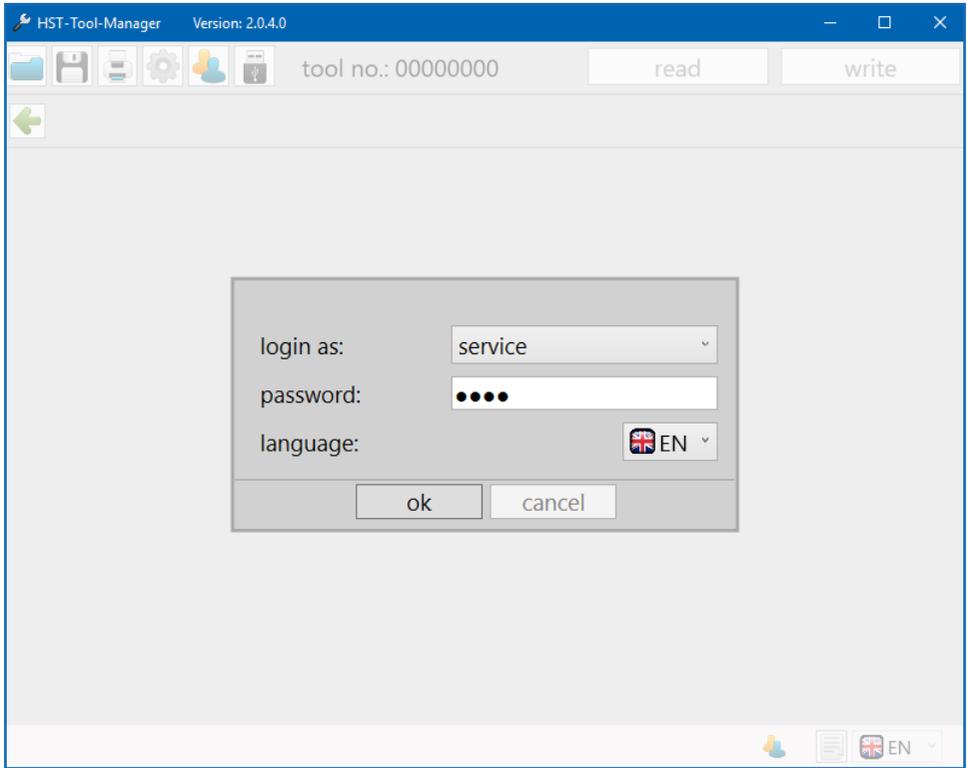


The tool will be connected to the computer via USB. The USB connection for the tool is located in the foot.

In order to select the correct software version the “pc. sw” no. is also specified here, which the required HST Tool Manger version depicts.

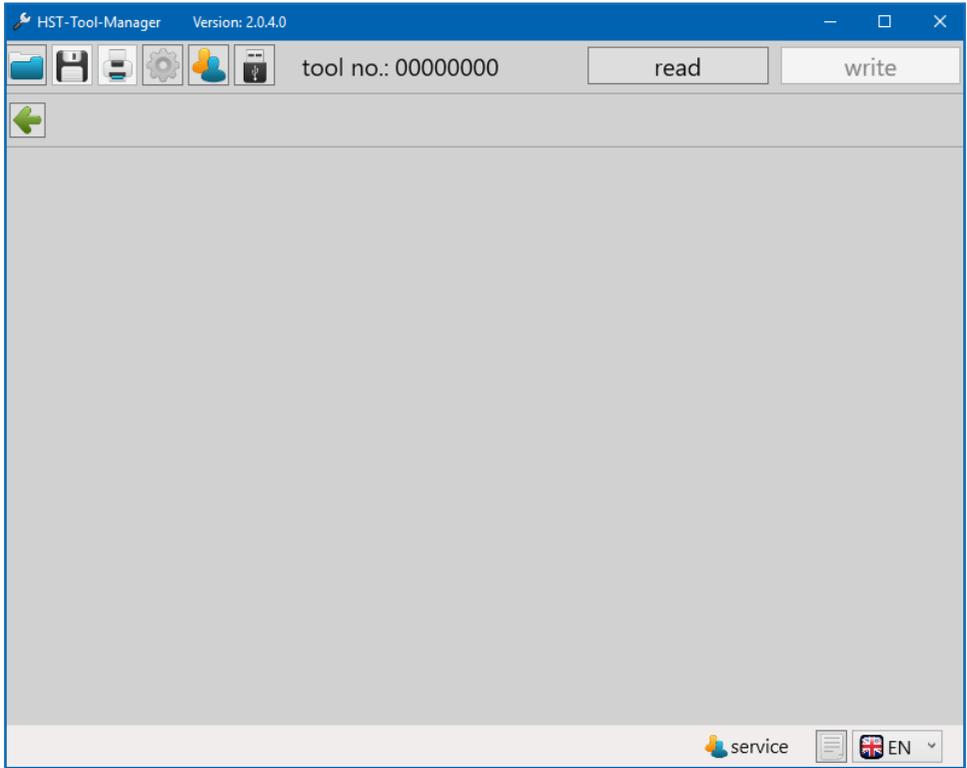


After starting the HST-Tool-Manager the user group “service” is selected. To do this you must still enter the password and select the desired language.



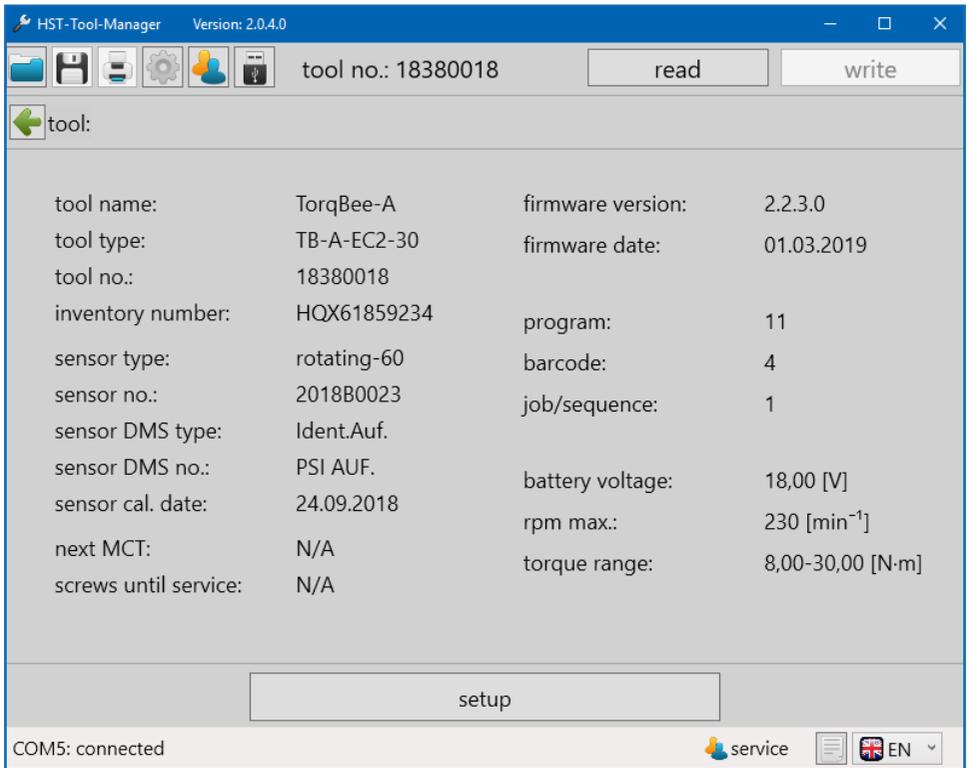
107 Registration Service

The empty start screen appears because no tool has been read yet. With one click on the “read” button the connected tool is read.



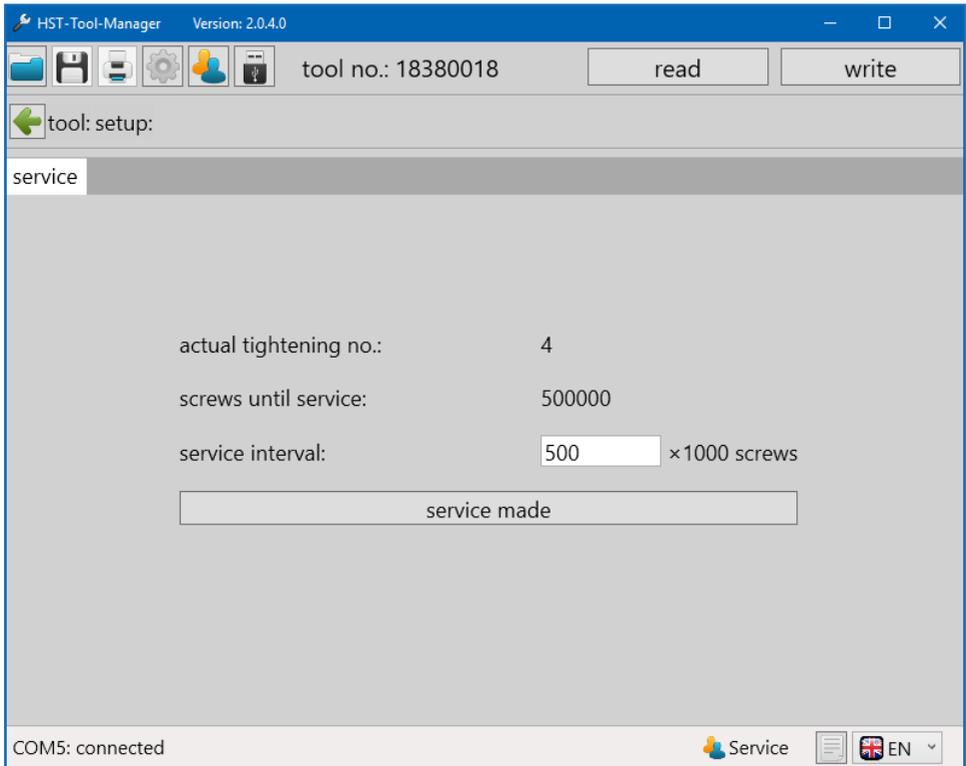
108 Registration Service 2

The tool was successfully read.
Then the “setup” button must be selected.



109 Service read tool

If the "screws until service" is at 0 the tool in the display has already issued the service symbol and locked the tool. The service interval can be individually established. Depending on the requirements of the tool the number of screw connections selected must be higher or lower. The value entered is multiplied by 1,000.



110 Set service interval

After conducting service work the service interval is reset by clicking the "service made" button.

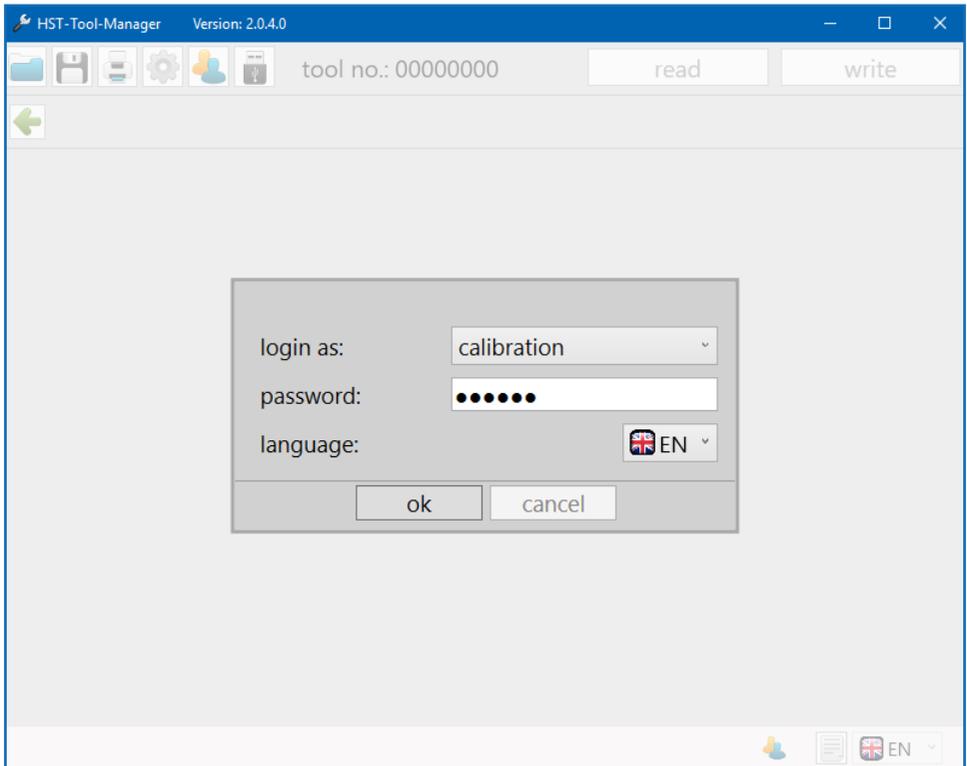
The screw number until service will be displayed in the overview after reading the tool.

13.2 USER GROUP CALIBRATION

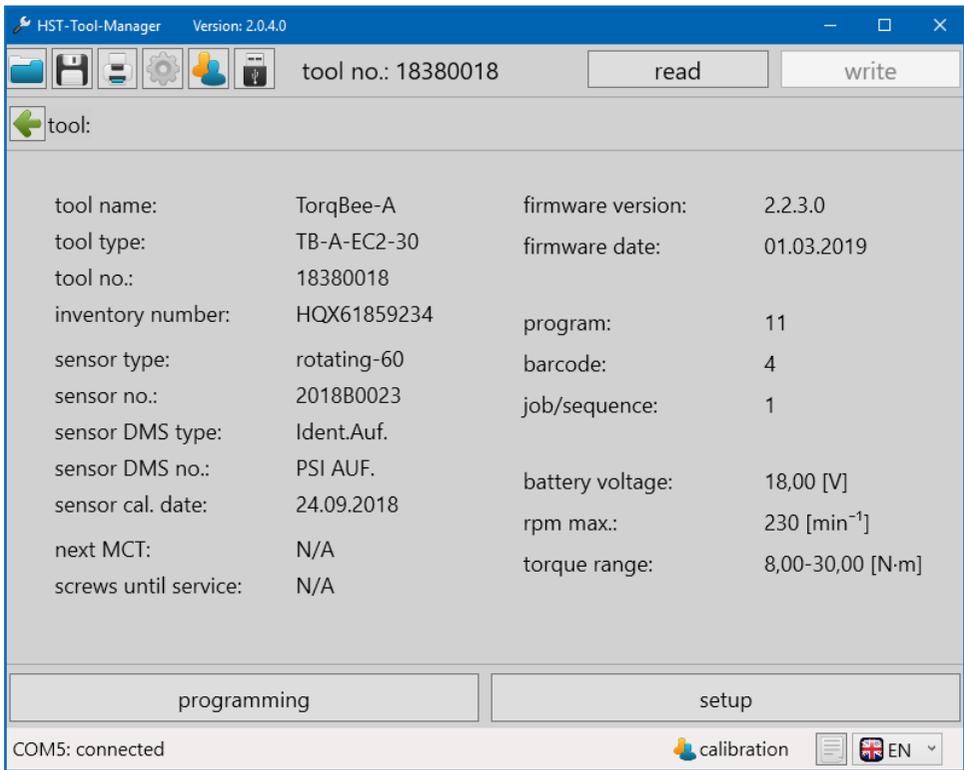
The relevant maintenance employee will decide after how many days a new MCT on the tool is necessary.

As soon as the days have elapsed the tool will display the MCT symbol. The tool will automatically be locked and must go for maintenance.

HS-Technik GmbH also offers this as an external service.



111 Registration calibrator



112 Calibrator read tool

The user group “calibration” can adjust the programs, barcodes and processes which are required for a tool inspection of MCT under “programming” as necessary.

The procedure for creating and changing programs, barcodes and processes is explained here: Programming of programs in Chapter 6 starting on page 64; Programming of barcodes in Chapter 8 starting on page 117; Programming of jobs (sequences) in Chapter 9 starting on page 125.

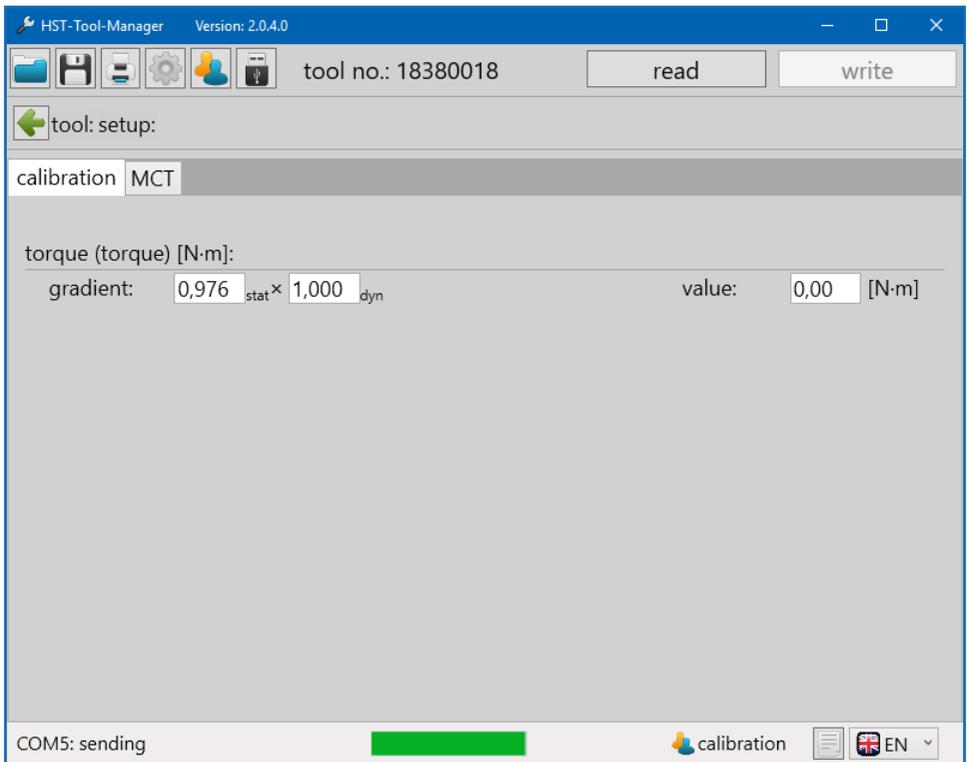
In addition under “setup” the interval until the next MCT can be set and the comparison values of the torque sensors can be changed.



DANGER

The comparison tab should only be operated under the supervision of an HS-Technik employee.

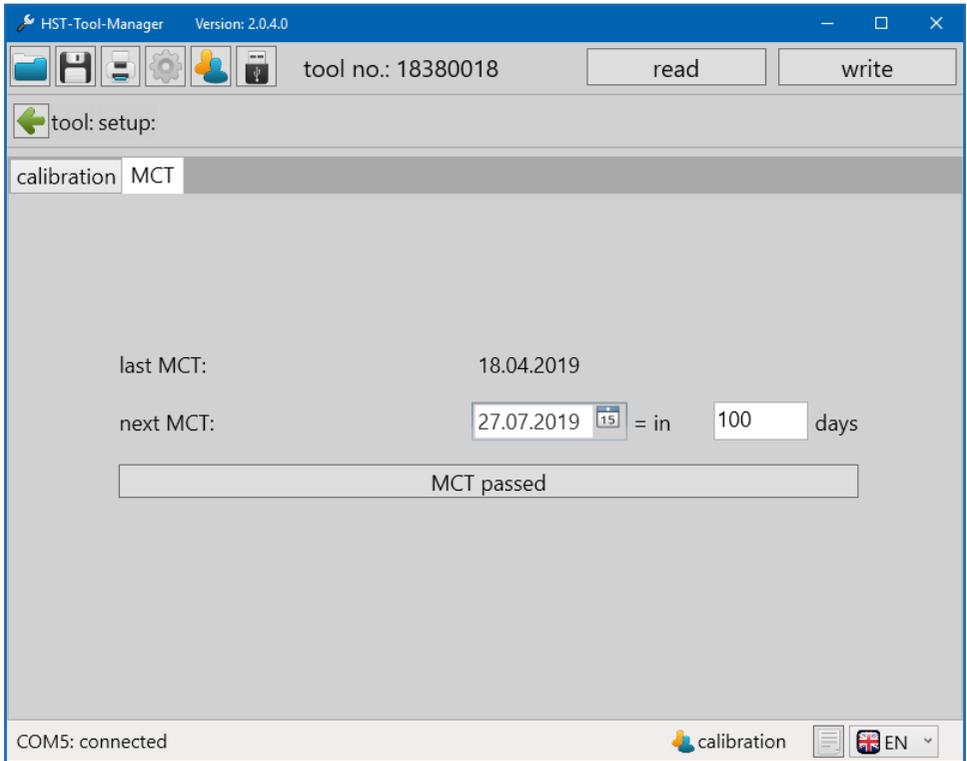
13.3 TAB “CALIBRATION”



113 Calibrator comparison

“gradient static”	This value cannot be changed.
“gradient dynamic”	Correction factor for mechanical friction losses. (e.g. angle head)
“value”	Current torque value recorded by tool.

13.4 TAB “MCT”



114 Calibrator MCT

“last MCT”

Provides the date of the last MCT conducted.

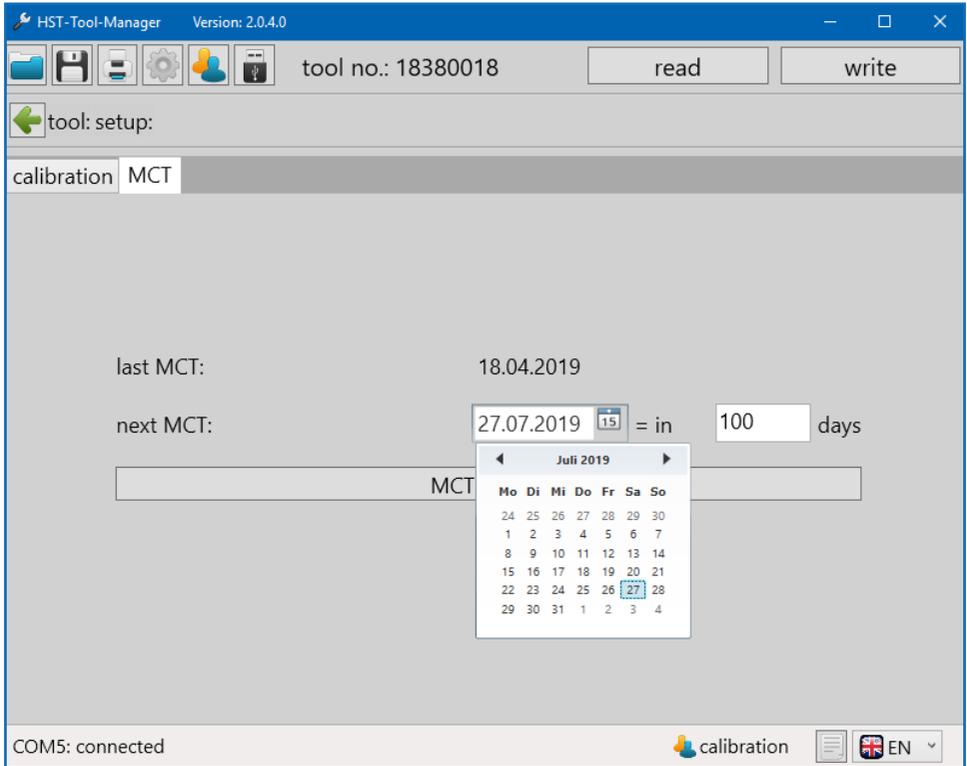
“next MCT”

- *Calendar*: Selection for the date of the next MCT using a calendar.
- *Direct input*: The date for the next MCT can be entered directly.
- *Interval input*: The date for the next MCT is automatically calculated from the current date and the interval specified in days.

“MCT passed”

Resets the interval counter for the MCT.

After clicking “MCT passed” the date of the last MCT is set to the current date and the date for the next MCT is determined.



115 Calibrator MCT Calendar

13.5 WIRELESS NETWORKS/SPECIAL CASE TOOL WITHOUT USB



NOTE

Only for tools without USB!

If you use the tools without an USB connection you must first configure the network settings. To do this a QR code is created as follows, which you can use to load/activate the network settings with the tool. Load an already existing tool file in the HST-Tool-Manager as described in Chapter 11.2 starting on page 137. The network administrator must now log in. Go to the "setup" button. Enter the network data of your IT.

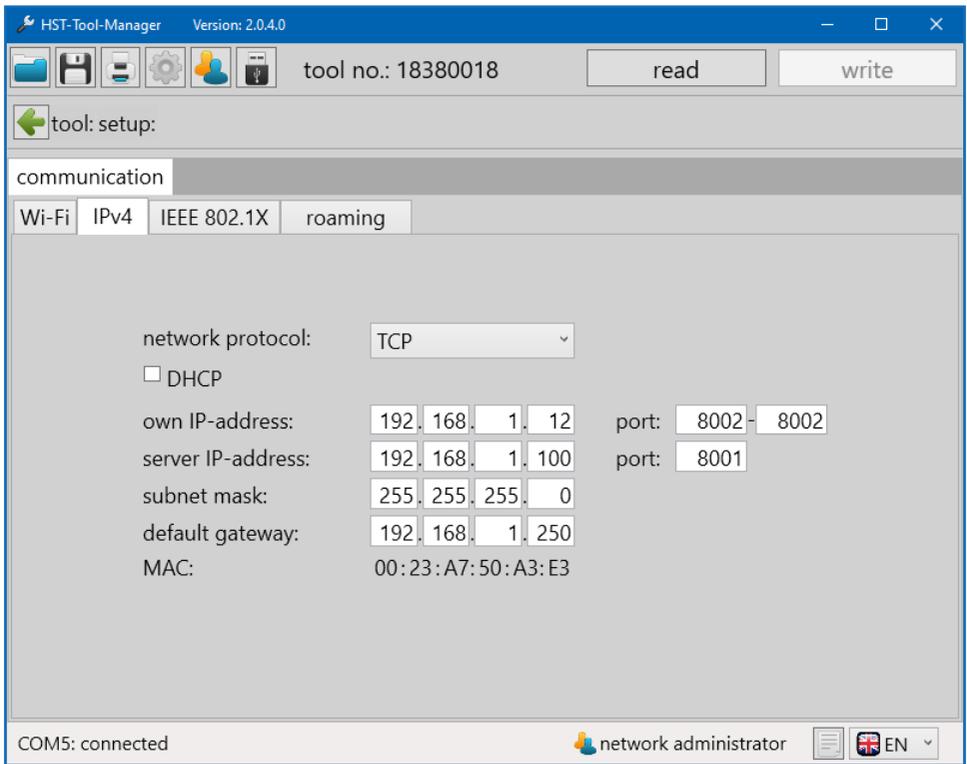
Certificates (IEEE 802.X) cannot be assumed using DataMatrix Code.

The screenshot shows the HST-Tool-Manager software interface. The title bar indicates the version is 2.0.4.0. The main window displays the tool number 18380018 and buttons for 'read' and 'write'. Below this, there is a 'tool: setup:' section with a back arrow. The 'communication' tab is active, and the 'Wi-Fi' sub-tab is selected. The configuration fields are as follows:

- authentication type: WPA2
- SSID: HST01
- network key: 12345678910
- region: Europe
- band: 5 GHz
- channel list: 56
- transmitting power: 17 dBm / 50 mW

A QR code is visible in the bottom right corner of the configuration area. The status bar at the bottom shows 'COM5: connected', the user 'network administrator', and the language set to 'EN'.

Set the IPv4 data and select the corresponding protocol.



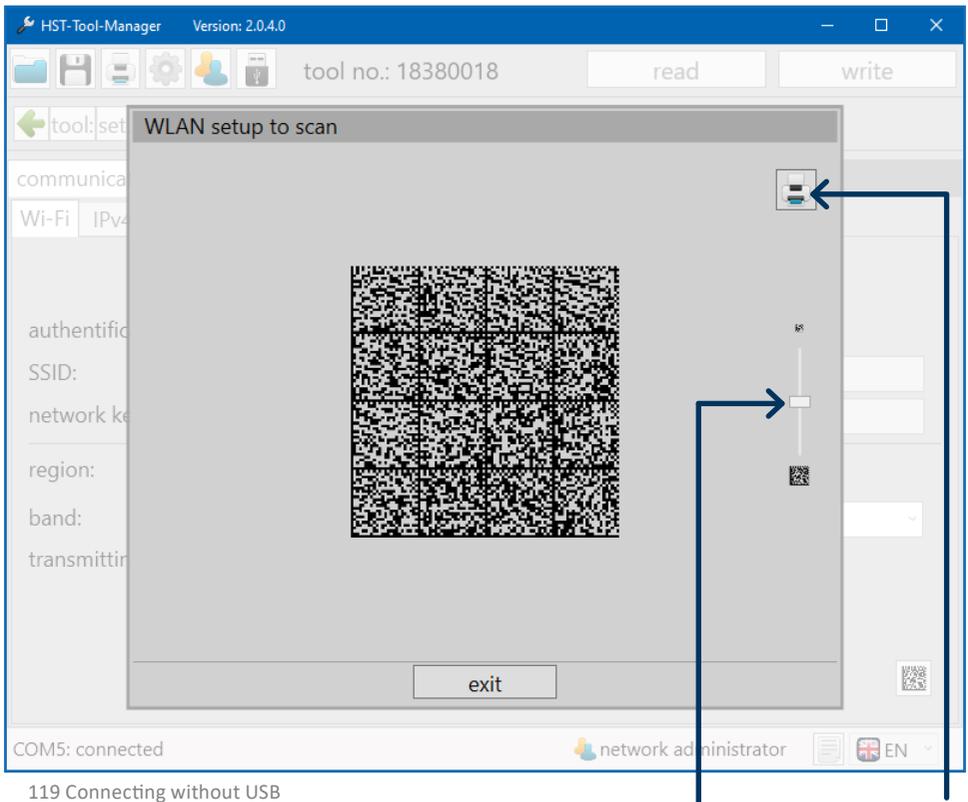
117 Connecting without USB 2

As soon as all the network data has been correctly and completed go back to the “Wi-Fi” tab and click on the QR code symbol at the bottom.



NOTE

If the tools are connected via RF868 you will see the settings for this under the network settings further back in these operating instructions.



Print it

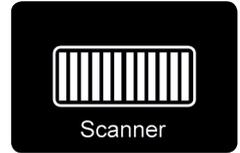
Enlarge / shrink

The size of the QR code can be adjusted on the edge on the right. If you do not want to scan from the screen you can also print it in the desired size.

In order to now connect the tool with the network scan the network setup barcode in.

13.6 INTEGRATE TOOL IN THE WI-FI NETWORK USING SCAN FUNCTION

In order to now scan the network setup barcode you must select scanner on the display. The function of the display is explained in the operating instructions for the tool.



Hold down the start key and align the scan field on the barcode. The tool will confirm a successful scan with a short signal tone and will then display on the screen that it is connecting with the network.

14 SPECIAL FUNCTION

14.1 CONNECT TOOL USING WI-FI WITHOUT USB

There is the option of parametrizing the tool without an USB using the Wi-Fi connection. An external control is required for this option. At the customer's request the corresponding network data can be saved in the HST-Tool-Manager so that the HST-Tool-Manager can connect using an AdHoc connection with the tool. The parametrisation in this case can be completed wirelessly.



NOTE

In this option this is a special function which can not be activated without the manufacturer. If you have any questions on this topic please contact HS-Technik GmbH: service@hs-technik.com | Telephone: +49 7628 9111-57.

In the case of the HST-Tool-Manager server this is a connection between a computer and a tool.

This type of connection is very rarely used. Here too, an automatic start can be set upon program start. The port needs to be entered and the status of the connection is being illustrated. A manual start is possible using the "start" button.

14.3 RF868

HST-Tool-Manager Version: 2.0.4.0

tool no.: 18380018

read write

tool: setup:

communication

network ID: 3

client address: 1

default address: 255

output power: +14dBm

sub-band: g1

channel: 0

hayes over the air: off

operation mode: addressed; secured

N° CR NH AES

Ret 2B ACK RSSI

listen before talk: on med sens

number of retries: 3

random waiting: on

radio baud rate: 38.4 Kbps

radio whitening char: 0

radio carrier length: 8

COM5: connected

network administrator

EN

120 RF868

“network ID”	Network identification by controller and tool must match.
“client address”	Address of the tool in the network.
“default address”	Address of the controller in the network.
“output power”	Selection of the output transmission power.
“sub-band”	Frequency band of the tool (must match the controllers).
“channel”	Channel of the tool (must match the controllers).
“hayes over the air”	System-specific setting. Adjust according to specification.

“operation mode”	System-specific setting. Adjust according to specification.
“listen before talk”	System-specific setting. Adjust according to specification.
“number of retries”	Number of the telegram repetition in the event of missing acknowledgement by the controller.
“random waiting”	System-specific setting. Adjust according to specification.
“radio baud rate”	System-specific setting. Adjust according to specification.
“radio whitening char”	System-specific setting. Adjust according to specification.
“radio carrier length”	System-specific setting. Adjust according to specification.

NOTE



Generally the setting of the 868 wireless module takes place with the commissioning of larger projects. However, should questions still arise please contact your HS-Technik GmbH contact person.

15 ANNEX AND DATA

15.1 TROUBLESHOOTING

Error	Cause	Action
No connection with the tool.	No USB cable connected.	Connect cable to tool and PC.
	USB cable not correctly inserted.	Check connection.
	No driver installed.	Install driver.
	Firewall blocks connection.	Deactivate firewall Issue release in firewall.
	Wi-Fi connection lost.	Restore Wi-Fi connection, or wait until the tool automatically connects.
Tool does not start after NOK screw connection.	Incorrect setting for NOK evaluation.	Setting under point program - general.
Tool does not start.	No program created.	Setting in the program overview.
	Incorrect program set as the default.	Setting on the homepage of the program.
No loosening possible.	Loosening deactivated.	Setting on the homepage of the program.
	Loosen after screw connection deactivated.	
Tool turns in the wrong direction.	Direction of rotation incorrectly entered.	Setting under step - gear.
Tool switches off too high.	Speed too high.	Setting under step - strategy or program - options.
	Incorrect switch off point entered.	
	Incorrect program activated.	Setting under "The active program".

Angle window too high/low.	Upper and lower limit incorrect.	Setting under step - strategy.
Tool shows crossed out battery symbol in the display and is issuing a warning melody.	Battery too low.	Connect charged battery.
Display off on inserted battery.	Tool is in energy saving mode.	Press the start button.
Engine is getting too hot.	Number of revolutions per minute is too low.	Too low of a number of revolutions per minute with high torque lead to overheating of the motor. Check tool programming.
	Soft screw connection on max. torque on tool.	Poss. a tool with a higher torque will be necessary.

NOTE



The error search concerns tips which we usually check first. The list is not complete and should only serve as an aid in your own error analysis in order to rule out programming/settings errors.

For a more detailed error analysis please contact service.

15.2 SHORTCUTS IN HST-TOOL-MANAGER

Abbreviation	Meaning
I_{act}	Current for tripping torque
M_{act}	Torque value in Nm with which the screw was tightened
M_{limit}	Limit of the torque
M_{max}	$M_{act} + M_{friction}$
$M_{friction}$	Friction coefficient determined (locking torque)
M_{target}	Target value torque
M_{start}	Beginning of the angle counting
T_{total}	Time required for the screw process
T_{act}	Time required for the screw connection
T_{start}	When the step was started
T_{total}	Total time required for the screw connection
TM_{start}	Time the starting torque was achieved (M_{start})
U	Battery voltage in the step
RPM	Number of revolutions in the step
α_{total}	Angle degree after activating the start key
α_{is}	Angle degree with which the screw was tightened
α_{limit}	Limit of the rotation angle
α_{target}	Target value of the rotation angle
α_{Sp}	Angle grade when changing steps

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